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#### **MAINTENANCE**

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#### **MAINTENANCE**

# FRICK® QUANTUM™ LX COMPRESSOR CONTROL PANEL

Version 7.1x



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#### THE FOLLOWING PUBLICATIONS ARE AVAILABLE FROM THE JOHNSON CONTROLS® WEBSITE jci.com

090.020-O Frick® Quantum™ LX Control Panel Operation - Service

090.020-CS Frick® Quantum™ LX Control Panel Communications Setup (setup and wiring for data communication using

available protocols)

090.020-M Frick® Quantum™ LX Control Panel Maintenance (repair and troubleshooting)

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## QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



#### **NOTES:**



### **SECTION 1**

# INTRODUCTION TO THE QUANTUM $^{\mathsf{m}}$ CONTROL SYSTEM





#### INTRODUCTION TO THE QUANTUM™ CONTROL SYSTEM

#### **INTRODUCTION**

The Quantum™ LX panel differs from previous Quantum™ panels primarily in the software operating system. The hardware portion (with the exception of the new international style keypad and cable) remains the same. The Frick® Quantum™ LX control system consists of five major areas:

Quantum™ Controller - The brains of the system. Currently, there are two versions of Quantum™ board in production, the Q4 board and the Q5 board. Both of these boards are discussed in greater detail later in this manual.

The combination of the hardware (Ouantum™ board) and the software program that runs on it creates what we call the Quantum™ LX system. The Ouantum™ board communicates with all of the Digital and Analog boards. This communication allows the Quantum™ to read the status of all the I/O boards, and display the data on the interface screen. The Quantum™ acts on this data, and provides the necessary control information to the I/O boards to provide the appropriate control of all input and output signals, based upon the configuration of installed features and options of the compressor package. Operator interaction is provided through the keypad, as well as informational status to the display. Interaction to the outside world is provided through industry-standard communications protocols. Additional information about the Quantum™ can be found under the QUAN-TUM™ CONTROLLER sections found later in this manual.

- Power Supply Provides the necessary operating voltages for the proper operation of all control components. Additional information about the power supply can be found under the POWER SUPPLY sections found later in this manual.
- Digital Input / Output Boards Digital (on/off) signals are sent and received by these boards. The output signals are used for energizing solenoids, valves, contactors, relays, etc., and the input signals are used to sense the condition of switches, relay contacts, auxiliary contacts, etc. This board runs an independent software program from the Quantum™ to control devices, and communicates the status of all devices back to the Quantum™. Additional information about the Digital Boards can be found under the DIGITAL BOARD section found later in this manual.

- Analog Input / Output Boards Analog (variable) signals are sent and received by these boards. The output signals are used for controlling VFDs, modulated valves, etc., and the input signals are used to read the values being sent from pressure transducers, temperature sensors, etc. This board runs an independent software program from the Quantum™ to control devices, and communicates the status of all devices back to the Quantum™. The Analog board has 24 analog inputs, and 8 analog outputs. Additional information about the Analog board can be found under the ANALOG BOARD section found later in this manual.
- Operator Interface This section actually consists of two major components; the Display and the Keypad. The Display is used to show the operator, via a graphical interface, the actual status of all compressor values. Warnings and shutdowns (and history/trending), pressure and temperature values, digital I/O status, setpoints, etc. are viewed on this display. The Keypad is used by the operator to enter data to the Quantum™ controller such as setpoint values, calibration data, etc. Additional information about the Display can be found under the DISPLAY section found later in this manual.

#### THE CONTROL PANEL ENCLOSURE

The Frick® Quantum™ LX control panel enclosure utilizes available space efficiently and the small size allows it to be used on all of our compressor packages. The panel is also equipped with the necessary posts and hardware to add options in the field. They may also include a second analog and/or digital board, enclosure heater and air-circulating fan.

Dimensions of the standard panel are 18x22x10 inches (WxHxD) and weighs approximately 75 pounds with all options. Typically the panel will be mounted on the package, but it is also designed for easy wall mounting as well. Refer to the Control Center Assembly drawing 649D5151 for the layout for this standard enclosure.

The DC power/communications harness in this panel is color-coded. This will make wire identification much easier. The coding is as follows:

- +5VDC RED
- +12VDC YELLOW
- -12VDC PURPLE
- Common/Ground BLACK
- +RX/TX BLUE
- -RX/TX BLUE w/WHITE stripe





#### **GENERAL INFORMATION**

The components within the control panel can be inadvertently damaged by static electricity or mishandling. Only qualified technicians should directly handle these components.

- DO NOT attempt to make corrections to the power supply without shutting off the power to the control panel. Accidental shorts can irreparably damage the processor boards or the display screen.
- DO NOT HANDLE the panel boards when their cables are disconnected without first attaching a properly grounded wrist ground strap to prevent static electrical discharge from your body.

Most problems encountered with the microprocessor and control circuits will be the result of a wiring fault, a blown fuse, faulty I/O module or failure of a peripheral control such as a solenoid coil or a pressure transducer. Faults in the computer, while possible, are unlikely. If a fault develops in the computer, the probability is that all functions will cease and the display screen will go blank. The control system of the compressor consists of an AC (high voltage) side, which can be either 120 volts, or 230 volts, and a DC (low voltage) side. The AC side actuates solenoids, relays, alarms, and other electromechanical functions. The DC side operates the computer and its various sensors.

When working within the panel, the AC high voltage side, which can be either nominal 120 VAC or nominal 230 VAC, CAN CAUSE INJURY OR DEATH.

To troubleshoot the low-voltage side of the control circuits, it is necessary to have the following tools:

- 1. Accurate digital multimeter (capable of reading to DC/AC, mA to the hundreds place)
- Small wire stripper
- Small screwdriver (with insulated shaft)
- 4. Small snip nose pliers
- 5. Wrist Grounding strap
- 6. Static free grounded work surface

**Note 1:** Proper panel voltage refers to the AC (high voltage) that has been supplied to the panel, which could be either nominal 120 VAC or nominal 230 VAC (Reference the Control Panel Power Specifications).

**NOTE 2:** Always ensure that the program card that you are trying to install is compatible with the controller that you are installing to. **A** Q4 LX Eurotech card will NOT boot on a Q5 LX or HD Advantech board and Q5 LX and HD cards will NOT boot on a Q4 LX Eurotech board.

#### WHAT TO DO BEFORE CALLING THE FACTORY

Many times when a suspected Quantum™ problem is called in to the factory, not enough information is provided for the service personnel to assist in solving the problem. This is because the caller most likely is not aware of the type of information that would be useful to factory personnel in helping to identify and correct the problem. An example of this is the statement that the Quantum™ is not booting (the main processor board is not starting). Unfortunately, this description is usually vague and only means that there is nothing on the display. A blank screen could be the result of many different problems. The following is a list of possible reasons for no display:

- No power
- Loose or Faulty Display Cable or Inverter Cable
- Bad Display
- Bad Backlight Inverter (on CCFT style displays)
- Bad Backlight Fluorescent Tube (on CCFT style displays)
- Improperly set jumpers on either the Q5 board or the Interface board.
- Wrong Combination of Display, Cable, Inverter, or Software
- · Faulty CPU Board

Before calling the factory for assistance, review the information on the following pages and try to discover and resolve your Quantum™ LX problem. The actual cause of most problems is usually not with the Quantum™ board itself, but with something external. However, on the rare occasion that the problem has been identified as being the Quantum™ board, use the following section as a guideline for replacing it.

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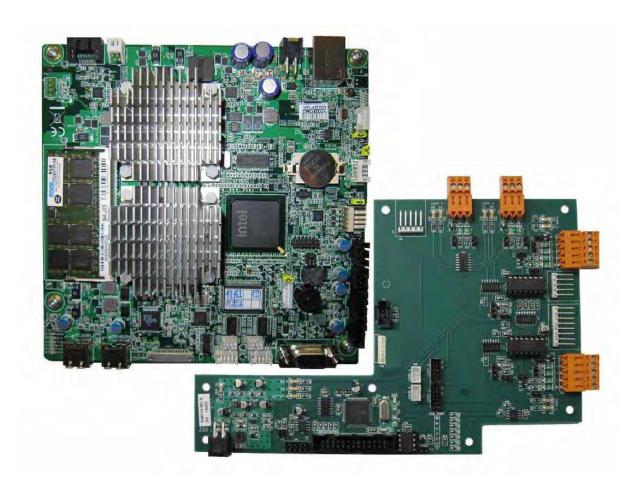
## QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



#### **NOTES:**



# SECTION 2 Q5 CONTROLLER





#### **Q5 CONTROLLER BOARD**

#### INTRODUCTION

Frick® Controls has released the latest version of the Quantum™ LX microprocessor board. This brand will be referred to as the Q5. A photo of this board appears here:



#### **FEATURES**

The Q5 board includes the following features:

- 6 total USB ports (2 are dedicated, 4 are available)
- 10/100/1000 Mbps Ethernet Connection
- 2 RS-422 ports
- · 2 RS-485 ports
- External Video monitor connection
- LED indicators to verify proper operation of various on board areas (power, communications, Ethernet connectivity, etc.)
- 2 GB RAM memory
- · Battery to maintain date and time

#### WHAT SHOULD OCCUR WHEN APPLYING POWER

When powering up, the following sequence of events are indicative of a properly working main processor board:

- The six LED's in the lower left corner should turn on solid.
- The on-board "buzzer" should "beep" once.
- The display should show several DOS (text) style screens. A penguin image will appear in the upper left corner of the screen as the boot sequence progresses.
- Just before fully booting, a Loading bar will appear at the bottom of the screen, showing the

percent of load that has completed.

The Operating Status screen will appear.

After the Q5 has properly powered up, the following sequence of events is indicative of proper communication to the analog and digital boards:

- The Analog and Digital I/O boards TX/RX lights should be blinking.
- Each I/O board should have the power LED lighted and the Active LED should be blinking.
- The first thing that should be checked when troubleshooting the Quantum™ 5 board is its powering up sequence.

## WHAT IF THE OPERATING STATUS SCREEN IS NOT SHOWN

If the Operating Status screen is not shown, check the following items:

- If no LED's are lit, then check AC and DC power. Refer to the Power Supply section.
- Check if the lighting of the LED's is occurring as described in the What Should Occur When Applying Powering section.
  - If the powering up sequence continues to repeat without displaying the Operating Status screen, then there is a booting problem.
- 3. Check all plugged connectors for proper seating.
- 4. Check if an error message is displayed when booting.
  - Be sure to write down any error messages exactly as they appear, as well as the top line on the screen where the message appears.
- 5. Check that the software is OK:
  - Is the correct software installed?
  - Did you just install new software?
- Check the display. If the Q5 board is booting but you have no display, check the following:
  - Check the backlight tube. Look very closely at the display to see if anything is visible in the dark screen. Using a beam type source of good lighting, such as a flashlight, look for any ghost type image. If it appears that there is something on the screen but very



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dark, the problem may be with the backlight tube. There is a sticker on the display mounting plate, that will have a part number that describes the type of display. If there is no sticker, you must take the display apart to identify the display manufacturer.

- Verify that both the display cable and the inverter cable are firmly seated. It may be necessary to remove the video cable from the back of the display and re-seat it to be sure it is connected properly. Note: This is a small connector and caution should be observed so that it is not damaged due to excessive force.
- Refer to the Operator Interface section and check that the display, display cable, and software versions are matched correctly.

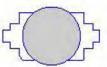
#### BATTERY FUNCTION AND REPLACEMENT

The Q5 board utilizes a battery to maintain correct date and time for the purpose of stamping warnings and shutdowns with the date and time that they occurred. If the date and time are not being maintained properly, this may indicate that the battery is not functioning, and should be replaced. The battery may be ordered through Baltimore Parts (P/N 333Q0001786) or may be purchased at most electronic shops (manufacturers P/N CR-2032).

The battery is fully assessable, but is surrounded by sensitive electronic components, so care should be taken when changing.

To replace the battery, ensure that the Control Power switch has been turned OFF.

Locate the Battery socket, as shown on the following drawing:



Place your fingernail under the edge of the battery, and gently lift up. The battery should release itself from the socket easily. Take a new battery and place it into the holder in the same orientation as the old battery (the side with the writing must be facing out). Return the Control Power switch back to ON.

Once the Q5 has rebooted, the correct Date and Time must be set.

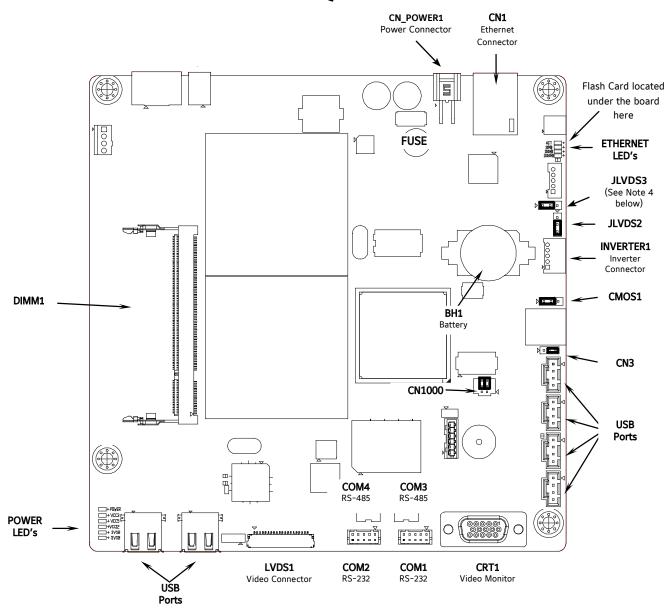
#### **Q5 INTERFACE BOARD**

An interface board has been developed by Frick controls allowing the user to interface exterior connections to the Q5. A photo of this interface board is shown here:





#### **Q5 BOARD**



- **NOTE 1:** The triangle symbol (  $\triangleright$  ) denotes Pin 1 on connectors. Refer to the chart on the following page for jumper settings.
- NOTE 2: Do NOT remove the CN4 jumper. Removal of this jumper will cause the processor to not power up.
- NOTE 3: Although the Q5 board is the main controller, most of customer connections will be to the Interface board, as shown later.
- **NOTE 4:** Ensure that this jumper is installed between pins 1 and 2 if a display is used that requires an inverter board. Install the jumper between pins 2 and 3 for an LED display that does not use an inverter board. See also the jumper table on the next page for JLVDS3.



### **Q5 BOARD JUMPERS, LED'S AND CONNECTORS**

#### **JUMPER TABLE**

Jumper Title	Function	Jumper So	etting
CMOS1	Normal (default)	1 2 3	1 - 2 Closed
(CMOS Clear)	Clear CMOS	D□○○ 1 2 3	1 - 2 Closed  2 - 3 Closed  1-3 Closed  8 2-4 Closed  3-5 Closed  8 4-6 Closed  3-5 Closed  8 4-6 Closed
	24-bit 800x600	6 0 0 5 4 0 0 3 2 0 0 1	&
CN1000 (LCD Resolution	24-bit 6 4 1024x768 2	4 00 3	&
Selector)	18-bit 800x600	6 0 0 5 4 0 0 3 2 0 0 1	&
	18-bit 640x480 <b>(default)</b>	6 00 5 4 00 3 2 0 0 1	

Jumper Title	Function	Jumper S	Setting
CN3	5-Wire Touch Screen	D□00 1 2 3	1-2 Closed
(Touch Panel Type Selector)	8-Wire Touch Screen (default)	D □ ○ ○ ○ 1 2 3	2-3 Closed
JLVDS2	0– 5V (default)	1	2-3 Closed
(Backlight Level Selector)	0 – 2.5V	1	1-2 Closed
JLVDS3	Voltage Mode - use with inverter (default)	D□00 1 2 3	1-2 Closed
(Backlight Con- trol Mode)	PWM Mode (Use for LED display - no inverter)	1 2 3	2-3 Closed

**NOTE 1:** The triangle symbol (  $\triangleright$  ) denotes Pin 1 on connectors. **NOTE 2:** Jumper CN4 is not shown on this chart, as it must always be installed.

#### **LED DEFINITION TABLE**

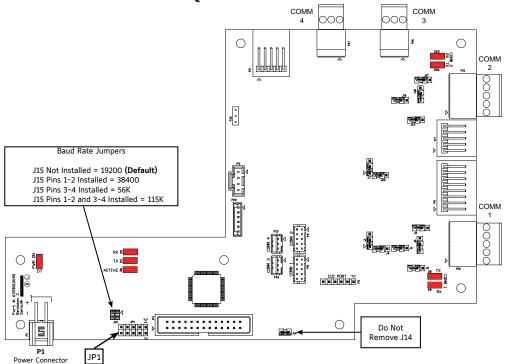
LED Title	Label	Color	Function
	LED1	Red	5VSB
	LED2	Red	3VSB
Power LED's	LED3	Green	VCC 12V
Fower LED 3	LED4	Green	VCC 5V
	LED5	Green	VCC 3V
	LED6	Blue	Power On OK Status
	1000MB	Green	Giga – LAN Speed
CN1000 (LCD	100MB	Yellow	100MB - LAN Speed
Resolution	10MB	Red	10MB -LAN Speed
Selector)	ACT	Green (Blinks)	LINK Activity

#### **CONNECTOR PINOUT TABLE**

<b>Connector Title</b>	Pin	Function	Pictorial
	1	Ground (GND)	г <u>4 3</u> л
CN_PWR1	2	Ground (GND)	
(Power Input)	3	VCC 12V	
	4	VCC 12V	2 1







#### JP1 SYSTEM SETTINGS

5: 1 0 : 0 : 1 : 1 : 1 : 1 : 1 : 1 : 1 :					
Jumper JP1	Function	Jump	er Setting		
1 - 2	1 - 2 Not Used		Not Installed		
3 - 4 Reformat E²Prom			Installed		
5 - 6	Erase Setpoints (at boot-up)		Installed		
7 - 8	DG81 Display Installed (default)		Installed		
	DG61 Display Installed		Not Installed		
9 - 10	Disable Watchdog	0000	Installed		

NOTE: Jumper 7-8 is normally the only jumper that would be installed (for a DG81 display only)

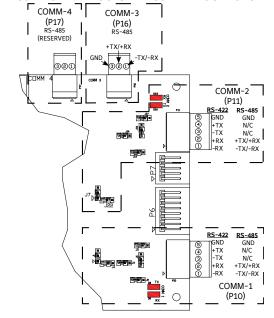
#### **COMMS 1 & 2 JUMPER SETTINGS**

(Comms 3 and 4 have no jumpers)

Comm 1	Comm 2	Function	Jumpe	er Setting	
	ī	RS-422 (4-Wire) <b>Default</b>	3	1 - 2 Closed	
J1	J7	RS-485 (2-Wire)	3 2 1 □ □	2 - 3 Closed	
J2	J13	Pull Down <b>Default</b>		1 Pin Only	
J3	J16	Pull Up <b>Default</b>		1 Pin Only	
J5	J17	RS-422 <b>Default</b>		1 Pin Only	
7.7	317	RS-485		1 - 2 Closed	
Ic	J6	J18			1 Pin Only
סר	1 110	RS-485		1 - 2 Closed	
J4	J22	High Speed Target  Default		1 - 2 Closed	

**NOTE:** The triangle symbol ( $\triangleleft$ ) denotes Pin 1 on connectors.

#### **COMMS 1-4 PINOUTS AND JUMPER LOCATIONS**

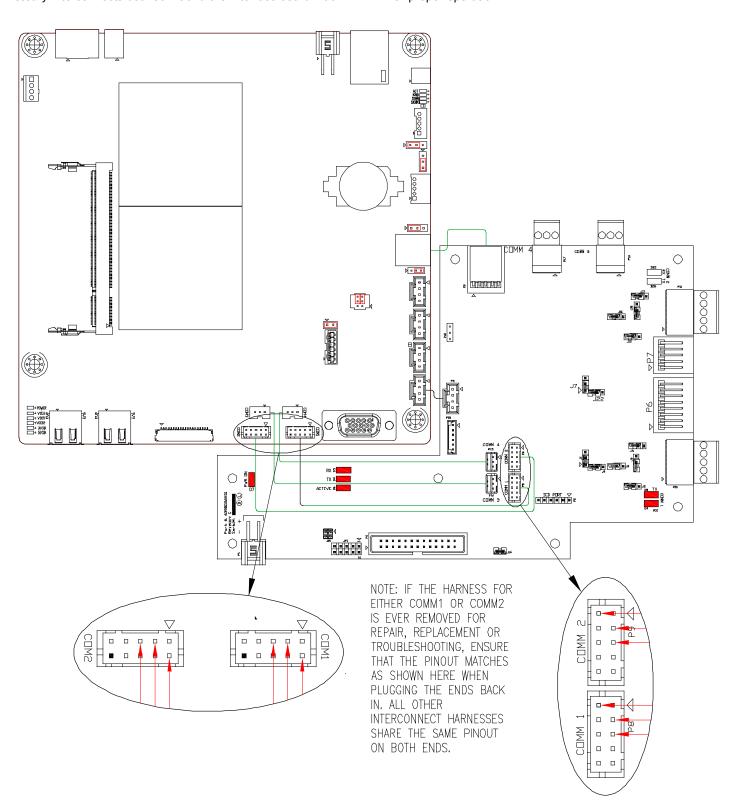




#### **Q5 INTERCONNECTIONS**

The pictorial below depicts the Q5 motherboard, and the necessary interconnects between it and the Interface board. Each

of the interconnecting harnesses must be installed as shown for proper operation.





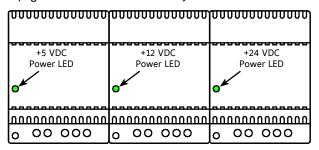
#### **POWER SUPPLY (Q5)**

#### DESCRIPTION

The power supply of the Q5 control panel consists of three independent supplies, and are located on the inside of the front door below the Interface board. They supply the following DC voltages:

- +5 VDC
- +12 VDC
- +24 VDC

All three supplies are adjustable and each has an indicator to show that they are powered. Refer to the following page for the location for the adjustment.



**Power Supplies** 

#### **POWER DISTRIBUTION**

DC power comming from the power supplies is wired directly to a series of terminal blocks. The terminals for these voltages are labled as follows:

- Common (1000)
- +24 VDC (1004)
- +5 VDC (1001)
- +12 VDC (1002)

Power is then distributed to the Q5 processor board, Interface Board, and Digital/Analog I/O boards from these terminals.

#### **MEASURING VOLTAGES**

CAUTION! Measuring and adjusting the power supply voltages require the control power switch to be energized. Extreme care must be observed when taking any readings, as 120 or 230 VAC (depending on incoming system voltage) will be present next to the DC voltage connector. Adjusting the supplies requires the use of a small Philips screwdriver inserted into the supply to access an adjusting potentiometer. CAUTION: It is possible for the screwdriver (and the person making the adjustment) to come into contact with potentially lethal voltages. Proper Personal Protective Equipment (PPE) measures need to be observed.

All circuit boards within the Q5 control panel require accurately adjusted DC voltages in order to function properly. Periodic measurement and adjustment of the DC power system is recommended for optimum system op-

eration. Over time, it is possible for temperature, humidity, vibration and component age, to degrade the accuracy of these voltages. When any of the DC voltages begin to stray from their optimum range, mysterious problems can begin to arise.

Even with a perfectly adjusted supply, it is possible for a potential drop in voltage at each connection point. This drop normally is in the millivolt range, but under some conditions, the drop can be much greater (as high as tenths of a volt). By the time the voltage reaches the last board in the daisy chain, and all of these potential voltage drops are considered, the combined drop can be such that problems can be apparent. Some examples of problems could be:

- · Loss of or intermittent communications failures.
- A shutdown message stating Digital Board x Reset (where "x" is replaced by the number of the Digital Board that failed).
- An shutdown message stating Digital Board x Comm. Fail - Shutdown (where "x" is replaced by the number of the Digital Board that failed).
- An shutdown message stating Analog Board x Comm. Fail - Shutdown (where "x" is replaced by the number of the Analog Board that failed).
- Numerous sensor fault shutdown messages.
- Q5 reboots for no apparent reason.
- Improper readings of analog pressures and temperatures.
- LED's on the Q5 are lit, but nothing appears on the display.

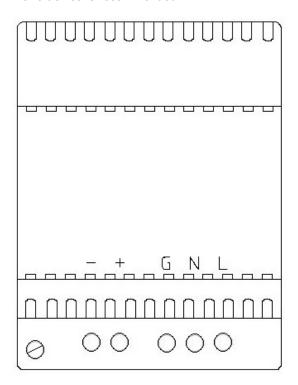
To perform measurements and adjustments on the power supply voltages, use a reliable, calibrated Digital Volt Meter (DVM). The DVM should be accurate to 1/100 of a volt DC. With the control power switch turned ON, wait until the Operating Screen appears. This is because the graphics required to create this screen will draw more current than when the screen is showing the normal POST (DOS) style messages during a boot up. If the screen never appears however (possibly due to a voltage problem), you will need to proceed regardless of what is or is not displayed.

In order to properly measure the DC power system, it must be checked at the DC power terminal strip.



#### **ADJUSTMENT**

Ensure that the meter is set to the proper range (DC, 0–50 V or equivalent), as well as observing proper wire polarity. The power supply drawing shown on the following page applies to all three power supplies. The adjustment access hole for each supply is located on the lower left of the front of the supplies. If an adjustment is required, use a thin, Philips screwdriver, insert the tip into the access hole for the appropriate voltage potentiometer (refer to the diagram on the following page for adjustment location). NOTE: Extreme care must be used when adjusting the potentiometer. Adjustment should only be performed by qualified personnel. The use of a non-conductive device is recommended.



#### +5 VDC Adjustment

Locate the DC power terminal strip. Terminal 1001 is the +5 VDC, and 1000 is common (COM).Place the negative lead on 1000, and the positive lead on 1001. Verify that the DVM is displaying in the range of +5.10 to +5.20.

If adjustment is required, locate the adjustment access hole on the +5 VDC supply, as previously shown. While watching the DVM, slowly rotate the screwdriver blade clockwise to increase the voltage or counter-clockwise to decrease until the voltage is correctly adjusted.

#### +12 VDC Adjustment

Locate the DC power terminal strip. Terminal 1002 is the +12 VDC, and 1000 is common (COM). Place the negative lead on 1000, and the positive lead on 1002. Verify that the DVM is displaying in the range of +12.10 to +12.20.

If adjustment is required, locate the adjustment access hole on the +12 VDC supply, as previously shown. While watching the DVM, slowly rotate the screwdriver blade clockwise to increase the voltage or counter-clockwise to decrease until the voltage is correctly adjusted.

#### +24 VDC Adjustment

Locate the DC power terminal strip. Terminal 1004 is the +24 VDC, and 1000 is common (COM). Place the negative lead on 1000, and the positive lead on 1004. Verify that the DVM is displaying in the range of +24.20 to +25.50.

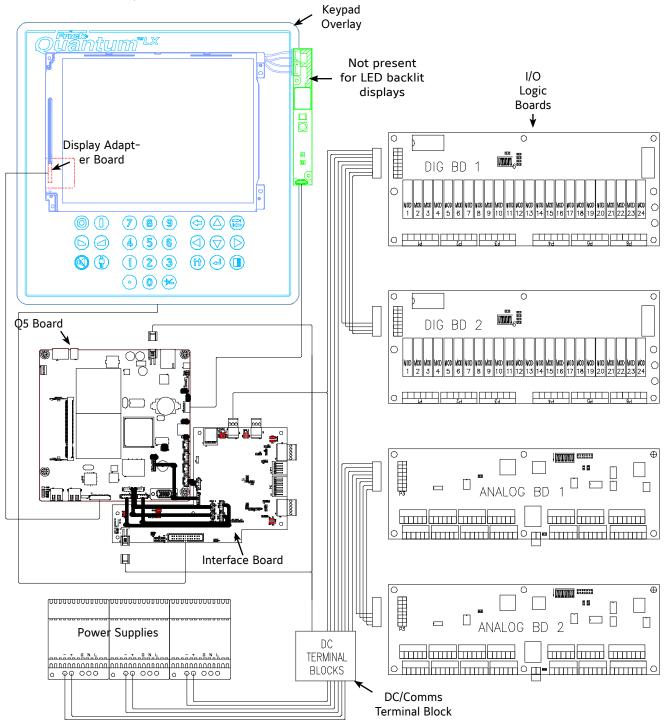
If adjustment is required, locate the adjustment access hole on the +24 VDC supply, as previously shown. While watching the DVM, slowly rotate the screwdriver blade clockwise to increase the voltage or counter-clockwise to decrease until the voltage is correctly adjusted.

#### POWER SUPPLY REPLACEMENT

If any of the power supplies are found to be bad, or not capable of acceptable adjustment, the failing supply will need replacing. Refer to the Recommended Spare Parts list for the appropriate part number.



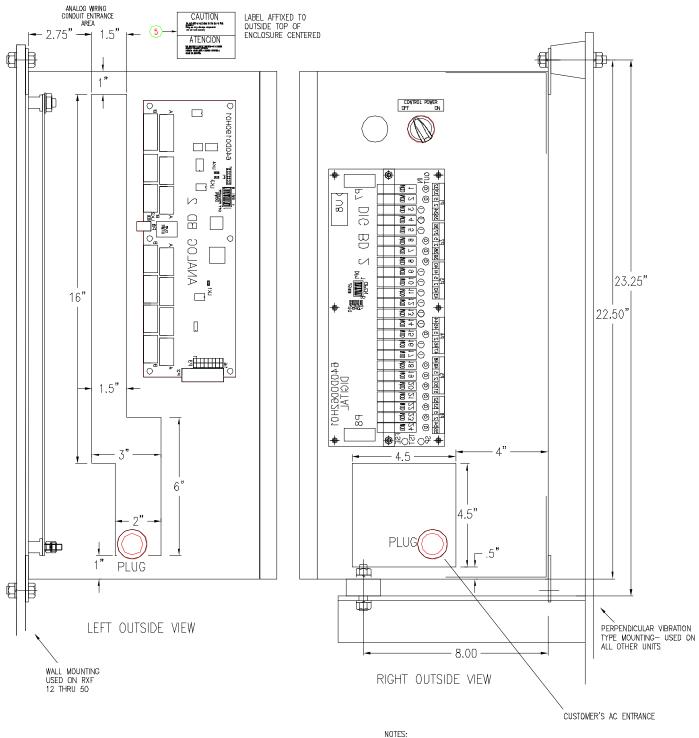
#### Q5 FLOW DIAGRAM - D.C. VOLTAGE/COMMUNICATIONS HARNESS



This pictorial represents a typical configuration using the Q5, and is not to scale. Specific units may or may not have both Digital and Analog boards, depending on options. Additionally, exact wiring to and from the DC Power Terminals is for reference only. The pictorial is meant to show the proper interconnection of the D.C. power - I/O communications harness, keyboard cable and display harness and hardware components. Refer to the wiring diagrams later in this manual for exact connections.



# Q5 RDB / RWB II / RWF / RXF (58-101) CONTROL CENTER ASSEMBLY (SHEET 1 OF 4)

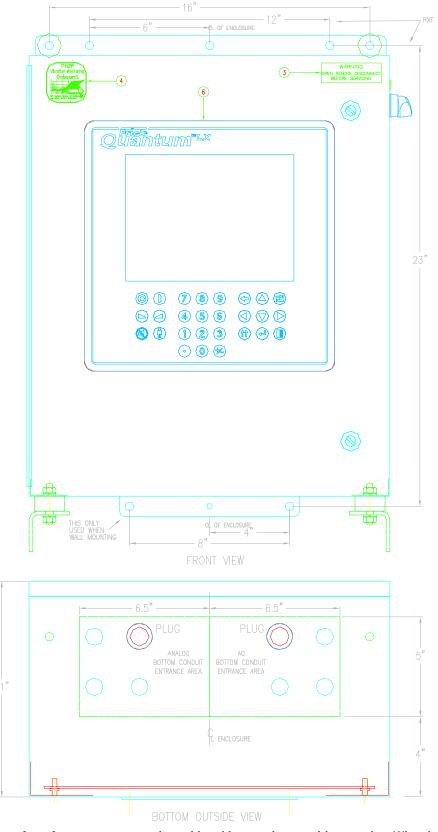


-ALL REFERENCES TO LEFT & RIGHT SIDE OF PANELS ARE FACING THE PANEL FROM THE FRONT

-RXF 12 THRU 50 UNITS USE THE BACK MOUNTING FLANGES TO MOUNT ENCLOSURE, PLUG TWO BOTTOM MOUNTING HOLES AT UNIT ASSEMBLY



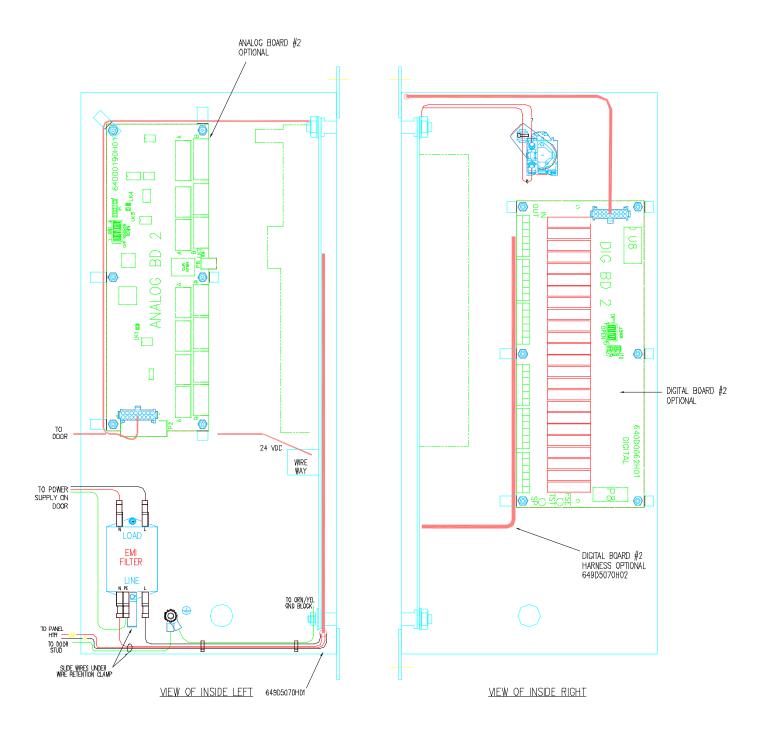
# Q5 RDB / RWB II / RWF / RXF (58-101) CONTROL CENTER ASSEMBLY (SHEET 2 OF 4)



This drawing appears here for reference purposes only, and is subject to change without notice. When installing, or servicing equipment, always refer to the actual drawings that are included with the control panel for the latest information.

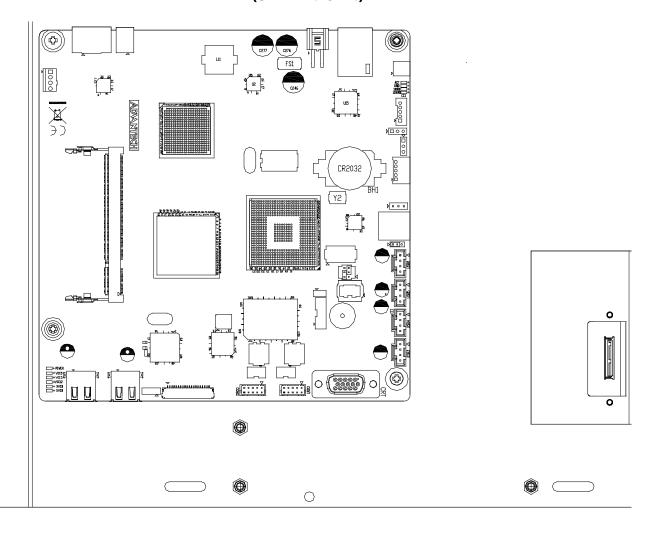


# Q5 RDB / RWB II / RWF / RXF (58-101) CONTROL CENTER ASSEMBLY (SHEET 3 OF 4)



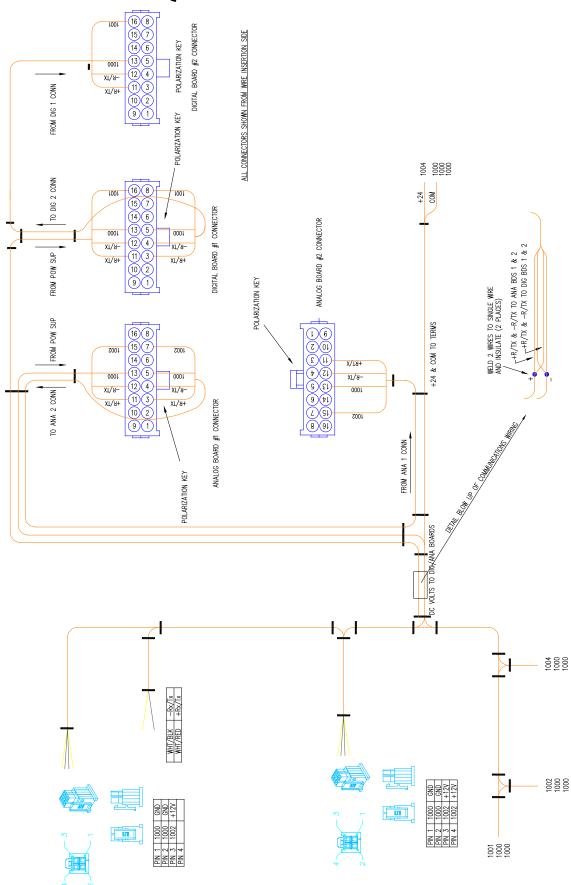


# Q5 RDB / RWB II / RWF / RXF (58-101) CONTROL CENTER ASSEMBLY (SHEET 4 OF 4)





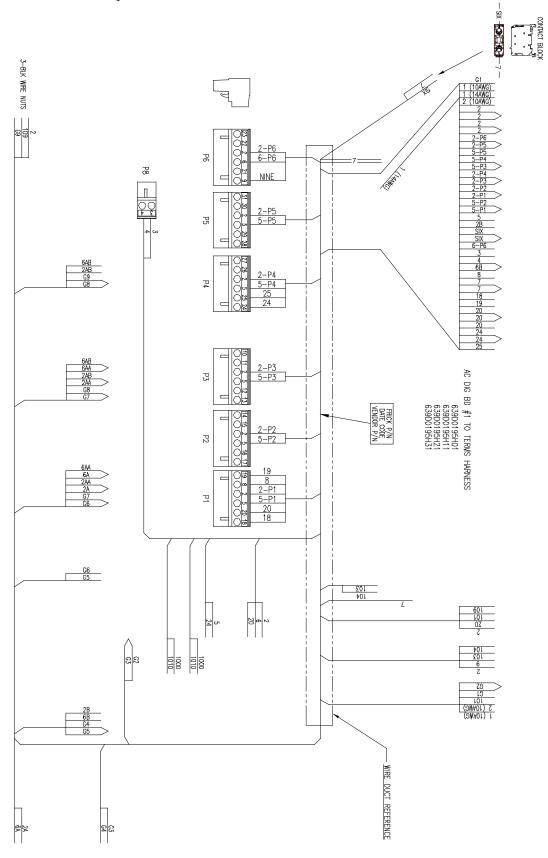
#### **Q5 I/O & DC POWER HARNESS**



# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$

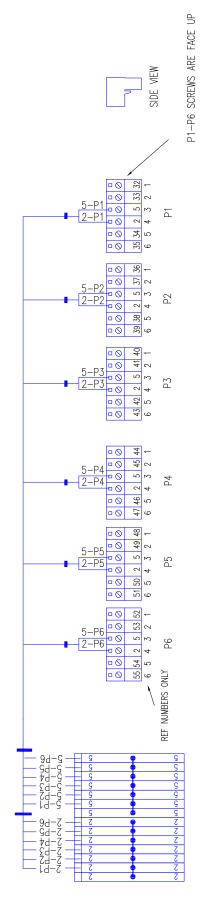


## Q5 A.C. POWER HARNESS (DIGITAL BOARD 2)





#### **Q5 A.C. POWER HARNESS**





#### **Q5 COMPRESSOR REPLACEMENT PARTS (PAGE 1 OF 3)**

Frick Number	SAP Number	Description
		Analog Boards <sup>(1)</sup>
640C0062G01	1107799	Analog Board #1 (Replaces existing "614" analog board only - no hardware)
640C0062G02	1107800	Analog Board #2 (Replaces existing "614" analog board only - no hardware)
640C0062G11	1108061	Analog Board #1 Field Upgrade Kit (Requires LX software version 7.11 or later and 24 VDC)
640C0062G12	1108062	Analog Board #2 Field Upgrade Kit (Requires LX software version 7.11 or later and 24 VDC)
		(1) Note: If replacing an older style analog board, contact Frick Service for details.
		Circuit Breakers
639A0206H10	484050	10 Amp circuit breaker
639A0206H15	484053	15 Amp circuit breaker
639A0206H20	484055	20 Amp circuit breaker
		Connectors
649A1027G14	643440	2-Pole connector (P8 – Analog Board)
649A1027G01	485871	6-Pole connectors (P1 through P6 – Digital Board 1)
649A1027G02	485872	6-Pole connectors (P1 through P6 – Digital Board 2)
649A1027G11	485874	6-Pole connectors (P4A through P7B – Analog Board 1 & 2)
649A1027G21	643460	6-Pole and 8-Pole connectors (P9A and P11B – Analog Board 1 & 2)
649A1027G31	643461	9-Pole connector (P2 – Analog Board 1 $\&$ 2, for vertically mounted boards with this connector at the top)
649A1027G41	643462	9-Pole connector (P2 – Analog Board 1 & 2, for vertically mounted boards with this connector at the bottom)
	•	Control Power
333Q0001418	467096	Filter, Line
333Q0001191	467024	Hour meter
639A0185H10	483963	2-Pos. Selector Switch (Control Power)
639A0185H30	483966	Latch, 3 Across (Attaches contact block to switch mechanism)
639A0185H31	483967	Normally Open Contact Block (for Control Power Switch)
639B0120H51	680313	Socket, Guarded, DPDT
639B0114H51	580348	Socket, Guarded, 3PDT
639B0114H98	580349	Spring Clip Hold Down
639B0120H01	680049	Relay, Control 24VDC, DPDT
639B0120H11	680311	Relay, Control 120VAC, DPDT
639B0120H21	680312	Relay, Control 240VAC, DPDT
639B0114H02	580342	Relay, Control 24VDC, 3PDT
639B0114H12	580345	Relay, Control 120VAC, 3PDT
639B0114H22	580347	Relay, Control 240VAC, 3PDT
639B0120H51	680313	Socket, Guarded, DPDT
639A0243H02	817257	Surge suppresser (2 inch leads)



#### **Q5 COMPRESSOR REPLACEMENT PARTS (PAGE 2 OF 3)**

Frick	SAP	Description			
Number	Number				
Digital Boards					
333Q0001172	467015	Output Module, 24 VDC			
111Q0281061	455056	Output Module, 24-280 VAC			
333Q0001171	467014	Input Module, 24 VDC			
333Q0000116	466842	Input Module, 120 VAC			
333Q0000789	466949	Input Module, 230 VAC			
333Q0001326	467073	Fuse, 5 amp, 250 V			
640C0024G01	484494	Digital Board #1 (Replaces existing board only - no hardware)			
640C0024G02	484495	Digital Board #2 (Replaces existing board only - no hardware)			
649D5210G21	660132	Digital Board #2 (Field Upgrade Kit- adds a second digital board for 22 x 18 x 10 panels)			
		Display Accessories			
639A0278H01	548266	Display Adapter Board (Bat Wing board)			
640A0032H01	484437	Plexiglas (mounts in front of display, plate does not have a notch)			
640A0032H02	569676	Plexiglas (mounts in front of display, plate has a notch)			
639B0117H01	670741	Harness, Display			
639B0126H01	884854	Harness, Inverter			
		Display Kit (Indoor LED)			
		Display Assembly includes:			
		Display, standard LED			
639D0230G01 *	865280 *	LVDS to VGA Converter (Bat Wing board)			
		Display Cable Assembly			
		LED Backlight Harness			
		Hardware			
		Display Kit (Outdoor LED)			
		Display Assembly includes:			
		Display, standard LED			
639D0230G11 *	865281 *	LVDS to VGA Converter (Bat Wing board)			
		Display Cable Assembly			
		LED Backlight Harness			
		Hardware			
		Fans			
649A0906G13	509129	Internal Circulation Fan, Field Install, 24 VDC			
649A0906G11	485514	Internal Circulation Fan, Field Install, 115 VAC			
649A0906G12	N/A	Internal Circulation Fan, Field Install, 220 VAC			

<sup>\*</sup> **NOTE:** When ordering a replacement display, please check for CPU BIOS version 1.13 and QLX software version 7.07 or newer (view the *ABOUT* screen). Contact Frick ECS for BIOS upgrade.



#### **Q5 COMPRESSOR REPLACEMENT PARTS (PAGE 3 OF 3)**

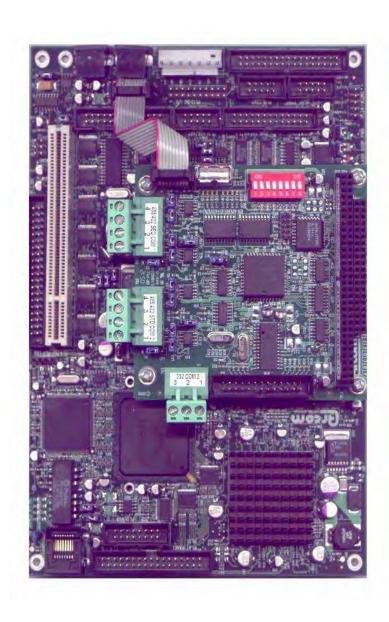
Frick Number	SAP Number	Description		
Flash Cards and Software				
649A1103Gxx	N/A	Quantum™ LX Program Flash Card (the xx indicates program version)		
649A1063G01	485994	Quantum™ LX program upgrade (USB Drive)		
649A1063G99	485995	Quantum™ LX Setpoint Saver (USB Drive)		
		Harnesses		
639D0191H02	696514	Harness Kit, Interface to Q5 board.		
639D0193H01	694589	Harness, DC Power-I/O Communications (standard LX panel 22" x 18" x 10")		
639D0195H01	694590	Harness, AC for Digital Board # 1, Q5		
639D0195H02	809832	Harness, AC for Digital Board # 2, Q5		
639D0210H01	827661	Harness, DC Power-I/O Communications (for LX panels 36" x 30" x 14" and 48" x 36" x 14")		
		Keypads		
640D0186H01	484621	Keypad/overlay with Frick logo (Quantum LX)		
		Miscellaneous		
333Q0001786	N/A	Battery, 3V (located on Q5 board)		
	Panel Heaters			
640M0007G16	484626	200 W, 115 VAC (24 x 22 x 10 panels)		
640M0007G18	484627	400 W, 115 VAC (36 x 30 x 13 panels)		
640M0007G27	484632	200 W, 220 VAC (24 x 22 x 10 panels)		
640M0007G21	484629	400 W, 220 VAC (36 x 30 x 13 panels)		
		Power Supply		
639B0115H01	642307	DC power supply – 5 VDC		
639B0115H02	642308	DC power supply – 12 VDC		
639B0115H03	642309	DC power supply – 24 VDC		
		Q5 Boards		
649C1152G01	813400	Q5 CPU Board Replacement (Q5 to Q5 Replacement Kit)		
639B0116G01	809831	Interface Board Q5 LX Field Replacement Kit w/screws		

#### **REMANUFACTURED PARTS**

Frick Number	SAP Number	Description	
640C0024S01	N/A	Digital I/O Board	
640C0057S01	484537	Analog I/O Board (32 Channel)	



# SECTION 3 Q4 CONTROLLER

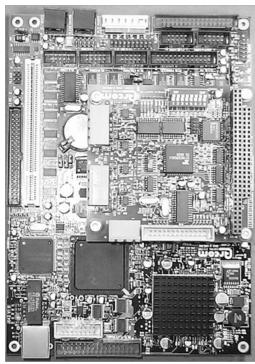




#### **Q4 CONTROLLER BOARD**

#### INTRODUCTION

Frick® Controls has strived to remain on the cutting edge of microprocessor technology and development. Because of the ever-increasing speed, memory features, and power of microprocessors, Frick® will continue to introduce the latest advancement in microprocessor control technology.



O4 Board

#### WHAT SHOULD OCCUR WHEN APPLYING POWER

The first thing that should be checked when troubleshooting the Q4 board is it's powering up sequence.

When powering up the Q4, the following sequence of events are indicative of a properly working main processor board:

- Green PWR (Power) LED will turn on solid.
- Red FLASH LED will flash several times early in the boot sequence. It is normally not lit.
- LED D8 (on the smaller board) will start to blink at the rate of about once-per-second. It will continue to blink after the Q4 has booted. The only time that this flashing rate is interrupted, is when a key is pressed on the keypad.
- The display should show several DOS (text) style screens. A penguin image will appear in the upper left corner of the screen as the boot sequence progresses.

- Just before fully booting, a Loading bar will appear at the bottom of the screen, showing the percent of load that has completed.
- · The Operating Status screen will appear.

After the Q4 has properly powered up, the following sequence of events is indicative of proper communication to the analog and digital boards:

- The Analog and Digital I/O boards TX/RX lights should be blinking.
- Each I/O board should have the power LED lighted and the Active LED should be blinking.

## WHAT IF THE OPERATING STATUS SCREEN IS NOT SHOWN

If the Operating Status screen is not shown, check the following items:

- If no LED's are lit, then check AC and DC power. Refer to the Power Supply section.
- Check if the lighting of the LED's is occurring as described in the What Should Occur When Applying Powering section.
  - If the powering up sequence continues to repeat without displaying the Operating Status screen, then there is a booting problem.
- 3. Check for bad connections.
- Check if an error message is displayed when booting.
  - Be sure to write down any error messages exactly as they appear.
- 5. Check that the software is OK:
  - Is the correct software installed?
  - · Did you just install new software?
- Remove Flashcard and reboot. This will cause the Q4 to boot under a pre-LX operating software. If it boots properly under this older software, then trying re-booting from the Flashcard again. If it doesn't boot with the card, then the Flashcard could be corrupted, and needs to be replaced.
- 7. Check the display. If the Q4 board is booting but you have no display, check the following:
  - · Check the backlight tube. Look very closely



at the display to see if anything is visible in the dark screen. Using a beam type source of good lighting, such as a flashlight, look for any ghost type image. If it appears that there is something on the screen but very dark, the problem may be with the backlight tube. On the LG Philips, NEC and Sharp displays this tube is field replaceable. On the Samsung display it is not available and the display will have to be replaced. There may be a sticker on the display mounting plate. If there is, it will have a part number that describes the type of display. If there is no sticker, you must take the display apart to identify the display manufacturer.

- Verify that both the display cable and the inverter cable are firmly seated. These cables both originate from the same connector on the Q4. It may be necessary to remove the video cable from the back of the display and re-seat it to be sure it is connected properly. Note: This is a small connector and caution should be observed so that it is not damaged due to excessive force.
- Refer to the Operator Interface section and check that the display, display cable, and software versions are matched correctly.

#### **BATTERY FUNCTION AND REPLACEMENT**

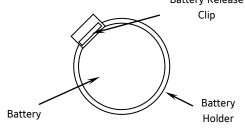
The Q4 board utilizes a battery to maintain correct date and time for the purpose of stamping warnings and shutdowns with the date and time that they occurred. If the date and time are not being maintained properly, it may indicate that the battery is not functioning, and should be replaced. The battery may be ordered through Baltimore Parts (P/N 333Q0001786) or may be purchased at most electronic shops (manufacturers P/N CR-2032).

The battery is partially covered by the communications daughter board, and is located directly beneath the COM1 port (it may be necessary to unplug any connector that is plugged into COM1 to fully access the battery).

To replace the battery, ensure that the Control Power switch has been turned OFF.

Locate the Battery Release Clip on the following drawing:

Battery Release

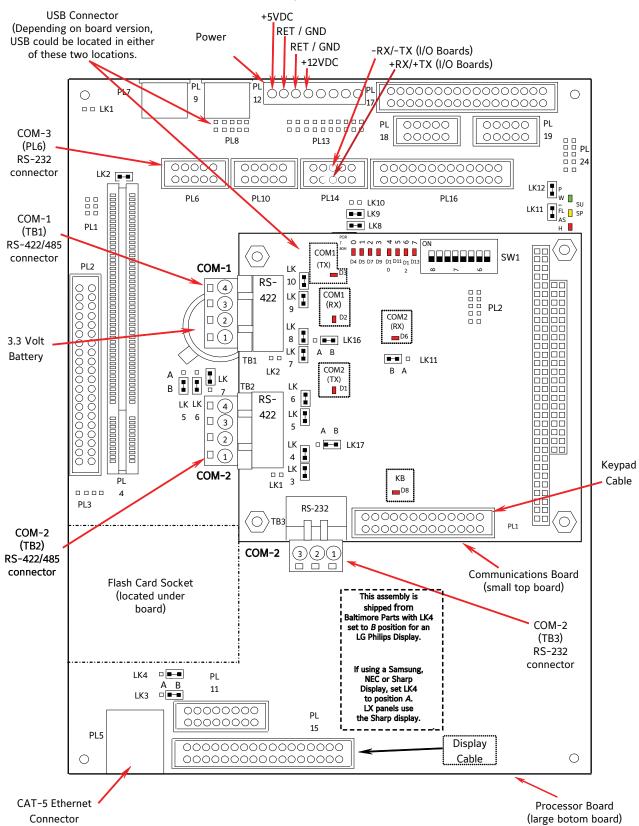


Simply push the clip away from the battery, to release the battery from the holder. Remove the battery, observing the orientation. Take a new battery and place it into the holder in the same orientation as the old battery (the side with the writing must be facing out). Reinstall the COM1 plug (if removed), and return the Control Power switch back to ON.

Once the Q4 has rebooted, the correct Date and Time must be set.







#### **Controller Board Pictorial**

Note: There are duplicate numbers for the links on the processor (larger) board and the communications (smaller) board. If you must make a change to a jumper (link), ensure that you modify the correct link.



#### **Q4 BOARD SETTINGS**

#### **Processor Board Jumpers**

LK1	in	2 second Watchdog timer timeout		
	out*	8 second Watchdog timer timeout		
	in*	Watchdog timer Enabled		
LK2	out	Watchdog timer Disabled		
1 1 1 0		<u> </u>		
LK3	A	+5V Backlight Voltage (not used)		
	В*	+12V Backlight Voltage (all displays)		
l	Α	+5V Supply (Samsung, NEC, Sharp)		
LK4	В*	+3.3V Supply (LG Philips & Sharp LED Display)		
LK5	Α	COM4 IRO3		
	B *	COM4 IRQ10		
		COM3 IDO4		
LK6	A	COM3 IRQ4		
	B *	COM3 IRQ11		
1 1/7	A *	Battery Backup Enabled		
LK7	В	Battery Backup Disabled (CMOS Cleared)		
	in*	RS-485 Receiver Enabled		
LK8	out	RS-485 Receiver Disabled		
LK9	in*	RS-485 Terminated		
	out	RS-485 Not Terminated		
	in	RS-422 Terminated		
LK10	out*	RS-422 Not Terminated		
LK11	in*	Bit 1 of 259H "Logic 1" User Application Link		
	out	Bit 1 of 259H "Logic O" User Application Link		
LK12	in*	Bit 2 of 259H "Logic 1" User Application Link		
	out	Bit 2 of 259H "Logic O" User Application Link		

<sup>\*</sup> Standard Setting

#### **Communications Board Jumpers**

#### Com-1 (TB1)

LK2	in out*	Terminate COM1 No termination	RS-422/485
LK7	in out*	Pull down COM1 No pull down	RS-422/485 (Rx-/Tx-)
LK8	in out*	Pull up COM1 No pull up	RS-422/485 (Rx-/Tx+)
LK9	in out*	Pull down COM1 No pull down	RS-422 (Tx-)
LK10	in out*	Pull up COM1 No pull up	RS-422 (Tx+)
LK16	A B*	COM1 RS-422 (TB1) COM1 RS-485 (TB1)	

<sup>\*</sup> Standard Setting

#### Com-2 (TB2 - TB3)

•		•	
LK1	in out*	Terminate COM2 No termination	RS-422/485
LK3	in out*	Pull down COM2 No pull down	RS-422/485 (Rx-/Tx-)
LK4	in out*	Pull up COM2 No pull up	RS-422/485 (Rx-/Tx+)
LK5	in out*	Pull down COM2 No pull down	RS-422 (Tx-)
LK6	in out*	Pull up COM2 No pull up	RS-422 (Tx+)
LK11	A B*	Select RS-232 for COM2 (TB2) Select RS-422/RS-485 for COM2 (TB3)	
LK17	A B*	COM2 RS-422 (TB2) COM2 RS-485 (TB2)	

<sup>\*</sup> Standard Setting



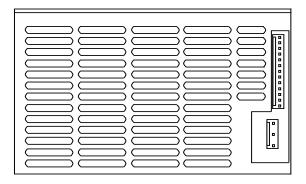
#### **Q4 POWER SUPPLY**

#### DESCRIPTION

The power supply used in the Q4 control panel is the Condor GLC-75D, and is shown below. This power supply provides the following DC voltages:

- +5 VDC
- +12 VDC
- -12 VDC
- +24 VDC

Of these four voltages, only the +5 VDC may be adjusted. Refer to the following page for the location of this potentiometer adjustment. If either the +12, -12 or +24 VDC is out of acceptable range, first check for short or a blown fuse. If no reason can be found for the loss of any DC voltages, then the power supply will need to be replaced.



**Power Supply** 

#### **MEASURING VOLTAGES**

All circuit boards within the Quantum™ control panel require accurately adjusted DC voltages in order to function properly. These voltages consist of +5 VDC, −12 VDC, +12 VDC and +24 VDC. Periodic measurement and adjustment of the DC power system is highly recommended for optimum system operation. Over time, it is possible for temperature, humidity, vibration and component age, to degrade the accuracy of these voltages. When any of the DC voltages begin to stray from their optimum range (especially +5 VDC), mysterious problems can begin to arise.

All four DC voltages originate from the power supply. They are then daisy-chained to the main board, and then on to all connected Digital and Analog boards. Refer to the Flow Diagrams for the Q4.

Even with a perfectly adjusted supply, it is possible for a potential drop in voltage at each connection point within the daisychain. This drop normally is in the millivolt range, but under some conditions, the drop can be much greater (as high as tenths of a volt). By the time the voltage reaches the last board in the daisy chain, and all of these potential voltages drops are considered, the combined drop can be such that serious problems can be apparent. Some examples of serious problems could be:

Loss of or intermittent communications failures.

- A shutdown message stating Digital Board x Reset (where "x" is replaced by the number of the Digital Board that failed).
- An shutdown message stating Digital Board x Comm. Fail - Shutdown (where "x" is replaced by the number of the Digital Board that failed).
- An shutdown message stating Analog Board x Comm. Fail - Shutdown (where "x" is replaced by the number of the Analog Board that failed).
- Numerous sensor fault shutdown messages.
- Q4 reboots for no apparent reason.
- Improper readings of analog pressures and temperatures.
- LED's on the Q4 are lit, but nothing appears on the display.

In order to properly measure the DC power, it must be checked at the Q4 main board, and verified for acceptable total voltage drop at the end of the daisy chain (last I/O board). For the +5 VDC (on either power supply), if the voltage at the Q4 is in the range of +5.15 to +5.20), and the voltage being read at the last I/O board is greater than +5.0 V, it can be assumed that the +5 V power is correctly adjusted. For the +12 VDC, if the range at the last I/O board is between +11.8 and +12.2 VDC (+12.00 is ideal), it can be assumed that the +12 V power is correct. The range for this voltage is not critical at the Q4 main board, and the reading does not need to be taken there.

CAUTION! Measuring and adjusting the power supply voltages require the control power switch to be energized. Extreme care must be observed when taking any readings, as 120 or 230 VAC (depending on incoming system voltage) is present within the power supply. Adjusting the supply requires the use of a small screwdriver with an insulated shaft (refer to NS-10-02) inserted into the supply to access an adjusting potentiometer. It is possible for the screwdriver (and the person making the adjustment) to come into contact with potentially lethal voltages.

#### **FUSE REPLACEMENT**

If voltage is NOT present at any of the DC power points, but proper AC voltage is measured at the AC input, one problem could be that there is a short on the DC Power Harness.

To isolate the problem:

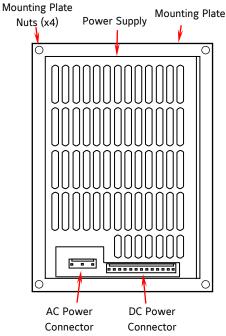
- Turn the Control Power switch to OFF.
- Unplug the DC power connector from the power supply.
- 3. Turn the Control Power switch back ON.
- Measure the voltages on the DC power output connector of the power supply as shown at the end of this section.



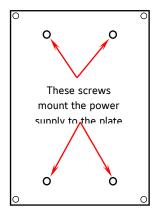
If the proper voltages are present, the problem is external to the power supply, and further troubleshooting should be performed.

If there are NO DC voltages present, then the problem could be that the internal power supply fuse is blown. To access and replace this fuse, please follow these instructions:

- Ensure that the Control Power switch has been turned OFF.
- Remove the AC and DC power connectors from the power supply.
- The power supply is mounted to a plate. Remove the four mounting plate nuts (one from each corner).

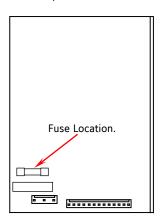


- 4. Remove the power supply from the enclosure, and turn it over (so power supply is facing down).
- 5. Four screws attach the power supply to the mounting plate, remove the four screws.



Remove the three Philips head screws located on the bottom of the power supply, and two on the side. Notice that there are also three slot-

- ted screws on the side of the supply, DO NOT remove these.
- Carefully lift of the slotted cover. This will expose the circuit board, as shown here:



- 8. Locate the fuse on the circuit board from the above drawing. It is mounted in a clip. Pry up on one end of the fuse and extract the fuse.
- Verify that the fuse in question is actually bad, and if so, replace the bad fuse with a known good one. Fuses may be ordered from Baltimore Parts (P/N 649A0954H19). This fuse is rated for 3.15 amps @ 250 volts.
- Reassemble the power supply in the reverse order that it was disassembled.
- 11. Mount the power supply on to its mounting plate.
- 12. Place the power supply/mounting plate back onto the studs in the enclosure, and secure with the mounting nuts.
- 13. Reattach the AC and DC power harnesses.
- 14. Turn the Control Power switch to ON.
- 15. Verify that DC voltages are now present on the DC power connector. The 5 VDC may now be adjusted per the adjustment procedure on the following page.

#### **ADJUSTMENT**

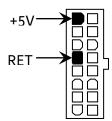
To perform measurements and adjustments on the power supply voltages, use a reliable, calibrated Digital Volt Meter (DVM). The DVM should be accurate to 1/100 of a volt DC. With the control power switch turned ON, wait until the Operating Screen appears. This is because the graphics required to create this screen will draw more current than when the screen is showing the normal POST style messages during a boot up. If the screen never appears however (possibly due to a voltage problem), you will need to proceed regardless of what is or is not displayed.

Ensure that the meter is set to the proper range (DC, 0-50 V or equivalent), as well as observing proper wire polarity. Measure the +5 VDC first. Place the negative lead on the common (return) pin, and the positive lead on the +5 VDC pin as shown. Verify that the DVM is displaying in the range of +5.15 to +5.20. If the reading is outside of this range, then using a thin, flat bladed, insulated screwdriver, insert the tip into the access hole for the appropriate voltage potentiometer (refer to the diagram on the following



page for adjustment location). NOTE: Extreme care must be used when adjusting the +5 VDC potentiometer. Adjustment should only be performed by qualified personnel, using an insulated screwdriver.

While watching the DVM, slowly rotate the screwdriver blade clockwise to increase the voltage or counter-clockwise to decrease. Once the voltage has been adjusted, remove the DVM probes from the Quantum<sup>™</sup>, and install them into the white connector on the last I/O board in the daisy chain, as shown below:



Check the reading on the DVM. If the reading at the Q4 has been adjusted properly, then this reading can be no lower than +5.0 VDC. If the voltage is less, check all of the daisy chain connections on the blue DC-I/O harness. Ensure that all of its connectors are tight. If all connections are good, then go back and start measuring over again, this time beginning at the first board in the daisy chain. Continue checking the voltage at each connection, until you locate the point at which the voltage drop is excessive. This will usually indicate a connection that is not being made properly, or the sockets within the connector are weak. In either case, the DC-I/O wire harness may need replacing.

Next measure the +12 VDC. Perform the same steps as with the +5 VDC measurement, with the exception that you will not need to measure at the Q4. Measure directly at the last connection. If the voltage is low, ensure that there is not an excessive voltage drop in the daisy chain. If the voltage is out of range, then the supply itself may need replaced.

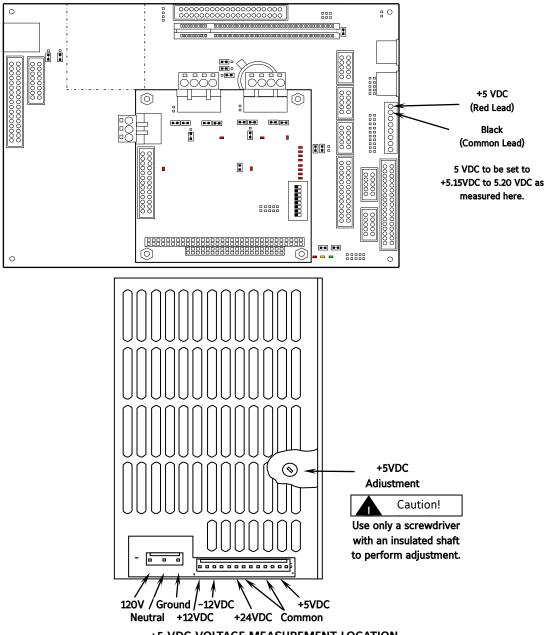
The -12 VDC may be measured the same as the other voltages, however, this voltage is not adjustable on any supply, so if the harness is not the culprit, the supply may need to be replaced.

#### POWER SUPPLY REPLACEMENT

If the power supply is found to be bad, or not capable of acceptable adjustment, it will need replacing. When ordering this replacement, you will receive an upgrade kit. The purpose of this kit is to allow for the upgrading of the I/O DC power harness, at the same time as replacing the power supply. Refer to the Recommended Spare Parts list for the upgrade part number. This upgrade kit will include the following components:

- Screws (6-32 x 3/8 flat head)
- Power supply (Condor)
- DC power cable harness (this is an improved version of the previous power cable)



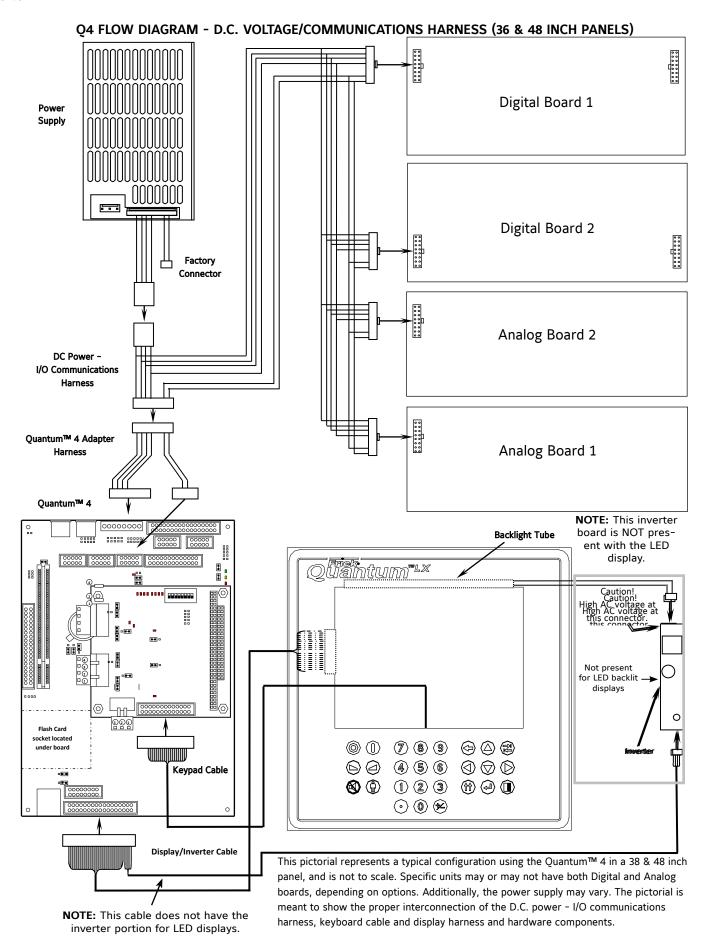


+5 VDC VOLTAGE MEASUREMENT LOCATION

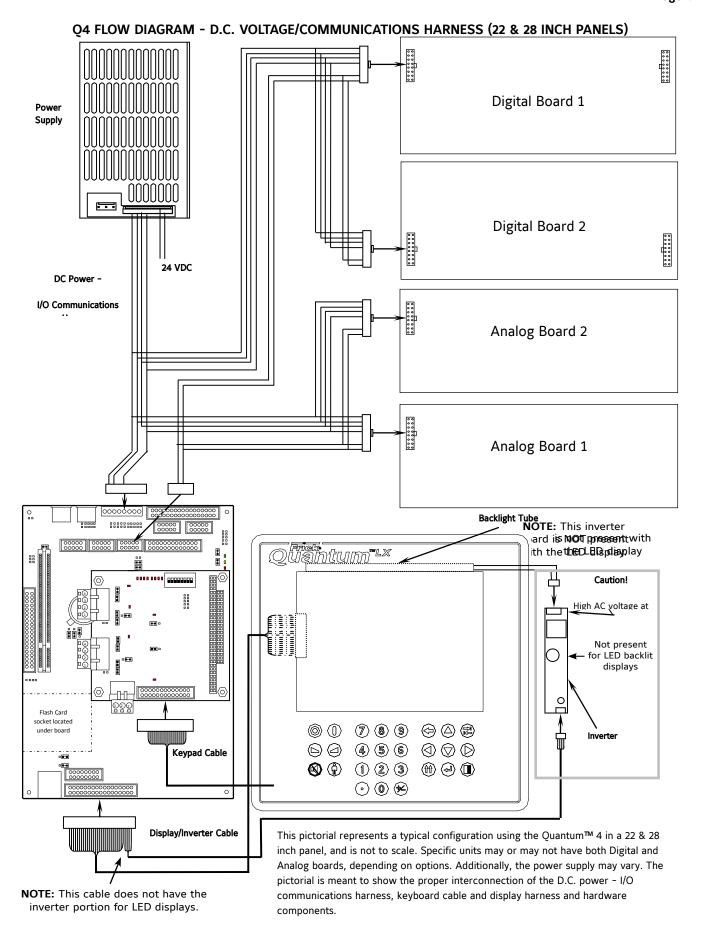
#### DC POWER SUPPLY PIN ASSIGNMENTS

INPUT: J1		'		INPUT: J	J2
AMP P/N: 640445-5			İ	AMP P/I	N: 1-640445-3
.312 CTR CONNECTOR,	3 CIRCUITS			156 CTR	CONNECTOR, 13 CIRCUITS
Pin 1 AC GROUND		'		PIN 1	OUTPUT #1 (+5.1V)
Pin 3 AC NEUTRAL	'			PIN 2	OUTPUT #1 (+5.1V)
PIN 5 AC LINE	'			PIN 3	OUTPUT #1 (+5.1V)
				PIN 4	COMMON
MATING CONNECTORS:	MOLEX			PIN 5	COMMON
	HOUSING	CONTACT		PIN 6	COMMON
INPUT	26-03-4050	08-52-0113		PIN 7	COMMON
OUTPUT	26-03-4131	08-52-0113		PIN 8	OUTPUT #2 (+24V)
				PIN 9	OUTPUT #2 (+24V)
				PIN 10	POWER FAIL
				PIN 11	OUTPUT #3 (-12V)
				PIN 12	COMMON
				PIN 13	OUTPUT #4 (+12V)



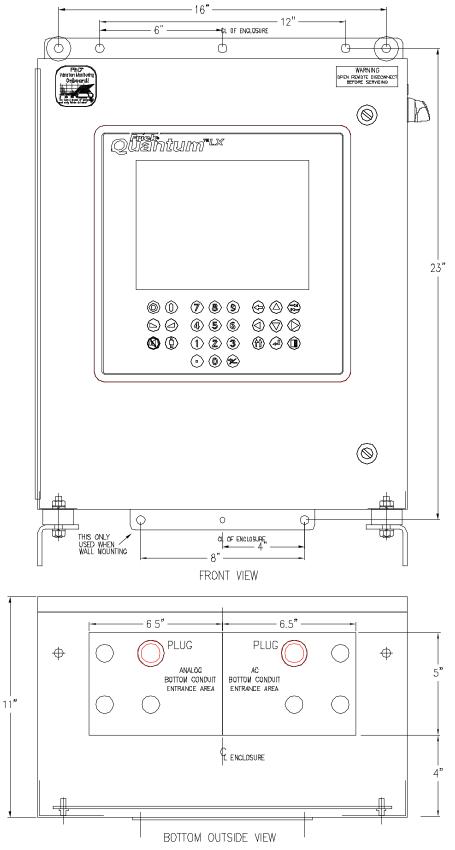








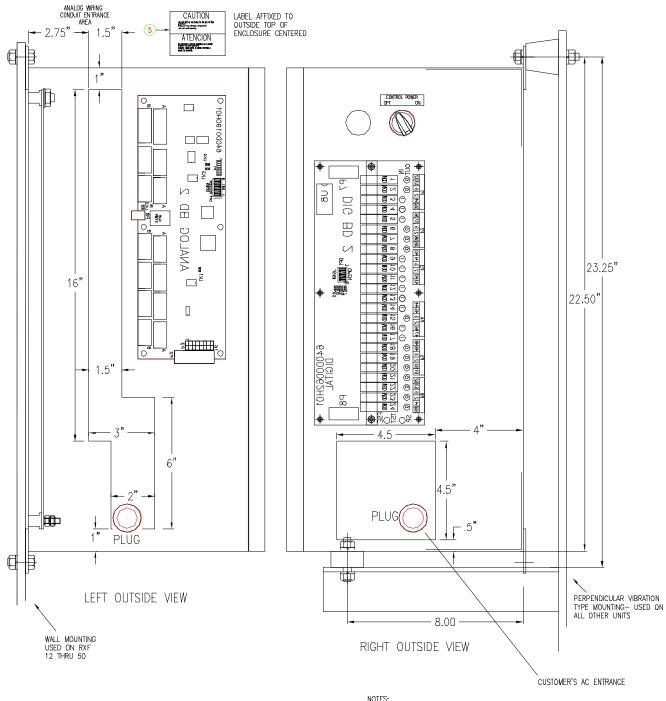
# Q4 RDB / RWB II / RWF / RXF (58 - 101) CONTROL CENTER ASSEMBLY (Sheet 1 of 4)



This drawing appears here for reference purposes only, and is subject to change without notice. When installing, or servicing equipment, always refer to the actual drawings that are included with the control panel for the latest information.



# Q4 RDB / RWB II / RWF / RXF (58 - 101) CONTROL CENTER ASSEMBLY (Sheet 2 of 4)

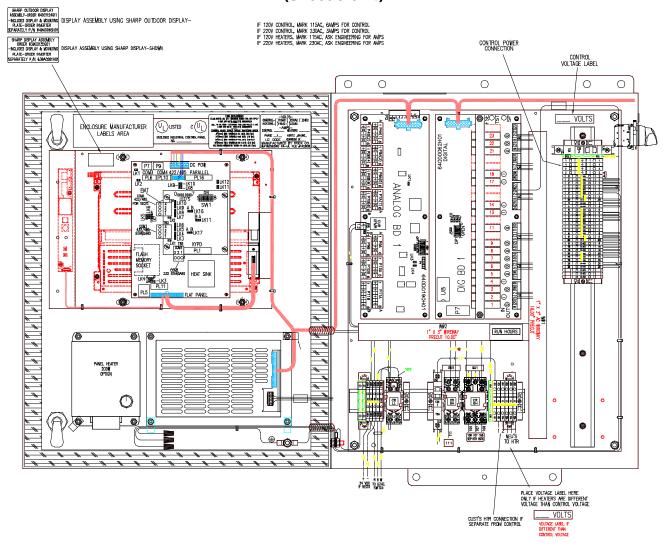


-ALL REFERENCES TO LEFT & RIGHT SIDE OF PANELS ARE FACING THE PANEL FROM THE FRONT

-RXF 12 THRU 50 UNITS USE THE BACK MOUNTING FLANGES TO MOUNT ENCLOSURE. PLUG TWO BOTTOM MOUNTING HOLES AT UNIT ASSEMBLY

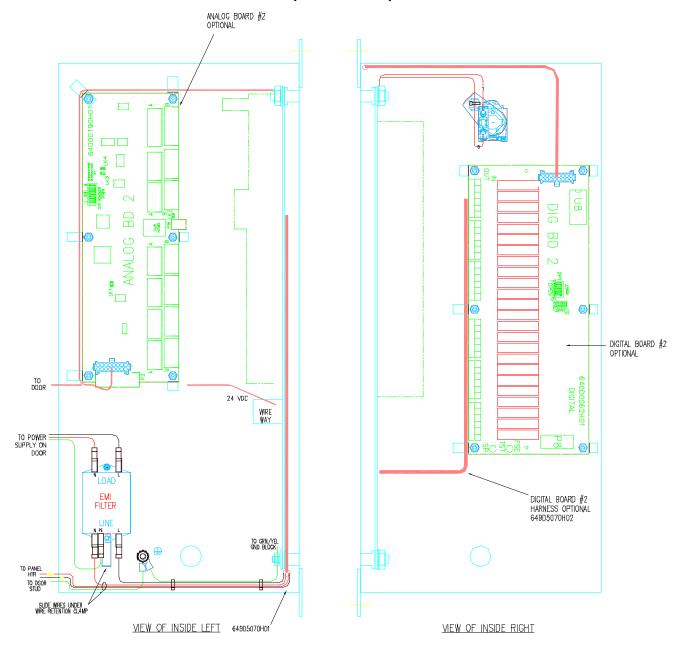


## Q4 RDB / RWB II / RWF / RXF (58 - 101) CONTROL CENTER ASSEMBLY (Sheet 3 of 4)



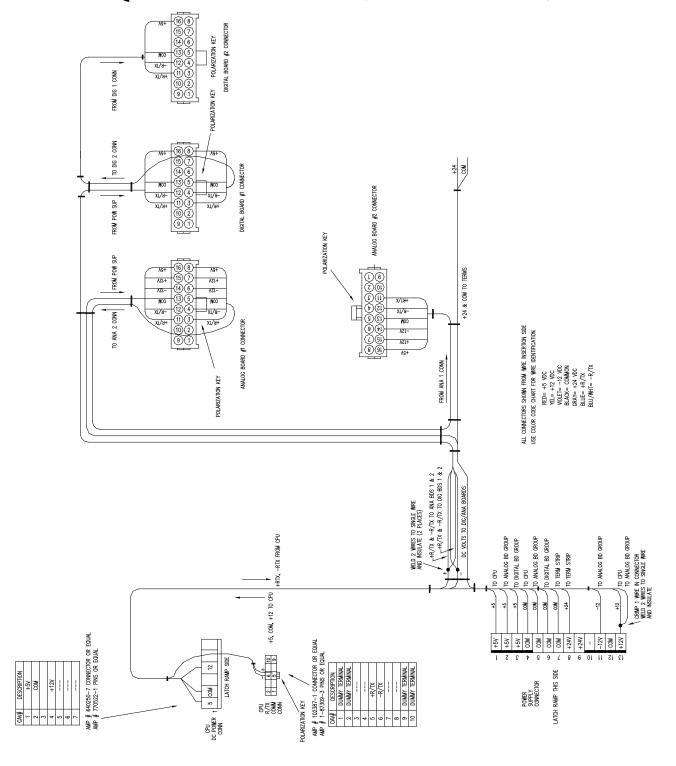


# Q4 RDB / RWB II / RWF / RXF (58 - 101) CONTROL CENTER ASSEMBLY (Sheet 4 of 4)



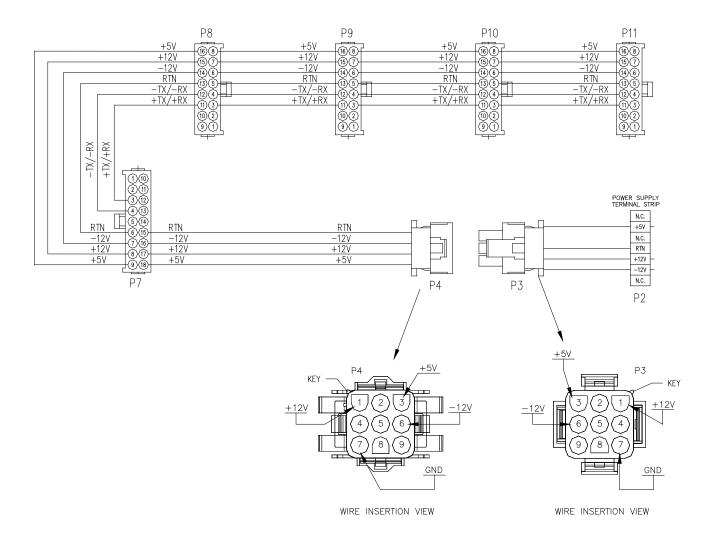


#### Q4 I/O & D.C. POWER HARNESS (22 AND 28 INCH PANELS)





### Q4 I/O & D.C. POWER HARNESS (36 AND 48 INCH PANELS )





### Q4 COMPRESSOR REPLACEMENT PARTS (PAGE 1 OF 3)

Frick	SAP	Description
Number	Number	Analog Boards <sup>(1)</sup>
640C0062G01	1107799	Analog Board #1 (Replaces existing "614" analog board only - no hardware)
640C0062G01	1107799	Analog Board #2 (Replaces existing '614" analog board only - no hardware)
640C0062G02	1108061	Analog Board #2 (Replaces existing 0.14 analog Board only 110 hardware)  Analog Board #1 Field Upgrade Kit (Requires LX software version 7.11 or later and 24 VDC)
640C0062G12	1108062	Analog Board #2 Field Upgrade Kit (Requires LX software version 7.11 or later and 24 VDC)
01000002012	1100002	(1) Note: If replacing an older style analog board, contact Frick Service for details.
		Circuit Breakers
639A0206H10	484050	10 Amp circuit breaker
639A0206H15	484053	15 Amp circuit breaker
639A0206H20	484055	20 Amp circuit breaker
		Connectors
649A1027G14	643440	2-Pole connector (P8 – Analog Board)
649A1027G01	485871	6-Pole connectors (P1 through P6 – Digital Board 1)
649A1027G02	485872	6-Pole connectors (P1 through P6 – Digital Board 2)
649A1027G11	485874	6-Pole connectors (P4A through P7B – Analog Board 1 & 2)
649A1027G21	643460	6-Pole and 8-Pole connectors (P9A and P11B - Analog Board 1 & 2)
		9-Pole connector (P2 - Analog Board 1 & 2, for vertically mounted boards with this connec-
649A1027G31	643461	tor at the top)
649A1027G41	643462	9-Pole connector (P2 - Analog Board 1 & 2, for vertically mounted boards with this connec-
		tor at the bottom)
2222222442	467006	Control Power
333Q0001418	467096	Filter, Line
333Q0001191	467024	Hour meter
639A0185H10	483963	2-Pos. Selector Switch (Control Power)  Latch, 3 Across (Attaches contact block to switch mechanism)
639A0185H30 639A0185H31	483966 483967	Normally Open Contact Block (for Control Power Switch)
333Q0000195	466846	Relay Base, 2 Pole
333Q0000193 333Q0000207	466849	Relay Base, 3 Pole
333Q0000207 333Q0000196	466847	Relay Hold Down Clips
333Q000195	466996	Relay, 2 Pole, 24 VDC
333Q0000194	466845	Relay, 2 Pole, 115 VAC
333Q0000154 333Q0000898	466979	Relay, 2 Pole, 220 VAC
333Q0000520	466897	Relay, 3 Pole, 24 VDC
333Q0000206	466848	Relay, 3 Pole, 115 VAC
333Q0000897	466978	Relay, 3 Pole, 220 VAC
639A0243H02	817257	Surge suppresser (2 inch leads)
		Digital Boards
333Q0001172	467015	Output Module, 24 VDC
111Q0281061	455056	Output Module, 24-280 VAC
333Q0001171	467014	Input Module, 24 VDC
333Q0000116	466842	Input Module, 120 VAC
333Q0000789	466949	Input Module, 230 VAC
333Q0001326	467073	Fuse, 5 amp, 250 V
640C0024G01	484494	Digital Board #1 (Replaces existing board only - no hardware)
640C0024G02	484495	Digital Board #2 (Replaces existing board only - no hardware)
649A1027G01	485871	Digital Board #1 Labeled Terminal Block Kit
649A1027G01	485872	Digital Board #2 Labeled Terminal Block Kit
0.5.1102,001	1 .555,2	



#### **Q4 COMPRESSOR REPLACEMENT PARTS (PAGE 2 OF 3)**

649D5210G11	486364	Digital Board #2 (Field Upgrade Kit– adds a second digital board for 22 x 18 x 10 panels)							
Frick Number	SAP Number	Description							
		Display Accessories							
639A0261H01	484329	CCFL inverter							
639D0216H01	913735	Display Harness, 10 inch (Q4 or LX processor mounted on display plate)							
639D0216H11	913736	Display Harness, 21 inch (Q4 or LX processor mounted on swing-out door)							
640A0032H01	484437	Plexiglas (mounts in front of display, plate does not have a notch)							
640A0032H02	569676	Plexiglas (mounts in front of display, plate has a notch)							
		Display Kit (Indoor LED)							
		Display Assembly includes:							
		Display (Cannot be ordered separately)							
639D0215G01	913882	Mounting plate							
		Display Harness, for Q4 or LX, standard panel							
		Display Harness for Q4 or LX, swing-out door							
		Hardware							
		Display Kit (Outdoor LED)							
		Display Assembly includes:							
		Display (Cannot be ordered separately)							
639D0215G11	913883	Mounting plate							
		Display Harness, for Q4 or LX, standard panel							
		Display Harness for Q4 or LX, swing-out door							
		Hardware							
		Fans							
649A0906G13	509129	Internal Circulation Fan, Field Install, 24 VDC							
649A0906G11	485514	Internal Circulation Fan, Field Install, 115 VAC							
649A0906G12	N/A	Internal Circulation Fan, Field Install, 220 VAC							
		Flash Cards and Software							
649A1121Gxx	485431	Quantum™ LX Program Flash Card (the xx indicates program version)							
649A1063G01	485994	Quantum™ LX Program upgrade (USB drive)							
649A1063G99	485995	Quantum™ LX Setpoint Saver (USB drive)							
649D5236G11	486386	Quantum™ LX Upgrade Kit (upgrades from Q4A to Quantum™ LX, includes Frick logo keypad and flash card)							
		Harnesses							
649D5070H01	486299	AC harness for Digital Board #1 (22" x 18" x 10" panel)							
649D5070H02	486300	AC Harness for Digital Board #2 (22" x 18" x 10" panel)							
639D0184H01	721249	DC power-I/O Comms harness (36" x 30" x 14" and 48" x 30" x 14" panel, color-coded)							
649D5069H01	486298	DC power-I/O Comms harness (22" x 18" x 10" panel, color-coded harness)							
640B0031H01	484470	Keypad cable (used with 640D0060H11 keypad)							
640B0039H01	484473	Shunting plug (used with 640B0038H01 harness only)							
649B0915H01	486163	AC Power to Power Supply							
		Keypads							
640D0186H01	484621	Keypad/overlay with Frick logo (Quantum LX)							
640D0060H11	484556	Keypad/overlay with Frick logo for upgrading from Quantum to Quantum LX							
		1							



#### **Q4 COMPRESSOR REPLACEMENT PARTS (PAGE 3 OF 3)**

		Miscellaneous
333Q0001786	N/A	Battery, 3V (located on Q3, and 4 board)
Frick Number	SAP Number	Description
		Panel Heaters
640M0007G16	484626	200 W, 115 VAC
640M0007G18	484627	400 W, 115 VAC
640M0007G27	484632	200 W, 220 VAC
640M0007G21	484629	400 W, 220 VAC
		Power Supply
640C0022G01	484492	DC power supply – Condor GLC-75D (includes power supply harness)
649A0954H19	485608	Fuse, 3.15A @ 250V (for Condor GLC-75D)
649A1036H08	485887	24 VDC Power Supply, 3 Amp, din-rail mounted (Power Pac)
649A1036H12	485889	24 VDC Power Supply, 5 Amp, din-rail mounted (Power Pac)
		Q4 Boards
649C1091G01	486194	Q4 (Arcom GX1)
639C0130G01	484378	Communications Daughter board only for Q4.
649C1083G01	486181	Upgrade from Q1, 2 or 3 to Q4
649C1093G01	N/A	Upgrade from Q1, 2 Lite to Q4
649C1092G01	N/A	Upgrade from Q3 Lite to Q4

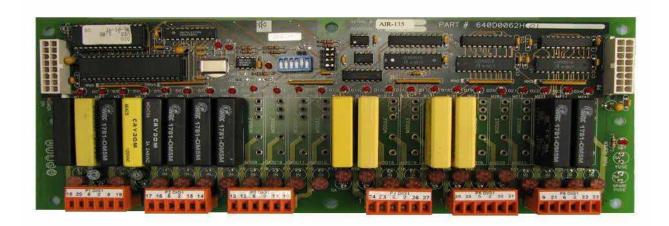
#### **REMANUFACTURED PARTS**

Frick Number	SAP Number	Description
640C0024S01	N/A	Digital I/O Board
640C0022S01	N/A	DC Power Supply (Condor to Condor)
640C0057S01	484537	Analog I/O Board (32 Channel)
649C1091S01	486198	Q4 to Q4



### **SECTION 4**

### **DIGITAL BOARD**





#### **DIGITAL BOARD**

#### **INFORMATION**

The information that follows in this section can help locate problems that can occur with Digital Input and Output circuit boards.

#### **DIGITAL BOARD DESCRIPTION**

The Digital board is a small microprocessor board and is programmed to control discrete outputs, or accept discrete inputs, from external electrical devices. Each Digital board has the capability of 24 independent channels or I/O (Input/Output). Each channel that is used needs a module plugged into it. A yellow module indicates that it is used for Inputs. A black module is used for Outputs. The standard Quantum™ LX compressor control can have up to two Digital boards (depending on options).

NOTE: The Digital Board is controlled through serial communications from the Quantum™ controller. If communications to the Quantum™ is lost for any reason, the Digital Board will initiate a watchdog timeout sequence and the board will reset after 10 seconds of no communication. When the board is reset, all the outputs on the Digital Board will be turned off which will de-energize the control signals to any equipment being controlled from the digital board.

#### **COMMUNICATIONS LED'S**

The main board is in constant communication with all Digital (and Analog) Boards. You will notice on each Digital and Analog board, that there are a pair of LED's labeled as RX and TX. These letters represent Receive (RX) and Transmit (TX). These LED's should be flashing at a high rate during normal operation. This indicates that the main board, and the Digital board that you are looking at, are properly communicating with each other.

 Reference the JUMPER AND DIPSWITCH SET-TINGS section later in this manual. This section contains the dipswitch settings for addressing the Digital I/O boards. When these switches are properly set, the main board is able to serially communicate with each I/O board and provide control signals and data exchange. If these switches are not properly set, the result will be lost or failed communications, or the wrong outputs being energized, or the wrong inputs being received.

#### CONNECTIONS TO THE QUANTUM™

As stated earlier, the Quantum™ LX standard compressor control system utilizes up to two Digital, and two Analog boards. To connect these boards together so that the Quantum™ LX can control them, they must be interconnected with a wiring harness that provides all of the necessary D.C. voltage requirements, as well as the communications capabilities.

The Digital boards only require the +5 Vdc voltage and the Return (or common) for logic power. The communications signals (RX & TX) are required by all boards.

Three different harnesses have been used and a diagram of each of these wiring harnesses can be found later in this manual (see the Power I/O Wiring Harness drawings). Depending on the type of panel, the following harness will be used:

Special Q4 Panel (36 & 48 Inch Panels) - This
harness has an 18-pin connector at one end
that plugs into the Quantum™. Another connector plugs into the power supply. The remaining
four connectors (16-pin) will plug into each of
the Digital and Analog boards in the system. All
wires in this harness are blue in color.

Upon close examination of this harness, you will notice that each of the connectors for both the main board and the four I/O boards, have two rows of connections. The wires that are inserted into the positions of one row are internally daisy chained on each I/O board, to continue the voltages and signals to the adjacent row. Therefore, any time that a connector is unplugged from the daisy chain, these voltages and signals cannot continue through the daisy chain to the next board. Whenever a plug is not to be inserted into a board, either for service or if not all boards are present, then a shunting plug (Frick P/N 484473) must be installed onto the open connector.

The four wires that feed from the power supply to the Q4 provide all of the necessary D.C. voltage that is required for the system (+5 VDC, -12 VDC, +12 VDC, and Return or Common). As mentioned previously, the -12VDC and +12VDC are not required for the Digital boards, but they are still daisy-chained on this harness for the Analog boards.

The voltages are passed through the connector on the main board, and two new signals are generated by the main board to be passed on through the daisy chain to the I/O boards. These two signals are the RX (receive) and TX (transmit). These signals are the means by which the main board communicates to the I/O.

Standard Q4 Panel (22 & 28 Inch Panels) - This harness has a 7-pin connector at one end that plugs into the Q4 at PL12, and provides power to the Q4. A second 10-pin connector plugs into PL14 of the Q4, where the communications signals originate. Another connector plugs into the power supply and picks up the DC voltages that are used. The remaining four connectors (16-pin) will plug into each of the Digital and Analog boards in the system (up to four total). This

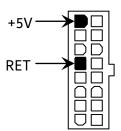


harness varies from the Special panel harness in that there are two main branches; one feeds the digital boards, the other feeds the analog boards. This harness uses Red, Blue, Yellow and Purple wiring.

 Q5 Panel - This harness distributes power and communications from the terminal blocks to the various logic boards. The harness terminates with four, 16 pin connectors, which plug into the digital and analog boards, and two, 4 pin connectors that apply DC power to the Q5 and Interface boards. This harness uses Red, Black, Yellow, Gray, White/Black and White/Red wiring.

#### LOGIC VOLTAGE (POWER) LED

Located on the Digital Board is a Power LED. This LED will be illuminated as long as the Control Power switch is ON, and the proper voltage is present at the power supply. The power supply generates the +5 Vdc voltage and passes it on through the Power-I/O harness. This LED does not indicate however that the proper voltage is necessarily present at the board, only that the voltage is enough to energize the voltage sensing circuitry. If a voltage related problem is suspected with regard to a Digital Board, the only way to actually determine this is to read the voltage on a Digital Voltage Meter (DVM). This may be accomplished by locating the white power / communications connector on the board. Notice that the Digital Board has one of these connectors on both ends of the board. The associated power / communications harness will only be plugged into one of these connectors. Take the red (positive) probe of the DVM and carefully insert the end into the "+5V" lead, and the black (negative) probe end into the "RET" (Return or Common) lead, as shown below:



Set the DVM to read DC, and set the proper range. The voltage reading must read a minimum of +5.0 Vdc. The Power-I/O harness will have an associated voltage drop at each board connection. As an example, if you are reading the voltage at the first I/O board in the daisy chain, and it reads 4.98 Vdc, you can be assured that the voltage at the subsequent connections for the remaining boards will be lower yet. The voltage will need to be corrected for proper operation of the system. The cause for a low voltage reading could be:

- The power supply may need adjustment (see the section on power supplies).
- The Power-I/O communications harness has a problem (a new harness may be needed).

- A problem may exist with one of the I/O boards (Digital or Analog).
- If the power LED is not lighted, check the cable for proper connectivity. Note: Each board provides the necessary connections to feed all signals to the following connectors. If the auxiliary Analog or Digital Board is not present then a jumper plug (see Recommended Spare Parts List) must be installed to daisy chain the signals.

The most common symptom that is exhibited by a low +5 VDC voltage to the Digital Boards is an alarm message that reads Digital Board Reset Shutdown.

#### **ACTIVE LED**

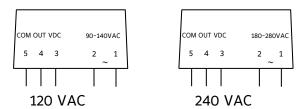
The Digital Boards have an Active LED indicator on the board that blinks when the board's software is running.

If the Active LED is not blinking, check to ensure that the EPROM is installed properly. The EPROM is located in chip slot U8, next to the power connector.

#### **DIGITAL INPUTS**

A Digital Input is the portion of the hardware that allows devices such as limit switches, relay contacts, and level switches, to interface with the Quantum™ LX. The software program within the Quantum™ LX is constantly looking at these Input channels, via communications, and based upon whether a control voltage is present or not, will provide the necessary control for an associated Output channel. For instance, if a control voltage is present on the Oil Level Sensor input, the software will determine that the Separator has sufficient oil level for the oil heaters to be energized (if the temperature of the oil is also sensed to be low. Temperature sensing will be discussed in the Analog Input section).

There are two possible varieties of Digital Input modules used on standard compressor control packages. One is for 120 Volt controls, and the other is for 240 volt controls. Both of these module styles are yellow in color. A side profile of these modules is shown below:



These Input modules, can be identified as to their operating voltage by looking at either the side, as shown above, or from the top. You will notice the module operating voltage printed on the top, and the voltage range printed on the side.

Never plug a 120 Volt Input module into a 240 Volt system, and vice-versa. Never plug an Output module into a position designated for an Input module.

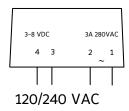


You will notice that when a module is plugged into the Digital board, there is a fuse located directly adjacent to the module. This fuse is of the pluggable variety, and must be plugged into the IN position for an Input module.

#### **DIGITAL OUTPUTS**

A Digital Output is the portion of the hardware that the Quantum  $^{\text{IM}}$  LX is to control (energize). These devices include solenoids, relay coils, and heaters to be energized, based upon the logic within the Quantum  $^{\text{IM}}$  LX software program.

There is one variety of Digital Output modules used on standard compressor control packages. This one module will handle both 120 Volt controls, and 240 volt controls. This module is black in color. A side profile of this module is shown below:



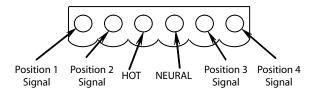
Although this Output module is labeled as 280 VAC on the top, and on the side, it can be used on both 120 and 240 volt applications.

Never plug an Input module into a position designated for an Output module.

You will notice that when a module is plugged into the Digital Board, there is a fuse located directly adjacent to the module. This fuse is of the pluggable variety, and must be plugged into the OUT position for an Output module.

#### CHECKING THE DIGITAL INPUTS AND OUTPUTS

Some problems that may be encountered involve troubleshooting the digital inputs and outputs. The Digital I/O (Input / Output) Boards have six Digital I/O (DIO) board connectors labeled P1 through P6. The Input and Output modules are wired to a DIO connector plug. Position 3 provides power and position 4 is a neutral on the DIO connectors. Positions 1, 2, 5, and 6 are signal connections, as shown below:



The Digital board's I/O modules are configured by proper module selection, AC or DC, operating voltage, input or output, and moving the fuse to the in or out position. An LED is associated with each module and displays the state of each module. A lit LED represents an Input that is High, receiving a signal or an Output that is On.

If a properly configured Digital I/O is not responding correctly, first look at the Digital Board on the Service Screen and check if the module is on. If it is not on, check if the LED on the Digital Board is also not lit. If the LED is not lit, then check the fuse. If the fuse is OK, then check the module.

#### **FUSE TESTING AND REPLACEMENT**

- 1. Power off the panel.
- 2. Open the panel door.
- 3. Remove the questionable fuse.
- Place the questionable fuse into the fuse tester at the one end of each Digital I/O Board (refer to the Digital Board drawings at the end of this section for exact fuse tester location).
- 5. Power on the panel.
- Check the LED on the tester. If the LED is lit, the fuse is OK.
- 7. Power off the panel.
- 8. If the fuse is faulty, check for external shorts on the corresponding circuit, the replace the fuse with a new plug-type fuse (refer to Recommended Spare Parts list).

#### INPUT AND OUTPUT MODULE TESTING AND REPLACEMENT

- 1. Power off the panel.
- 2. Open the panel door.
- 3. Replace the questionable module.
- 4. Power on the panel.
- If it is an Output module, check for proper panel voltage on the DIO connector plug. Check the voltage between position 4 (neutral) and the associated position to the Output module.
- 6. If it is an Input module, check if the associated LED is on when power is applied to the module.

#### TROUBLESHOOTING AN OUTPUT

- Make sure the LED associated with the Output is on when power is applied to the module.
- If the LED is not on when it should be and there is no operating condition preventing it, contact the Frick® Service Department.
- If the LED is on when it should be, check for proper panel voltage on the DIO connector plug. Check the voltage between the position 4 (neutral) and the associated position to the Output module.



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- If the voltage is OK, check for proper panel voltage between the associated position to the Output module on the DIO connector and the associated position on the terminal strip.
- If the voltage is OK, check the wiring external to the panel.
- 6. If voltage is not OK, check the fuse.
- 7. If the fuse is OK then check the module.
- 8. If the module is OK, check for proper panel voltage on the DIO connector plug between position 3 (Hot) and position 4 (neutral).

#### TROUBLESHOOTING AN INPUT

- Make sure the LED associated with the Input is on when power is applied to the module.
- If the LED is on then the fuse and Input module are good.
- If the LED is on and there is no input voltage, replace the Input module.
- If the LED is not on when power is applied, check the fuse.
- 5. If the fuse is good, replace the Input module.
- If you are receiving an Alarm or Shutdown from a digital input in which the adjacent LED indicator light is on, check the Service Screen to see if that channel is turning on and off. If so, replace the input module.

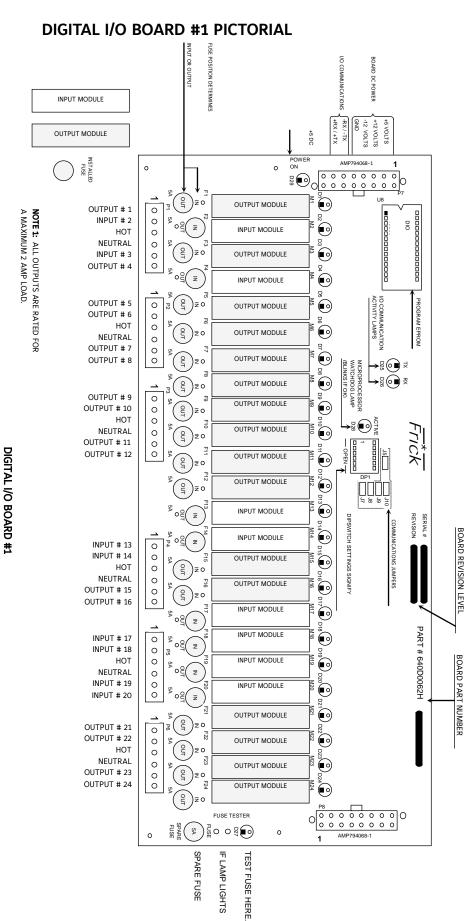
#### REPLACING A DEFECTIVE DIGITAL BOARD

The procedure to replace a Digital board is outlined below:

- 1. Shut off control power.
- Remove the old board from the machine and the new board from its packing and place both on an anti-static surface.
- Check that all jumpers, dipswitches and components are properly setup on the new board as it was on the old board (refer to the Digital Settings tables near the end of this section).
- 4. Install the modified replacement board in the panel.

After replacing or installing a Digital Board and powering on the control panel, select [Re-detect I/O Boards] from the Menu > Configuration > Communications screen. This selection provides a method to detect all connected Digital and Analog boards. If a board has been removed, a communication error shutdown will be issued until this key is selected. The *About* screen will show what was detected.





WITH PURCHASED OPTION NOTE 2: OPTIONAL MODULES INSTALLED

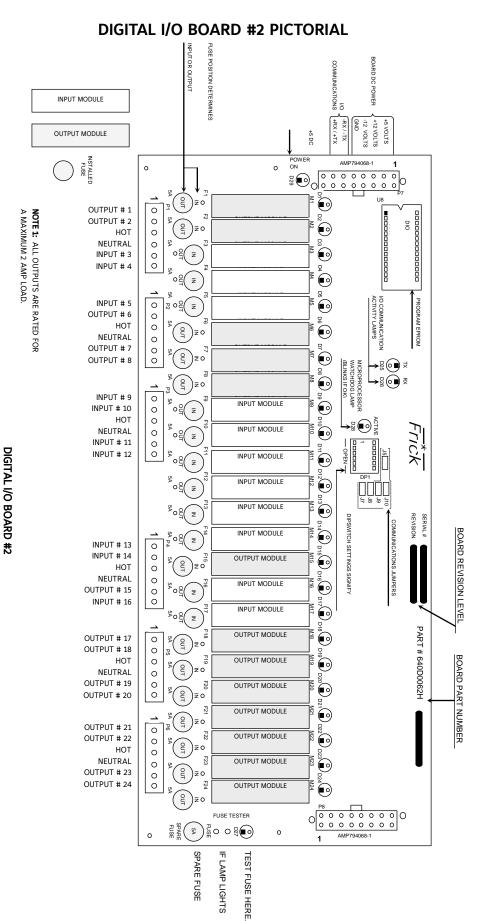
REPLACEMENT PART # 640C0024G01



NOTE 2: OPTIONAL MODULES INSTALLED

REPLACEMENT PART # 640C0024G02

WITH PURCHASED OPTION





#### **DIGITAL BOARD SETTINGS**

#### **COMMUNICATIONS SETTINGS**

The following table is to be used when configuring the Quantum™ for external communications.

J5	in	120 ohm long communications line termination.
	out*	No termination.
J7	in	RS-422/485 transmit pull-up for long communications lines.
J/	out*	No pull-up.
J8	in	RS-422 transmit pull-up for long communications lines.
76	out*	No pull-up.
J9	in	RS-422/485 receive pull-down for long communications lines.
19	out*	No pull-down.
J10	in	RS-422 receive pull-down for long communications lines.
710	out*	No pull-down.

<sup>\* =</sup> standard setting

#### **DIPSWITCH SETTINGS**

The following table is to be used to set the digital board addresses. If there is only one board installed, it should be set as board #1, if there are two boards they each need to be set according to the wiring diagrams

	SW1	SW2	SW3	SW4	SW5	SW6
Board #1	on	on	on	on	off	on
Board #2	off	on	on	on	off	on



### **SECTION 5**

### **ANALOG BOARD**





#### ANALOG BOARD

#### **OVERVIEW**

The Frick Quantum™ HD control panel is capable of reading external analog devices, such as temperature probes and pressure sensors. It uses these input signals for the purpose of monitoring and control. As an example, if an external temperature sensor began to read a higher than expected temperature in some area, the controller would sense this change, and provide the necessary output control signal to remedy the situation. Unlike a digital signal, which is typically either an on or off state, an analog signal can assume a wide variety of states, such as a temperatures probe reading a wide range of temperatures.

The method used for receiving (and sending) these signals is the analog board. The analog devices are wired directly to the board, and the on-board software/hardware converts the electrical signals received from these devices into data, which is then sent on to the Q5 Processor Board via communications.

It features twenty-four input channels, and eight output channels. Rather than using physical jumpers to configure each channel, this is done through the software. A more detailed description of the operation of this board is provided in the sections that follow.

#### ANALOG BOARD DESCRIPTION

The Analog Board is actually a small microprocessor board and is programmed to control analog outputs, or accept analog inputs, from external electrical devices. Each board has the capability of 24 independent input channels. With the Quantum™ HD Compressor Control, these I/O channels are dedicated through the software and external wiring, as to the function of each channel. The Quantum™ HD 5 controller can utilize up to two separate analog boards (Analog Board #1 and #2), depending on the selected options.

For each of the boards that are installed, they will have specific I/O (Input / Output) functions. For the operating software to distinguish board #1 from #2, each board must be properly addressed as #1 and #2 using the dipswitches on each board (see Analog Board Dipswitch Settings chart for this information).

#### **COMMUNICATIONS LED'S**

The main board is in constant communication with all Analog (and Digital) Boards. You will notice on each Digital and Analog board, that there are a pair of LED's labeled as RX and TX. These letters represent Receive (RX) and Transmit (TX). These LED's should be flashing at a high rate during normal operation. This indicates that the main board, and the Digital board that you are looking at, are properly communicating with each other.

 Refer to the JUMPER AND DIPSWITCH SETTINGS section later in this section. This table contains the dipswitch settings for addressing the Analog I/O boards. When these switches are properly set, the main board is able to serially communicate with each I/O board and provide control signals and data exchange. If these switches are not properly set, the result will be lost or failed communications, or the wrong outputs being energized, or the wrong inputs being received.

#### CONNECTIONS TO THE QUANTUM™ HD

As stated earlier, the Quantum™ HD compressor control system utilizes up to two Digital, and two Analog boards. To connect these boards together so that the Quantum™ HD can control them, they must be interconnected with a wiring harness that provides all of the necessary D.C. voltage requirements, as well as the communications capabilities.

Analog boards only require the +24Vdc voltage and the Return (or common) for logic power. The communications signals (RX & TX) are required by all boards.

A harness distributes power and communications from the terminal blocks to the various logic boards. The harness splits into two branches, with each branch ending with a 16 pin connector. The branch that supplies power and communications to the Analog board(s) utilizes gray and black wires for +24Vdc power and Common, and white/black and white/red wires for serial communications.

#### LOGIC VOLTAGE (POWER) LED'S

Located on the Analog Board are two power LED's. The first of these is D65 PG LED (+24Vdc), and will be illuminated as long as the Control Power switch is ON, and the proper +24Vdc voltage is present at Analog Board connector P3. This LED does not indicate that the proper voltage is necessarily present at the board, only that the voltage is enough to energize the voltage sensing circuitry.

If a voltage related problem is suspected with regard to a Board, the best way to actually determine this is to read the voltage on a DVM (Digital Volt Meter). This may be accomplished by locating the white power / communications connector on the board. Notice that the Analog Board has only one of these connectors. The associated power/communications harness plugs in to it. Take the red (positive) probe of the DVM and carefully insert the end into the +24Vdc lead, and the black (negative) probe end into the RET (Return or Common) lead, as shown below:

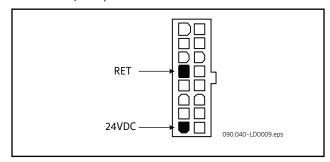


Figure. Return Lead

Set the DVM to read DC, and set the proper range. The Ideal voltage setting for the +24Vdc power is 24.2 - 24.5Vdc.

The cause for a low voltage reading could be:

- The power supply may need adjustment (see the section on power supplies).
- The Power-I/O communications harness has a problem (a new harness may be needed).



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- A problem may exist with one of the I/O boards (Digital or Analog).
- If the power LED is not lighted, check the cable for proper connectivity.

#### **ACTIVE LED**

The Analog Board has an Active LED indicator that blinks when the board's software is running.

If the Active LED is not blinking, it could be an indication that the internal program is not running. Try powering the Q5 Processor Board off, then back on to see if the Active light starts blinking. If not, a new board may be required.

#### **ANALOG INPUTS**

An Analog Input is the portion of the hardware that allows devices such as temperature sensors and pressure transducers to interface with the Quantum™ HD. The software program within the Quantum™ HD is constantly looking at these Input channels, via communications, and based upon what the voltage or current level of the channel is, will provide the necessary control for an associated action.

Analog inputs arrive at the board on connectors P4 through P10. Each of these connectors can receive two channels (for a total of twenty-four).

Refer to the following chart for a listing of possible input channel configurations.

Table. Analog Board Input Configuration Table

Channel	ICTD	0-5Vdc	0-10Vdc	0-20mA	POT (Potentiometer)	CT (Motor Current)	Accelerometer (Vibration Monitoring)	RTD (Motor Protection Only)
1	*	*	*	*				*
2	*	*	*	*				*
3	*	*	*	*				*
4	*	*	*	*				*
5	*	*	*	*				*
6	*	*	*	*				*
7	*	*	*	*				*
8	*	*	*	*				*
9	*	*	*	*				*
10	*	*	*	*				*
11	*	*	*	*				*
12	*	*	*	*				*
13	*	*	*	*				*
14	*	*	*	*	*			
15	*	*	*	*	*			
16	*	*	*	*		*		*
17	*	*	*	*			*	*
18	*	*	*	*			*	*
19	*	*	*	*			*	*
20	*	*	*	*			*	*
21	*	*	*	*			*	*
22	*	*	*	*			*	*
23	*	*	*	*			*	*
24	*	*	*	*			*	*

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#### **ANALOG OUTPUTS**

An Analog Output is the portion of the hardware that the Quantum™ HD uses to provide control. With the Quantum™ HD, this output is typically a 4-20 mA signal that is outputted to an external device. This device is usually a customer specific application, such as to simply receive a signal back from the Quantum™ HD providing the Slide Valve Position to an external application (perhaps a PLC), as an example. The output can be set as a 0-20mA signal in the calibration of the output by accessing Menu > Calibration > Output.

The 4-20mA signal can be altered if necessary to a Vdc signal by using a resistor at the input of the device being controlled. Refer to the following chart for values:

Table. Resistor Values

Original signal	Desired signal	Resistor to use
4-20mA	1-5Vdc	250 ohm, 1%, 1/4 watt
4-20mA	2-10Vdc	500 ohm, 1%, 1/2 watt
0-20mA	0-5Vdc	250 ohm, 1%, 1/4 watt
0-20mA	0-10Vdc	500 ohm, 1%, 1/2 watt

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### TROUBLESHOOTING THE ANALOG INPUTS AND OUTPUTS

Some problems that are encountered involve troubleshooting the Analog inputs and outputs. The Analog Board has twelve Analog I/O board connectors labeled P4 through P10. The external Analog devices are wired to a connector plug. Position 1 connects to the plus (+) of the external device for channel 1, position 2 connects to the signal (SIG) of the external device for channel 1 and position 3 connects to ground (GND) of the external device for channel 1. Position 4 connects to the plus (+) of the external device for channel 2, position 5 connects to the signal (SIG) of the external device for channel 2 and position 6 connects to ground (GND) of the external device for channel 2, as shown below:

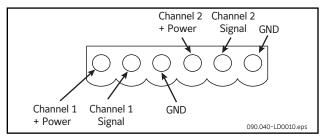


Figure. Signal Connections

Each channel is setup through software calibration for the proper transducer type and range, and each transducer must

be calibrated through the appropriate sensor calibration screen. Improper setup of either the hardware or software will result in improper operation or range.

The most common fault associated with the improper reading of the analog channels other than hardware or software setup problems fall into one of the following categories:

- · Sensor fault
- · Wiring problem
- · Improper grounding of system

An open wire, shorted or shunted wire, or faulty sensor will usually give a reading at either the minimum or maximum end of the range scale. An erratic reading or a reading that seems to float up and down is usually indicative of a grounding problem. When a single transducer or cable is shorted to earth (or system) ground, this can show up as a whole assortment of problem channels. The easiest way to find a short to earth problem is to disconnect all the sensor plugs and ohm out each plug screw terminal to earth for open (infinite) impedance. All sensors should read open to earth with the exception of the CT motor current channel. One side of the CT is grounded in the Motor Control Center (MCC). (The third pin on pressure sensors is ground.)

#### REPLACING A DEFECTIVE ANALOG BOARD

The procedure to replace an Analog board is outlined below:

- 1. Shut off control power.
- 2. Unplug all connectors from the board.
- Remove the old board from the machine and remove the new board from its packing and place both on an antistatic surface.
- Check that all jumpers and dipswitches are properly setup on the new board as it was on the old board.
- 5. Install the modified replacement board in the panel.
- 6. Plug all connectors back in.
- 7. Turn on control power.
- 8. After replacing or installing an Analog Board and powering on the control panel, the processor will start to communicate to the new board automatically. If this does not occur power down the panel and check the dipswitch settings. If correct re-power the panel.

If an I/O board is removed for any reason an I/O Comms fail message for that board will occur. It will be necessary to do a **[Redect I/O Comms]** to reset the processor memory as to which boards it is communicating to. Always check the about screen after a Redetect to be sure that all boards are accounted for.



#### PHD VIBRATION ANALYSIS

The Frick \$\text{M}\$ 32 channel analog board has the built-in capability to directly receive signals from vibration accelerometers, and motor stator RTDs (100 \$\Omega\$ platinum) which are mounted on the compressor housing and/or the motor/shaft. The purpose of these devices is to monitor compressor plus motor/bearing vibration and/or motor bearing plus motor stator temperature.

Accelerometers transmit continuous signals to the analog board. The Q5 Processor Board software monitors these signals, and can detect any variations in the frequency of the vibration. If the vibration levels increase over time, predefined setpoint limits may be exceeded, resulting in a warning from the Quantum™ HD notifying the operator of the condition. If the alarm is not addressed, a shutdown will

occur to prevent damage to the compressor. Likewise, if an RTD is used for bearings, it will measure the temperature of the motor bearings and stator, which may increase (due to lack of lubrication).

Typically, all PHD related connections will be to Analog Board # 1. However, if monitoring of both motor bearing vibration and temperature is required, the temperature sensors will be wired to Analog board #2, channels 19 and 20. Refer to the drawing at the bottom of this page for the wiring connections of the different possible configurations.

The full wiring diagram may be found later in this manual in the Quantum™ HD Drawings section. Additional information on PHD vibration monitoring and theory may be found in the PhD Vibration Monitoring System manual (E70.020-TB).

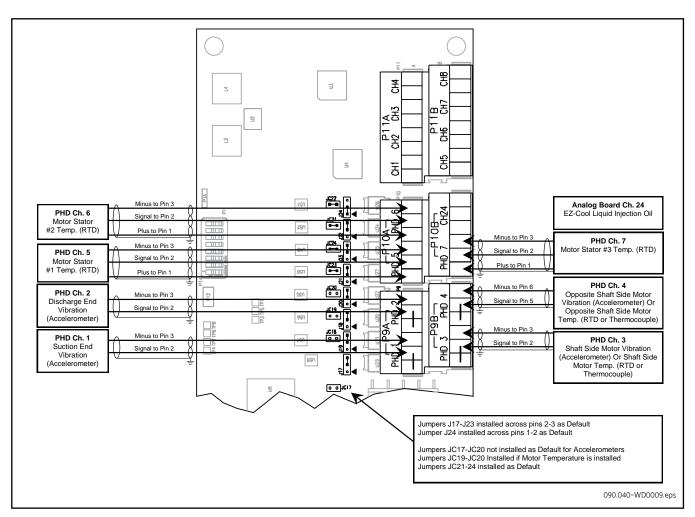


Figure. PHD Connections (Analog Board #1)



#### **CURRENT TRANSFORMER (MOTOR AMPS)**

Channel 16 of Analog Board 1 is dedicated to reading motor amps, either through the use of the on board current transformer when using a 0-5 amp CT, or from an external source. When reading motor amps directly at the P8 terminal strip

from a CT, the input signal cannot exceed 5 amps. An external DC Ma or voltage device, may be used as an alternate method of reading motor amps. Connect the wiring to connector P7B as shown in the diagram below:

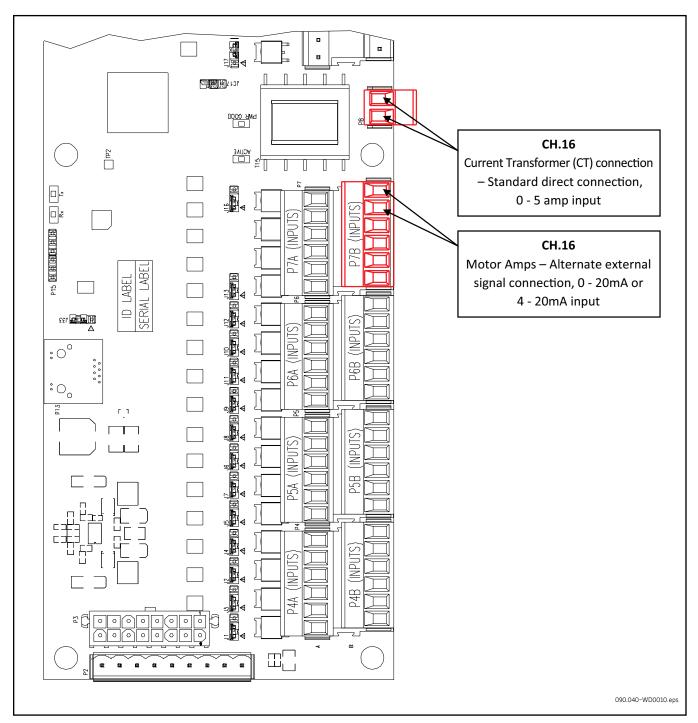


Figure. Current Transformer



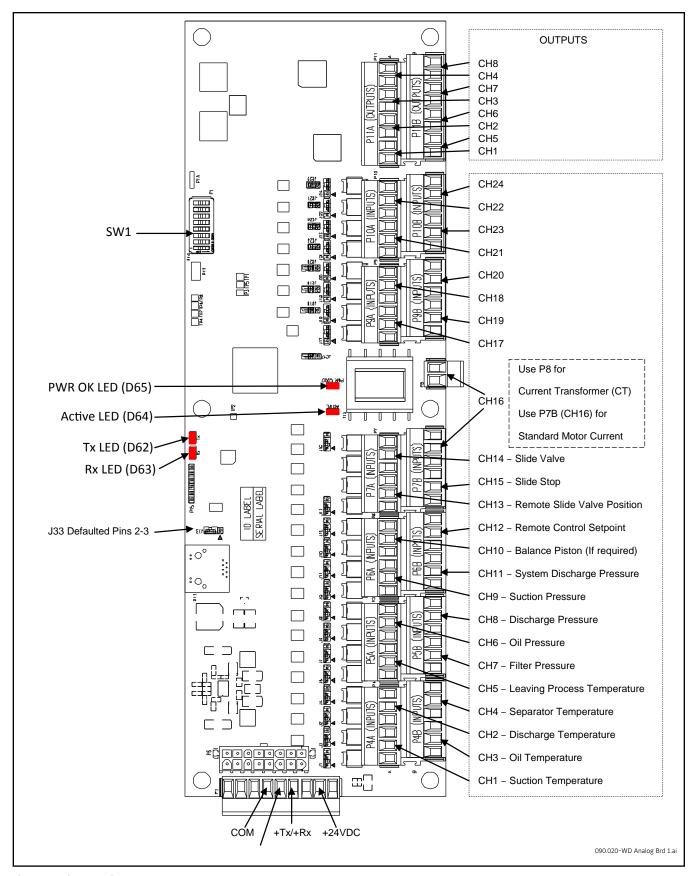


Figure. Analog Board #1



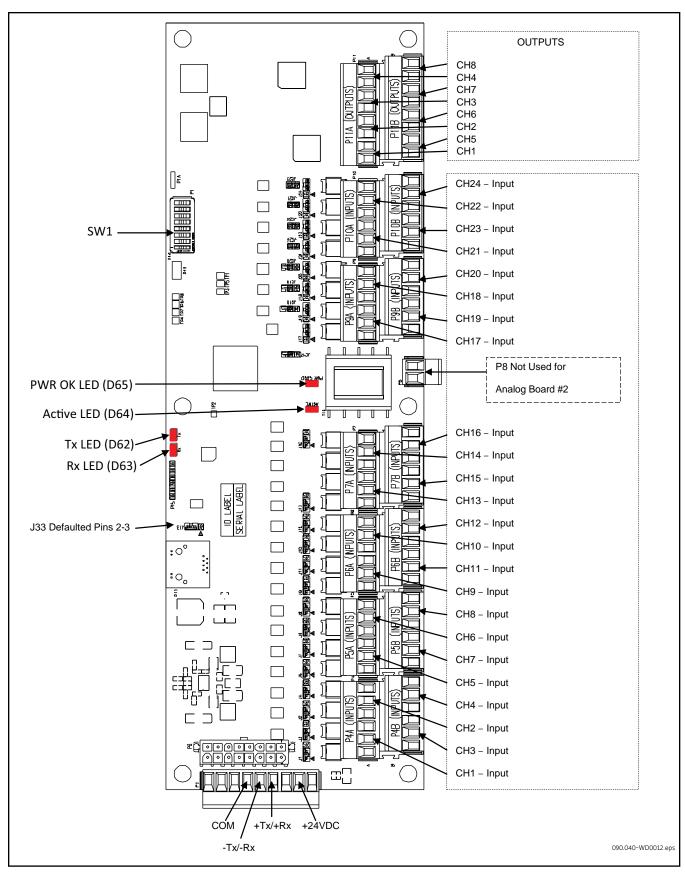


Figure. Analog Board #2



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#### ANALOG BOARD SETTINGS

#### Table. Communications

The following table is to be used when configuring the Quantum HD for external communications.

J33 Pins 1-2 120 ohm long communications line termination. Pins 2-3 \* No termination.

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#### Table. Dipswitch Settings (Used to set board address)

The following table is to be used to set the analog board addresses. If there is only one board installed, it should be set as board #1, if there are two boards they each need to be set according to the wiring diagrams.

	SW1	SW2	SW3	SW4	SW5	SW6	SW7	SW8
Board #1	Off							
Board #2	On	Off						

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#### Table. Analog Board Jumper Settings

Jumpers shown are the default jumper settings per analog board. See wiring diagrams for correct jumper settings.

	J1	J2	J3	J4	J5	J6	J7	J8	J9	J10	J11	J12
Analog Bd #1	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2
Analog Bd #2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2

	J13	J16	J17	J18	J19	J20	J21	J22	J23	J24
Analog Bd #1	1-2	1-2	2-3	2-3	2-3	2-3	2-3	2-3	2-3	2-3
Analog Bd #2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2	1-2

	JC17	JC18	JC19	JC20	JC21	JC22	JC23	JC24
Analog Bd #1	OUT	OUT	OUT	OUT	IN	IN	IN	IN
Analog Bd #2	IN							

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PINS 1-2 ARE FOR 30mA MAX SENSOR POWER (ie. ICTD, PRESSURE TRANSDUCER, PRESSURE TRANSMITTERS, LINEAR TRANSMITTERS, ANY DEVICE THAT REQUIRES 9-28VDC POWER)

PINS 2-3 ARE FOR 3mA MAX SENSOR POWER (ie. RTD'S [PT100], ACCELEROMETERS)

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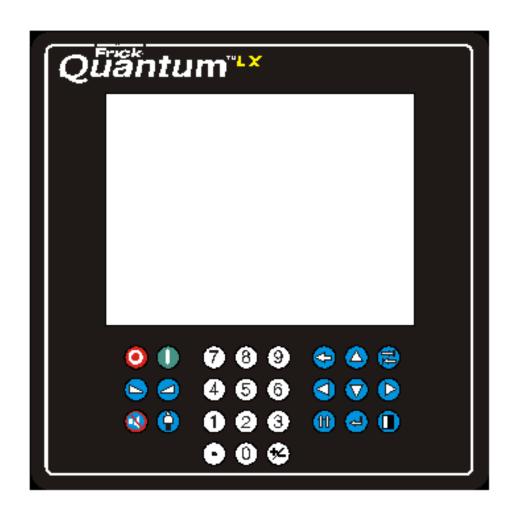
### QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



#### **NOTES**



# SECTION 6 OPERATOR INTERFACE





#### **OPERATOR INTERFACE**

#### **DESCRIPTION**

The Quantum™ LX Operator Interface actually consists of two components: A color 10-1/2" (diagonally measured) graphic display and a membrane touch keypad. The display is used to view information coming from the Quantum™ controller, while the keypad allows the user to enter information into the controller.

#### **DISPLAY ASSEMBLY**

The Display assembly consists of a 640 x 480 resolution, LCD or LED screen (which includes a fluorescent or LED backlight tube(s), an optional backlight inverter circuit board, and a wiring harness). Refer to the Parts Lists earlier in this manual for specific replacement part numbers.

**NOTE:** Before replacing a display unit, ensure that the symptom is not actually being caused by a bad fluorescent tube, inverter or harness.

#### **IDENTIFYING THE TYPE OF DISPLAY**

Various display manufacturers have been utilized over the years, and although the variations between the displays of these manufacturers is subtle, it needs to be addressed here. If a display related problem is ever encountered and factory service is contacted, they may request the type of display that is being diagnosed. This information can be found on a sticker located on the back of the display mounting plate, and should resemble the following example (the example shown is for reference only):

SHARP DISPLAY ASSEMBLY
ORDER 639C0230G01
- INCLUDES DISPLAY, MOUNTING
PLATE & DUAL BULB INVERTER

This sticker will give the part number of the display that is currently installed. Refer to the Spare Parts list at the end of this manual for applicable part numbers.

**NOTE:** In the past, CCFL style displays had been used. These displays can be identified by an inverter circuit board mounted next to the display. This board took the low voltage signal from the Q4/Q5, and stepped the voltage up to drive a fluorescent tube inside the display to illuminate the display screen. Currently, LED style displays are being used. These displays can be identified by the lack of the external inverter board as mentioned before. The voltage from the Q4/Q5 board is used to directly drive an internal LED light stick within the display to light the screen. It is important to verify the jumper settings on both the Q4 and Q5 to ensure that they are set appropriately for the type of display being used. Refer to the charts on the following page.

#### **DISPLAY REPLACEMENT**

**NOTE:** For a Q5 controller, when ordering a replacement display, please check for CPU BIOS version 1.13 and QLX software version 7.07 or newer (view the *ABOUT* screen). Contact Frick ECS for BIOS upgrade.

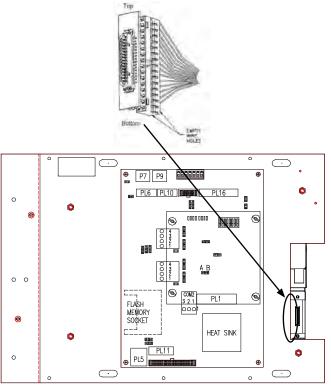
- 1. Shut off control power.
- Carefully unplug all connectors that are attached to the display. Ensure that you are familiar with the relocation of each of these connectors.
- Loosen the four hex nuts located on the display plate.
   The location of these nuts is shown on the Q4 and Q5
   Display Mounting Plate drawings.
- While supporting the display plate assembly with one hand, carefully remove the four hex nuts that were loosened in the previous step.
- 5. Once the four nuts have been removed, carefully remove the display plate. There is a section of plexiglas between the display and the clear viewing window of the keypad assembly. Ensure that this plexiglas does not come out. If it does come out, simply ensure that it is reinstalled before placing the new display in place. Also be sure not to get fingerprints on the plexiglas.
- Carefully lay the display plate down on a table or bench, with the display side up.
- 7. If you haven't already done so, remove the connector from the back of the display. There are two variations on the way the display connector is attached depending on whether the unit is a Q4 or Q5. Please refer to the notes provided later in this section as to how to properly perform the cable removal.
- Remove the four phillips head screws located near the corners of the display.
- 9. Remove the defective display.
- 10. Install the new display.
- 11. Reinstall the four phillips head screws near the four corners of the display. Do not overtighten.
- 12. Reconnect the display connector on the back of the display. Once again, refer to the two sections shown later as to the proper method to do this.
- 13. Reinstall the display plate back into position on the panel door, and loosely reinstall the four hex nuts, do not tighten yet.
- 14. Look at the front of the display from the front of the panel door. Ensure that the display looks centered in the display opening. Once centered, tighten the four hex nuts. Re-centering the display may be necessary after these steps have been completed. If this is the case, simply loosen these four nuts, and re-center the display, then retighten.
- 15. Reattach all of the connectors that were removed during step 2.
- 16. For a Q4 board, verify the jumpers (link) settings per the tables as shown later in this section. For a Q5 board, verify the Q5 board jumpers, as well as the Interface board jumpers that are shown in Section 2 of this manual.



#### **Q4 SPECIFIC INFORMATION**

The end of the display cable that plugs into the display has an adapter connector plugged into it, which adapts the display cable to the display. When unplugging the display cable from the back of the display, it is possible that the display cable connector may separate from the display adapter connector. If this occurs, refer to the following drawing to ensure proper connector orientation when plugging the display cable back into the display:

With the display connector held as shown, orient the display harness to plug onto the back pins with the 2 empty wire holes oriented down toward the bottom as shown:



#### O4 Motherboard Display Jumpers (links)

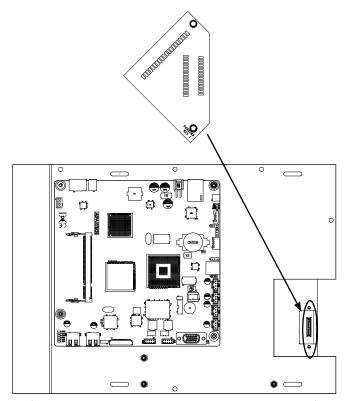
Link #	Link Pos.	Description	Frick P/N	
	Α	+5V Backlight Voltage (Not used)	N/A	
LK3	В*	+12V Backlight Voltage (All Displays)	N/A	
LK4	А	+5V LCD Supply Samsung	333Q0001180	
		+5V LCD Supply NEC	333Q0001494	
		+5V LCD Supply Sharp	333Q0001581	
		+5V LCD Supply Sharp DG61	639C0132H01	
	В*	+3.3V LCD Supply LG Philips	649C1078H01	
		+3.3V LCD Supply Sharp DG81	639C0144H01	

<sup>\*</sup> standard setting

(Refer to "Q4 Board Settings" for location of jumpers)

#### **Q5 SPECIFIC INFORMATION**

The display for the Q5 utilizes a "bat wing" adapter board that plugs into the display connector, and accepts the display harness from the Q5. This adapter board is keyed so that it cannot be plugged in wrong. The display harness is also keyed, so that its orientation is assured. To aide in accessing this "bat wing" adapter, the Interface board should be removed. A drawing of the "bat wing" adapter and its location is shown here (with Interface board removed) NOTE: Verify the setting of the JLVDS3 (shown below), especially when replacing a CCFL display, with an LED display (DG81):



(Interface board not shown in above pitorial for clarity)

#### **Q5 Motherboard Display Jumpers (links)**

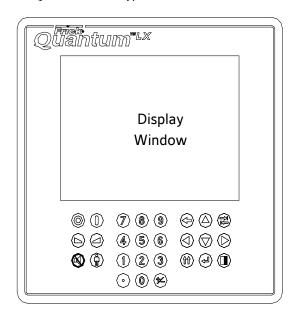
Jumper Title	Function	Jumper Setting			
CN1000 (LCD Resolution Selector)	18-bit 640x480 <b>(default)</b>	6 0 0 5 4 0 0 3 2 0 0 1	3-5 Closed & 4-6 Closed		
JLVDS2 (Backlight Level Selector)	0- 5V (default)	1	2-3 Closed		
	0 - 2.5V	1	1-2 Closed		
JLVDS3 (Backlight Control Mode)	Voltage Mode (CCFL) (default)	D□OO 1 2 3	1-2 Closed		
	PWM Mode (LED - DG81)	1 2 3	2-3 Closed		

(Refer to "Q5 Board Settings" for location of jumpers)



#### **KEYPAD**

The Quantum™ LX keypad is shown here:



The Keypad consists of two areas, the Display window and the Keypad itself. The Display window is simply a clear portion of the Keypad assembly which the Display is able to be viewed through.

#### **KEYPAD TROUBLESHOOTING**

The Keypad area consists of a series of 27 membrane switches. Depressing each switch (key) should result in an audible tactile clicking sound. To ensure that each key is actually functioning:

Q4: Visually inspect the D8 LED located on the control board. This LED will normally flash on and off at a rate of about once-per-second. Pressing a key on the keypad will interrupt this flash rate, and repeatedly depressing a key will cause the LED to flash each time a key is pressed.

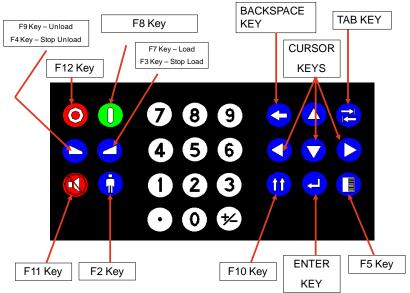
Q5: Visually inspect the D6 (Active) LED located on the Q5 Interface board. This LED will normally flash on and off at a rate of about once-per-second. Pressing a key on the keypad will interrupt this flash rate, and repeatedly depressing a key will cause the LED to flash each time a key is pressed.

If a keypad problem is suspected, or apparent, a USB capable computer keyboard (will have a USB style connector on the end of the keyboard cable) can be used as a troubleshooting aid. To by-pass the Quantum™ LX keypad, open the control panel door. **NOTE:** Always be aware of the presence of live AC voltage! Depending upon the type of Quantum™ being diagnosed, use the following instructions:

Q4: Locate the USB connection on the controller, and plug the USB end of the keyboard cable in to it.

Q5: Locate the two USB connections on the controller, and plug the USB end of the keyboard cable into either one.

The external USB based keyboard is now active and ready to use. Some of the keyboard keys are mapped so that they will duplicate the functions of the Quantum™ LX keypad. NOTE: There is a slight variation between the way a Q4 and a Q5 interpret this mapping, but these variations are minor. To navigate using the external keyboard using Q5 keyboard mapping, refer to the following pictorial:





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#### **KEYPAD REPLACEMENT**

- 1. Shut off control power.
- Unplug the defective keypad from the Quantum™ board.
- 3. The keypad is affixed to the controller door with a double-sided tape film. Start by lifting the keypad at one of the corners. Once the keypad starts to break free from the underlying tape, continue pulling. A carefully used putty knife can help to separate the keypad from the adhesive.
- 4. Once the keypad has been entirely removed, you will notice that much of the double-backed tape is remaining on the panel door. Carefully using a window scraper style razor will remove most of this tape. Be careful not to scratch the paint outside of the keypad footprint.

- Take the new keypad, and feed the flat cable through the slotted opening at the bottom of the display area.
- Remove the paper backing of the keypad to expose the double-backed tape underneath.
- 7. Carefully align the keypad on the door, ensuring that the display is centered within the window of the keypad. Once you are satisfied with the position, firmly press the keypad into place.
- 8. Plug the keypad cable back into the Quantum™.
- 9. Turn Control power back on.
- 10. Test the new keypad as described earlier.

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# QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



### **NOTES:**



## **SECTION 7**

## **SERVICE SCREENS**

		A COLUMN	A	-			
	Board 1 Channels			Board 2 Channels			
1	Off	13	On	1	Off	13	On
2	Off	14	On	2	Off	14	On
3	Off	15	on	3	Off	15	Off
4	Off	16	Off	4	Off	16	Off
5	Off	17	On	5	Off	17	On
6	Off	18	On	6	Off	18	On
7	Off	19	On	7	Off	19	On
8	off	20	On	8	Off	20	On
9	Off	21	off	9	Off	21	on
10	Off	22	On	10	Off	22	On
11	Off	23	orr	11	Off	23	Off
12	Off	24	Off	12	Off	24	Off



# SERVICE SCREENS SERVICE - Digital Board Inputs and Outputs

igite	ital I/O				a. rusa	-	
	Board 1 Channels				Board 2	Channel	\$
1	Off	13	On	1	Off	13	On
2	Off	14	On	2	Off	14	On
3	Off	15	on	3	Off	15	Off
4	Off	16	Off	4	Off	16	Off
5	Off	17	On	5	Off	17	On
6	Off	18	On	6	Off	18	On
7	Off	19	On	7	Off	19	On
8	Off	20	On	8	Off	20	On
9	Off		off	9	Off		Off
10	Off	22	On	10	Off	22	On
11	Off	23	orr	11	Off	23	Off
	Off	24	Off	12	Off	24	Off

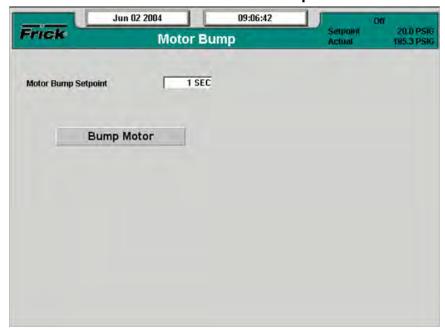
**DESCRIPTION:** This Digital Service Screen shows Digital values as ON or OFF

**SERVICE - Analog Board Inputs and Outputs** 

Anal	og Inputs		(data un	its are V	olts DC)		
	Board 1 Ch	annel	<u>s</u>		Board 2	Channels	
1	3.62	13	0.62	1	4.95	13	0.00
2	2.93	14	0.27	2	4,95	14	0.00
3	2.78	15	0.29	3	4.95	15	0.00
4	3.16	16	0.18	4	0.63	16	0.00
5	1.16	17	2.37	5	0.00	17	0.00
6	2.11	18	1.80	6	0.00	18	0.00
7	4.03	19	4.58	7	0.00	19	0.00
8	1.83	20	5.00	8	0.00	20	0.00
9	2.98	21	5.00	9	0.00	21	0.00
10	0.62	22	4.18	10	0.00	22	0.00
11	0.88	23	5.00	11	0.00	23	0.00
12	0.60	24	0.33	12	0.00	24	0.00
lnate	og Outputs		(data un	its are V	olts DC)		
	Board 1 Ch		A. Isaaca L. I		Board 2 (	Channels	
1	0.00	5	1.00	1 1	1.00	5	0.00
2	0.00	6	1.00	2	0.00	6	0.00
3	1.22	7	0.00	3	1.00	7	0.00
4	0.00	8	0.00	4	0.00	8	0.00

**DESCRIPTION:** The Analog Service Screen has been provided to view the raw data from an Analog Board. Analog values are converted from binary to show volts. The error factor is +/- .05 volts.

### **SERVICE - Motor Bump**



**DESCRIPTION:** The Motor Bump screen has been provided as a way for the service technician to verify proper motor rotation.

The following setpoint box appears on this screen:

**Motor Bump Setpoint** - A value from 0 to 15 seconds may be entered here. This value is the amount of time that the compressor motor will be energized for once the Bump Motor toggle switch has been selected.

The following toggle switch has been provided:

**Bump Motor** - When this button has been highlighted, and the **[Enter]** key pressed, the compressor motor will be energized for the period of time as set in the Motor Bump Setpoint box. It is during this motor spin time, that

the technician can view the motor shaft, for determining proper rotation. NOTE: Use extreme care in performing this operation. The compressor shaft linkage must be disconnected from the motor prior to performing this test!

For safety reasons, the **[Bump Motor]** toggle switch only appears in local mode (at the panel itself). It will not appear when viewing this panel remotely.



#### **SERVICE - Software Maintenance**



**DESCRIPTION:** The Software Maintenance screen has been provided as a way for the user to upload the operating software to their system, to save setpoints or to restore setpoints. **NOTE:** On early versions of the Quantum™ LX with the Q4 board, there was no dedicated USB port. In this instance it is recommended that a USB adapter, with a USB drive device (P/N 649A1063G01) be plugged into the PL8 USB port of the Quantum™. On more recent versions, both the Quantum™ LX Q4 and Q5 boards have dedicated USB ports, and a standard USB drive will plug directly into these ports.

#### PLEASE OBSERVE THE FOLLOWING NOTES:

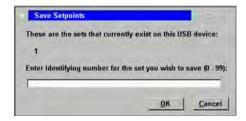
**NOTE 1:** This procedure covers updating from version 6.07 or above. Use caution when accessing this screen remotely with a web browser.

NOTE 2: Do not attempt to restore setpoints using the USB Program Upgrade Flash Drive from Quantum LX versions 6.01 through 6.06. Do not attempt to upgrade the software from Quantum LX versions 6.01 through 6.20 or that has a 64mb flash card to version 6.50 or later. A replacement Quantum™ LX Program Flash Card will be needed and the setpoints will have to be re-entered manually.

**NOTE 3:** Always ensure that the program card that you are trying to install is compatible with the controller that you are installing to. **A** Q4 LX Eurotech card will NOT boot on a Q5 LX or HD Advantech board and Q5 LX and HD cards will NOT boot on a Q4 LX Eurotech board.

**NOTE 4:** Do not attempt to restore setpoints using the USB Program Upgrade Flash Drive from Quantum LX versions 6.01 through 6.06. Do not attempt to upgrade the software from Quantum LX versions 6.01 through 6.20 or that has a 64mb flash card to version 6.50 or later. A replacement Quantum LX Program Flash Card will be needed and the setpoints will have to be re-entered manually.

While performing this procedure, one of two dialog boxes will appear. The first of these boxes indicates that a valid USB device has been detected. Any numerals that appear on the center line of this box will represent units that have already been saved (from 0 to 99). If no units have yet been saved, the center line will be blank:



If however, there is no USB device installed, or the device does not contain the operating software, the following dialog box will appear:





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Perform the following steps to prepare the Quantum™ LX for software maintenance:

- Ensure that all setpoint values have been documented as a safety precaution.
- Stop the compressor.
- With power ON, insert the USB device into the provided USB port of the Quantum™.
- Go to User Level 2. The default password is 20.
- Press the [Menu] key.
- Cursor down to Service... and press [Enter].
- Cursor down to Software Maintenance and press the [Enter] key.

The following selections have been provided:

- Save Setpoints Use this option to save all setpoints and custom text to a USB device as a form of backup:
  - Press [1] to Save Setpoints.
  - The program will read the USB device, and display a dialog box.
  - Enter a number on the keypad that corresponds to the unit number that you wish to save, and then press [Enter]. If the unit number has not been saved before, the setpoints will be saved to a file on the USB device (a progress bar will appear asking you to Please Wait... In the future, any time you try to write the setpoints to this number, you will be prompted with a message telling you that the set number already exists do you wish to overwrite it? Answer by highlighting the Yes button, and pressing [Enter] if you do indeed wish to overwrite the values. If you enter a number that does not appear on the center line, no such warning will appear.
  - After the file has been written or updated, the dialog boxes will disappear, and you can either exit, or continue with another function.
- 2) Full System Install Use this option to install the program:
  - Ensure that all setpoint values have been documented as a safety precaution.
  - Press [2] to do a Full System Install.
- 3) Restore Setpoints And Calibration Data Use this option to re-load previously saved setpoints and custom text to the Quantum™.
  - Ensure that all setpoint values have been documented as a safety precaution. Install the previ-

- ously saved setpoint USB device into the provided connection on the Quantum $^{\text{TM}}$ .
- Press [3] to Restore Setpoints and Calibration Data.
- The program will read the USB device, and display a dialog box.
- Enter a number on the keypad that corresponds to the unit number that you wish to restore, and then press [Enter].
- A progress bar will appear asking you to Please Wait...
- After the file has been written or updated, the dialog boxes will disappear, and you can either exit, or continue with another function.
- 4) Restore Setpoints Only Use this option to Restore the setpoints only (custom text that has already been changed will not be affected) for a particular unit:
  - Ensure that all setpoint values have been documented as a safety precaution. Install the previously saved setpoints USB device into the provided connection on the Quantum™.
  - Press the [4] button.
  - The program will read the USB device, and display a dialog box.
  - Enter a number on the keypad that corresponds to the unit number that you wish to restore, and then press [Enter].
  - Highlight the Yes button, and press [Enter]. The dialog box will be updated with a new message stating that Set number (0-99) has been restored.
  - Press [Enter] to return to the Software Maintenance menu.
- 5) Delete Setpoints Use this option to delete the setpoints and custom text for a particular unit:
  - Ensure that all setpoint values have been documented as a safety precaution. Install the previously saved setpoints USB device into the provided connection on the Quantum™.
  - Press the [5] button.
  - The program will read the USB device, and display a dialog box.
  - Enter a number on the keypad that corresponds to the unit number that you wish to delete, highlight the Ok button, and then press [Enter]. You



will be prompted with a new dialog box which will ask you OK to delete set number (0-99)?

- Highlight the Yes button, and press [Enter]. The dialog box will be updated with a new message stating that Set number (0-99) has been deleted!
- Press [Enter] to return to the Software Maintenance menu.
- 6) Exit Use this selection to leave this screen:
  - While leaving the USB device plugged in, press
     [5] to Exit.
  - During the reboot of the Quantum™ LX, a message will appear that says, "A System Update file has been detected on the mounted USB device.
     Do you wish to perform this update?" Select [Yes], and a System Update will be performed.
  - At the conclusion of the System Update, a message will appear that says, "The USB device can now be removed and power should be recycled."
     Follow these instructions.

## Setpoint Defaults When Performing A Quantum™ LX Software Upgrade

The term software upgrade refers to the whole procedure of Saving Setpoints, Full System Installs, and Restoring Setpoints when on the Software Maintenance screen. They get set to these default values even after a Restore Setpoints is performed, so the individual doing the upgrade must then set them manually to what they need to be if they are critical to the application.

Refer to the chart on the following page to determine the setpoints and their defaults that would be affected by a revision upgrade, find the row or rows corresponding to the Software Version that you will be upgrading to. On that row or rows you can see the setpoints and their related defaults.

Here are some examples:

- If upgrading from 6.48 to 6.51, then both the PowerPAC Flag and the Ethernet Process Enable setpoints will be changed to the defaults shown for each.
- If upgrading from 6.48 to 6.52, then the Power-PAC Flag, Ethernet Process Enable, Regulation Mode and Max Slide Valve timer setpoints will be changed to the defaults shown for each.
- If upgrading from 6.51 to 6.55 (both shown on this chart), then the PowerPAC Flag, Ethernet Process Enable would have already been changed when you had initially upgraded to 6.51 and will not change again. But now that you are upgrading to 6.55, additionally the Regulation Mode, Max Slide Valve timer, Compressor Type, Pump Type, Process Leaving Temp. Safeties, Compressor Types in the Sequencing Systems and the Compressor Start #'s in the Sequencing Systems setpoints will be changed to the defaults shown for each.

The main message here is ensure that the Setpoint Data Sheets within this manual are filled out, and that when performing any software upgrade, first save your existing setpoints to a Setpoint Saver Card for later use. After completing an upgrade to one of the versions shown here, and then restoring your original setpoints, review this chart and compare the setpoints shown against what the program sees, and make changes to these defaults as necessary.



### Q4 USB Plug-in locations Setpoint Defaults When Performing a QLX Software Upgrade

Setpoint Description	To Access	Default	Software Version
Ethernet Configuration	Menu > Configuration > Ethernet		6.11
PowerPAC Flag	Menu > Configuration > Compressor	No	6.51
Ethernet Process Enable	Menu > Configuration > Ethernet > Protocol	Disabled	6.51
Regulation Mode	Menu > Modes > Active Mode	Mode 1	6.52
Max Slide Valve Timer	Menu > Setpoints > Miscellaneous	30 (tenths of secs)	6.52
Compressor Type	Menu > Configuration > Compressor	RWF	6.55
Process Leaving Temperature Safeties	Menu > Setpoints > Miscellaneous	Disabled	6.55
Compressor Start #'s in the Sequencing Systems	Menu > Setpoints > Sequencing > System x Setup	1	6.55
Pump Type	Menu > Configuration > Compressor	Demand	6.55
Filter Differential Calculation	Menu > Configuration > Compressor	Filter – Oil	6.58
Allen Bradley Checksum Type for Comm 1, 2, & 3	Menu > Configuration > Communication	ВСС	6.58
Pump Type	Menu > Configuration > Compressor	Demand	6.59
Data Points For Trending (8 points)	Menu > System Status > Trending > Trending Setup	Suction Pressure, Discharge Pressure, Motor Cur- rent, None, None, None, None, None	6.65
Power Assist	Menu > Setpoints > Package	30 Sec.	6.82
Low (Main) Oil Inj. Pressure Shutdown Delay	Menu > Setpoints > Package	180 Sec.	6.82
Vyper Standby Time	Menu > Operating Values > Vyper > Vyper	20 Min.	6.83
EZ Cool PID Control	Menu > Setpoints > PID Setup	Always	6.83
All PID Control Points will revert to default values.	Menu > Setpoints > PID Setup > Page 1 or 2		7.00
User Defined List will revert to default values.	Menu > Operating Values > User Defined		7.00
Trending Lists will revert to default values.	Menu > System Status > Trending > Trending Setup		7.00
Motor Amps - Before restoring setpoints from any version previous to 7.06 to 7.06 or later, access the the Motor Setpoints screen and take note of the value in the box for CT Factor. After restoring setpoints, access the Motor Setpoints screen and change the CT Factor to 10, and Submit. Then change the CT Factor back to the value that you had noted earlier and Submit again.	Menu > Setpoints > Motor		7.06
The Oil Pump Type will revert to its default when doing a software upgrade. <b>NOTE:</b> When the Oil Pump type is changed, the <i>Low Compressor Oil Pressure Shutdown</i> and <i>Warning</i> setpoints will also revert to their default settings. These setpoints are rarely changed from their default values in the field.	Menu > Configuration > Compressor	Demand Pump	7.07

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# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



### Setpoint Defaults When Performing a QLX Software Upgrade (Continued)

Setpoint Description	To Access	Default	Software Version
Capacity Mode (1-4) Control Channel will revert to its default setting when doing a software upgrade. <b>NOTE:</b> When the Capacity Mode (1-4) Control Channels are changed, the associated control setpoints will reset to default values also. This would include all the Capacity Control Mode (1-4) setpoints that are enabled. Before performing the software upgrade, write down all these setpoints or verify that they are recorded in the Setpoint Data Sheets.	Menu > Configuration > Compressor  - ALSO -  Menu > Setpoints > Capacity > Mode 1 (2, 3 or 4)		7.07
Input Channel to Retransmit will revert to their default settings when doing a software upgrade.	Menu > Calibration > Analog Outputs > Re- transmitting Outputs		7.07
User Defined will revert to their default settings when doing a software upgrade.	Menu > Operating Values > User Defined		7.07
Digital Output Control Channels will revert to their default settings when doing a software upgrade. <b>NOTE:</b> When the Digital Output Control Channels are changed, the associated control setpoints will reset to default values also. This would include all the Digital Output Control Channel setpoints that are enabled. Before performing the software upgrade, write down all these setpoints or verify that they are recorded in the Setpoint Data Sheets.	Menu > Setpoints > Auxiliaries > Digital Out- puts		7.07
Trending lists will revert to their default settings when doing a software upgrade.	Menu > System Status > Trending > Trending Setup		7.07
The Maximum Discharge Pressure setpoint will revert to its default when doing a software upgrade.	Menu > Setpoints > Miscellaneous	270 PSIG	7.08
Separator Velocity Reference	Menu > Setpoints > Compressor	2%	7.08
The Compressor Type will revert to its default value.	Menu > Configuration > Compressor	RWF	7.08
The PID Control Point, Regulation Control Point, Input Channel to Retransmit, User Defined, Digital Output Control Channel, Trending lists will revert to their default settings when doing a software upgrade. <b>NOTE:</b> When the PID Control Point is changed, the associated control setpoints will reset to default values also. This would include all the PID setpoints that are enabled. Before performing the software upgrade, write down all these setpoints or verify that they are recorded in the Setpoint Data Sheets.	Menu > Setpoints > PID Setup > Page 1 or 2		7.08



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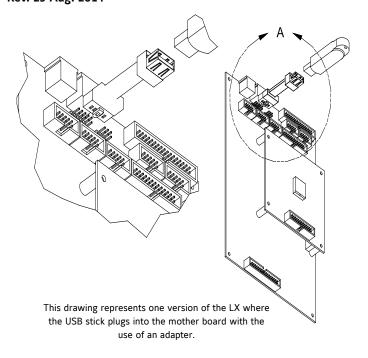
### Setpoint Defaults When Performing a QLX Software Upgrade (Continued)

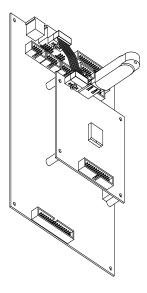
Setpoint Description	To Access	Default	Software Version
High Compressor Vibration Warning - Suction	Menu > Setpoints > PhD Monitoring	3.5 gF	7.11
High Compressor Vibration Warning - Discharge	Menu > Setpoints > PhD Monitoring	3.5 gF	7.11
High Compressor Vibration Shutdown - Suction	Menu > Setpoints > PhD Monitoring	10.0 gF	7.11
High Compressor Vibration Shutdown - Discharge	Menu > Setpoints > PhD Monitoring	10.0 gF	7.11
High Motor Vibration Warning - Shaft Side	Menu > Setpoints > PhD Monitoring	3.5 gF	7.11
High Motor Vibration Warning - Opposite Shaft Side	Menu > Setpoints > PhD Monitoring	3.5 gF	7.11
High Motor Vibration Shutdown - Shaft Side	Menu > Setpoints > PhD Monitoring	10.0 gF	7.11
High Motor Vibration Shutdown - Opposite Shaft Side	Menu > Setpoints > PhD Monitoring	10.0 gF	7.11
EZ Cool LIOC Port Multiplier	Menu > Setpoints > EZ Cool LIOC	1.0	7.11

**NOTE:** The warnings below may appear after upgrading from version 6.53 or below. This is due to a sensor input out of range, usually because the input is not used. If this is the case, you can disable this input (if it is not used) to clear the warning. In session level 3, set the "I/O Board" to "None" to disable the input.

Low Rem Capacity Sensor Warning	Menu > Calibration > Motor Miscellaneous
Low RPM Sensor Warning	Menu > Calibration > Motor Miscellaneous
Low Manifold Pressure Sensor Warning	Menu > Calibration > Pressure
Low Filter Pressure Sensor Warning	Menu > Calibration > Pressure

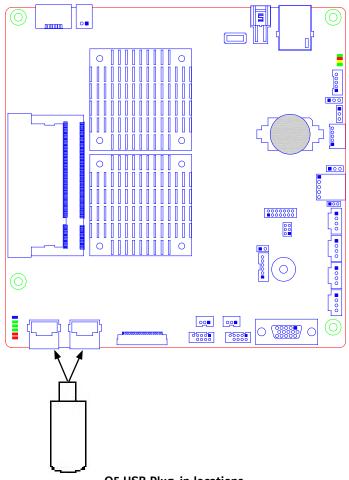






This version of the LX has a USB connector located on the daughter board, no adapter is required.

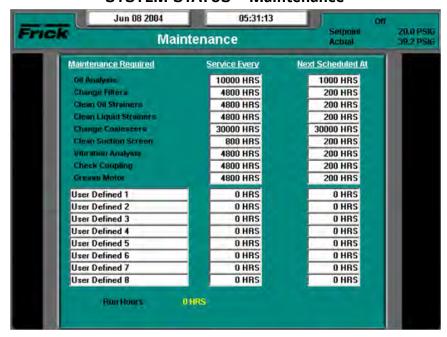
### Q4 USB Plug-in locations



Q5 USB Plug-in locations



#### SYSTEM STATUS - Maintenance



**DESCRIPTION:** This screen has been provided to aid the service technician with keeping track of system maintenance, and can be accessed from the System Status screen. From here, the service technician can view up to eight (8) user definable maintenance schedules. Each of the schedules may be custom named. This screen is based upon the Maintenance Schedule that is provided in the IOM manual for the specific compressor package. For additional information about this screen, refer to 090.020-0 (Operation Manual).

#### 11:08:05 May 02 2005 20.0 PSIG Communications Actual 21.6 PSI 0 Compressor ID Comm1 Comm2 Comm3 Status Status Status **Baud Rate Baud Rate** 38400 -19200 -**Baud Rate** 19200 💌 Data Bits Data Bits Date Bits 8 -8 + 8 -Stop Bits Stop Bits Stop Bits 1 💌 1 . 1 🕶 None -None -None \* Yes • No 💌 Frick • None . None . I/O Comms Use Map File No + Download MapFile.txt From Quantum LX Redetect IO Comms Upload MapFile.txt To Quantum LX

#### **CONFIGURATION - Communications**

**DESCRIPTION:** The purpose of this screen being shown here is to indicate where the [Redetect I/O Comms] key is located. This selection provides a method to detect all connected Analog and Digital boards. For additional information about this screen, refer to 090.020-CS (Communications Manual)

The following are some of the things that can occur that would cause an I/O board to stop communicating with the Quantum<sup>™</sup>, and would require that you Redetect I/O Comms:

- A board has been removed, and power was turned on with the board removed. You would need to replace the board, re-power, and then Detect I/O Boards.
- A board has failed in such a way that it cannot properly communicate with the Quantum™ LX.
- A failure with the communications cable which is plugged into the end of each board

If any of these things occur, a communications error shutdown will be issued until this key is selected. You should always view the About screen to see what has been detected.



# MISCELLANEOUS SCREENS About



**DESCRIPTION:** The About screen shows any Analog and Digital boards that have been detected. If a board has lost communications, a shutdown will be issued. All outputs are turned off on a Digital Board that has lost communications. All inputs will get set to their minimum value range on an Analog Board that has lost communications. A loss of communications to an analog board should result in sensor fault shutdown messages that are associated with the sensors on that board. If the RX LED on the I/O board is blinking but the board was not detected on the About screen, or an I/O Comm failure occurs, check the address of the board.



### **SECTION 8**

### **TROUBLESHOOTING**

#### TROUBLESHOOTING A PROBLEM THAT APPEARS UNEXPLAINABLE

When there is a problem that makes no sense due to unexplainable things happening, check the following:

- 1. Is the panel powered by an isolating power source such as a control transformer in the starter panel?
- Verify that the panel is not powered from a lighting or utility panel.
- It is important to know if the unit ever worked properly.
- 4. If the unit used to work properly, try to determine when the problem first showed up.
- 3. It is important to know if the problem occurs randomly, frequently, or all the time.
- 4. Check what the temperature is in the engine room and at the panel. Is it very hot or very cold?
  - Make sure that the motor is not blowing exhaust air on the control panel.
- 5. If it just started to act up, then check if there was recently a severe lightning storm, fire, flood, or a plant accident. If any of the following conditions are possible, then check for it:
  - Has any water, refrigerant, or oil leaked into the panel or conduit?
  - Does the conduit with the Slide Valve or Slide Stop contain liquid?
  - Does the Slide Stop potentiometer cover contain any liquid?
- If it just started to act up, then check if anything was recently changed in the system (i.e. software or hardware.)
- If it just started to act up, then check if any service was recently done to the compressor or its electrical system?
- If there is communication wiring connecting the panel to another panel or device, then check the following:

- If the Quantum<sup>M</sup> is unexplainably shutting down, try disconnecting the communications cable to see if the problem goes away.
- Check if the communications cable shields are tied to machine ground at only one location. For a PLC or Opto22 based system, the shield should normally be tied only at the PLC or Opto22 panel.
- Check that you are using the Frick recommended communications cable.
- 9. If this is an older plant, has the plant wiring been brought up to code?
- 10. Do you have power wiring mixed with control, sensor or communications wiring?
- 11. Check that the starter panel is grounded to the plant transformer. There are usually four wires: 3 for the 3 phases and 1 for plant ground.
- Check that the motor is grounded to the starter panel. There are usually four wires: 3 for the phases and 1 for ground.
- Ensure that one side of the motor current transformer is grounded in the motor starter panel. The wire to the control panel terminal #2 is usually the only one grounded.
- 14. Check that the pressure transducers are properly grounded. The two types of transducers you may have are as follows: an older type has an 8 to 10 inch 3-conductor pigtail coming out of the transducer. This type will have the attaching cable's shield cut off and insulated at the transducer end. The shield is then tied to a panel ground terminal in the panel. The newer type has the cable as an integral part of the housing and has the shield crimped to the case at the transducer end. This type of transducer has the cable's shield cut off and insulated in the control panel.
- 15. Check that the temperature transducers are properly grounded. The temperature probes usually have two short wires coming out of the sensor, and are tied to a shielded cable at the thermal well head. The shield is insulated at the temperature probe and grounded



at the panel end.

- 16. Check if one of the temperature probes has a signal wire shorted to machine ground. To do this, first pull the orange plug from the micro board and then use a DVM and check each white wire to machine ground and each black wire to machine ground.
- 17. Check that all inductive loads (i.e. coils, solenoids, or relays, etc.) connected to the I/O output modules have surge suppressers across them, preferably at the devices. Most of the larger factory installed inductive loads should have surge suppressors as well.
- 18. If the compressor control settings unexplainably change modes, it may be a noise problem affecting the keypad's input circuit. Check if it works OK with the keypad cable disconnected. If it works OK, then check the grounding as described above. If the grounding is OK then replace the keypad.

- 19. Make sure that you have a continuous ground back to the power source. The ground connection must be aluminum or copper. A conduit ground will not work. Do not drive a ground stake at the compressor since extraneous currents will be attracted to the compressor.
- 22. Make sure that there is no AC wiring lying next to the printed circuit board.
- Unexplainable compressor auxiliary failures are usually indicative of noise due to wiring problems (i.e. incorrect earth grounds, mixed power and control wiring, unsuppressed coils, etc)
- 24. If the compressor is unexplainably shutting down, check if the machine shares control transformer power with something else. Make sure each compressor has its own isolation transformer in the motor control center off the three-phase bus with the secondary properly grounded.



# TROUBLESHOOTING CHART FOR FRICK® QUANTUM™ LX CONTROL PANEL (REFER TO WIRING DIAGRAMS)

SYMPTOM	PROBABLE CAUSES and CORRECTIONS
DISPLAY IS INOPERATIVE	Check for power at the panel. See if any of the diagnostic lamps on the Main Board are blinking or any lights are blinking on the other boards. If no lights are blinking, make sure the control power switch is switched on. If there are still no lights, then check the circuit breaker (2CB). If the breaker is not tripped, check for power into 2CB. If there is no power, check the external power being supplied. If power from 2CB, check power supply for input AC and output DC level.  Shut off power to the panel and first confirm that the display connector is firmly seated. This is a delicate connection and care should be used to reconnect it. Confirm that the connectors at both ends of the backlight inverter (optional) are properly connected. Confirm that the display harness is connected properly on the main board.  Check the display with a flashlight. If characters are visible, the display is good, but the backlight tube is not on.
OIL PUMP DOES NOT START	The LED (D3) for Output 3 (MOD 3) of Digital I/O Board #1 should be on when Manually On is selected for the oil pump mode. If the pump does not start when the LED is on, check for the proper panel voltage between position 4 and 5 on the P1 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F3) and if the fuse is OK, check the output module (MOD 3). If the voltage was OK, check for the proper voltage between position 5 on the P1 DIO connector and position 8 on the terminal strip. If voltage is OK, check for the proper voltage between position 8 and 2 on the terminal strip. If the voltage is OK, check at the oil pump starter. If all of this is OK, then check the Service Screen to see if channel 3 is ON.  The Oil Pump #1 Auxiliary Contact switches voltage to Input 4 (MOD 4) of Digital I/O Board #1 when the auxiliary contacts are closed. If the input does not turn on, check if the LED (D4) is lit when it should be. If it isn't, check the fuse (F4) and if the fuse is OK, check the input module (MOD 4). Check the voltage between positions 4 and 6 of the P1 DIO connector. If the LED is ON, check channel 4 on the DIO of Digital Board 1, at the Service Screen.
OIL PUMP IS RUNNING BUT THE COMPRESSOR DOES NOT START	For compressor models with a slide valve: Verify that the Slide Valve has unloaded to or below the Highest Slide Valve Position to allow starting the compressor setpoint. If the slide valve has not unloaded, troubleshoot the hydraulic system. Compressor will not start until the Slide Valve is unloaded. Output 1 (MOD 1) of Digital I/O Board #1 controls the motor starter. If the motor does not start when the LED (D1) is on, check for the proper panel voltage between position 4 and 1 on the P1 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F1) and if the fuse is OK, check the output module (MOD 1). If the voltage was OK, check for the proper voltage between position 1 on the P1 DIO connector and position 18 on the terminal strip. If voltage is OK, check for the proper voltage between position 18 and 2 on the terminal strip. If the voltage is OK, check the interposing relay (By others).

# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



SYMPTOM	PROBABLE CAUSES and CORRECTIONS
COMPRESSOR AUXILIARY SHUTDOWN	Output 1 controls the Compressor Start Relay (By others). If the compressor does not start and the LED (D1) for Output 1 (MOD 1) is on, check for the proper panel voltage between position 4 and 1 on the P1 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F1) and if the fuse is OK, check the output module (MOD 1). If the voltage was OK, check for the proper voltage between position 1 on the P1 DIO connector and position 18 on the terminal strip. If voltage is OK, check for the proper voltage between position 18 and 2 on the terminal strip. If the voltage is OK, check the interposing relay (By others).  The Compressor Starter Auxiliary Contacts turn on Input 2 (MOD 2) of Digital I/O Board #1 when they are closed. These contacts are located on the Compressor Starter. If the input does not turn on check if the LED (D2) is lit when it should be. If it isn't, check the fuse (F2) and if the fuse is OK, check the input module (MOD 2). Check the voltage between positions 2 and 4 of the P1 DIO connector.
OIL HEATERS DO NOT OPERATE	The oil heaters should operate only when the compressor is NOT running and the oil separator temperature is not greater than or equal to the Oil Heater Off Above setpoint, and that the Oil Level input is made.  If the oil heaters do not work and the LED (D21) for Output 21 (MOD 21) is on, check for the proper panel voltage between position 4 and 1 on the P6 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F21) and if the fuse is OK, check the output module (MOD 21). If the voltage was OK, check for the proper voltage between position 1 on the P6 DIO connector and position 9 on the terminal strip. If voltage is OK, check for the proper voltage between position 9 and 2 on the terminal strip. If the voltage is OK, check the Oil Heater Relay (1CR).  If the problem hasn't been located, check the circuit breaker (1CB). If the breaker is not tripped, check power into 1CB. If OK check between Wires 103 and 106. If the Oil Heater Relay (1CR) is closed, check for proper panel voltage between wires 106 and 102. If OK, check the Oil Heater.
COMPRESSOR DOES NOT LOAD and/or UNLOAD* (Compressor that steps on Capacity)	For a 4-Step compressor, verify that the 50% SV (Solenoid Valve) is energized BEFORE the 75% SV is energized. For a 3-Step compressor, verify that 75% SV is energized BEFORE the 100% SV. Feel hydraulic tubing to the compressor unloading pistons. If tubing is hot, inspect the unloader pistons for worn parts or improper seating. Check that the hydraulic valves feeding the solenoid valve as well as those feeding the unloader pistons are open.  Confirm that hydraulic tubing and wiring is properly connected.  Check the solenoid valve coil to see if it has been damaged.  NOTE: Verify that the proper capacity control setpoint has been programmed.
COMPRESSOR WILL ONLY PAR- TIALLY LOAD* (Compressor that steps on Capacity)	With the first SV (solenoid valve) properly energized, verify that the second SV energizes and then check the third SV if there is one for this compressor model.  Check that the hydraulic valves feeding the first SV as well as those feeding the compressor unloading pistons are open.  Inspect the compressor unloading ports for worn or improperly seated parts.



SYMPTOM	PROBABLE CAUSES and CORRECTIONS
SLIDE VALVE DOES NOT LOAD	Verify that the Slide Valve is in the AUTO mode and that capacity control is calling for load and/or unload. Output 5 (MOD 5) controls the Slide Valve Load Solenoid. If LED (D5) for Output 5 (MOD 5) is on, check for the proper panel voltage between position 4 and 1 on the P2 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F5) and if the fuse is OK, check the output module (MOD 5). If the voltage was OK, check for the proper voltage between position 1 on the P2 DI O connector and position 17 on the terminal strip. If voltage is OK, check for the proper voltage between position 17 and 2 on the terminal strip. If the voltage is OK, check the solenoid valve.
and/or UNLOAD*	Output 6 (MOD 6) controls the Slide Valve Unload Solenoid. If the LED (D1) for Output 6 (MOD 6) is on, check for the proper panel voltage between position 4 and 2 on the P2 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F6) and if the fuse is OK, check the output module (MOD 6). If the voltage was OK, check for the proper voltage between position 2 on the P2 DIO connector and position 16 on the terminal strip. If voltage is OK, check for the proper voltage between position 16 and 2 on the terminal strip. If the voltage is OK, check the solenoid valve.  NOTE: Verify that the proper capacity control setpoint has been programmed.
SLIDE STOP DOES NOT IN- CREASE and/or DECREASE*	Verify that the Slide Stop is in the AUTO mode and that the VI Ratio is calling for a VI increase or decrease.  Output 7 (MOD 7) controls Slide Stop Increase Solenoid. If the LED (D7) for Output 7 (MOD 7) is on, check for the proper panel voltage between position 4 and 5 on the P2 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F7) and if the fuse is OK, check the output module (MOD 7). If the voltage was OK, check for the proper voltage between position 5 on the P2 DIO connector and position 15 on the terminal strip. If voltage is OK, check for the proper voltage between position 15 and 2 on the terminal strip. If the voltage is OK, check the solenoid valve.  Output 8 (MOD 8) controls the Slide Stop Decrease Solenoid. If the LED (D8) for Output 8 (MOD 8) is on, check for the proper panel voltage between position 4 and 6 on the P2 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F8) and if the fuse is OK, check the output module (MOD 8). If the voltage was OK check for the proper voltage between position 14 on the terminal strip. If voltage is OK, check the solenoid valve.
LIQUID INJECTION SOLENOID DOES NOT ENERGIZE* (Liquid Injection Refrigerant Cutout - LICO)	Verify that the Liquid Injection TXV is modulating properly and not feeding excessive liquid to LICO the compressor. This solenoid SHOULD be de-energized when the compressor is off. This solenoid should be energized if the Discharge temperature equals or exceeds the "Discharge Temperature On At" setpoint for the delay time.  Output 9 controls the Liquid Injection Solenoid. If the LED (D9) for Output 9 (MOD 9) is on, check for the proper panel voltage between position 4 and 1 on the P3 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F9) and if the fuse is OK, check the output module (MOD 9). If the voltage was OK, check for the proper voltage between position 1 on the P3 DIO connector and position 13 on the terminal strip. If voltage is OK, check for the proper voltage between position 13 and 2 on the terminal strip. If the voltage is OK, check the solenoid.

# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



SYMPTOM	PROBABLE CAUSES and CORRECTIONS
HI VI LIQUID INJECTION PORT SOLENOID DOES NOT ENER- GIZE*	Output 10 controls the Hi Vi Liquid Injection Port solenoid. If the LED (D10) for Output 10 (MOD 10) is on, check for the proper panel voltage between position 4 and 2 on the P3 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F10) and if the fuse is OK, check the output module (MOD 10). If the voltage was OK check for the proper voltage between position 2 on the P3 DIO connector and position 12 on the terminal strip. If voltage is OK, check for the proper voltage between position 12 and 2 on the terminal strip. If the voltage is OK, check the solenoid. NOTE: For an RXB and a GST compressor model, this output should only be on when the Vi is at 5.0.
ECONOMIZER*	Output 11 (MOD 11) controls the Economizer Solenoid Valve. If the LED (D11) for Output 11 (MOD 11) is on, check for the proper panel voltage between position 4 and 5 on the P3 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F11) and if the fuse is OK, check the output module (MOD 11). If the voltage was OK, check for the proper voltage between position 5 on the P3 DIO connector and position 11 on the terminal strip. If voltage is OK, check for the proper voltage between position 11 and 2 on the terminal strip. If the voltage is OK, check the solenoid.  NOTE: The economizer output will be on based on the Economizer On/Off setpoint.
ALARM CIRCUIT DOES NOT ENERGIZE	Output 22 (MOD 22) controls the Alarm Circuit. The Alarm should turn on only when there is a warning or shutdown. If the Alarm does not occur when these conditions are found and the LED (D22) for Output 22 (MOD 22) is off, check for the proper panel voltage between position 4 and 2 on the P6 DIO connector on Digital I/O board #1. If the proper voltage is not found, check the fuse (F22) and if the fuse is OK, check the output module (MOD 22). If the voltage was OK, check for the proper voltage between position 2 on the P6 DIO connector and position 21 on the terminal strip.
CONTROL PANEL DOES NOT RESPOND TO REMOTE CONTROL SIGNALS	Digital I/O Board 2, Inputs 3 through 5 can be used to operate the compressor from a remote location. NOTE: Check the Operating display to verify that the compressor and the Slide Valve are in REMOTE I/O.  If the Input 3 (MOD 3) does not turn on, check if the LED (D3) is lit when it should be. If it isn't, check the fuse (F3) and if the fuse is OK, check the input module (MOD 3).  If the Input 4 (MOD 4) does not turn on, check if the LED (D4) is lit when it should be. If it isn't, check the fuse (F4) and if the fuse is OK, check the input module (MOD 4).  If the Input 5 (MOD 5) does not turn on, check if the LED (D5) is lit when it should be. If it isn't, check the fuse (F5) and if the fuse is OK, check the input module (MOD 5).
MOTOR LOAD CONTROL(FORCED UNLOAD) OCCURS AT HIGH MOTOR AMPS	The current transformer is used to convert the AC motor amps to a DC voltage signal for the microprocessor. If the %FLA reading from the Operating display is incorrect, contact the Frick® Service Department.



SYMPTOM	PROBABLE CAUSES and CORRECTIONS
PRESSURES ON THE OPERAT- ING SCREEN DO NOT APPEAR CORRECT	1st – Check the range and sensor type in the setup of the panel. If this is correct:  2nd – Open transducers that can be isolated from the system and opened to atmosphere, these would be Suction, Oil and Filter (if present). Set these transducers to Og pressure or atmospheric pressure if your readings are in absolute. Close the transducers from atmosphere and reopen to the system/package. After these pressures have settled down, set the Discharge to match the Oil pressure.  NOTE: Reference the Pressure Transducer Conversion Data Chart.
COMPRESSOR WITH SLIDE VALVE DOES NOT AUTOMATI- CALLY LOAD OR UNLOAD*	Verify that the Slide Valve Mode [AUTO] key has been pressed and AUTO appears under Slide Valve Mode on the Level 1 Operating Status screen.  If the problem persists, see the Troubleshooting section SLIDE VALVE DOES NOT LOAD and/or UNLOAD.
COMPRESSOR THAT STEPS ON CAPACITY DOES NOT AUTO- MATICALLY LOAD OR UNLOAD*	Verify that the Capacity Mode <b>[AUTO]</b> key has been pressed and AUTO appears under Capacity Mode on the Level 1 Operating Status screen.  If the problem persists, see the Troubleshooting section COMPRESSOR DOES NOT LOAD and/or UNLOAD.

<sup>\*</sup> If applicable

	COMPRESS	OR MODEL D	FFERENCES			
FRICK®	RWB, SC	RXB*	RXF	RDB 3-Step	RDB 4-Step	Other
GRAM	GSV, YLC	GST*		GSB 3-Step		Other
Slide Valve Reading	0-100%	0-100%	0-100%	N/A	N/A	0-100%
Slide Valve Setpoints	Yes	Yes	Yes	N/A	N/A	Yes
Slide Valve Calibration	Yes	Yes	Yes	N/A	N/A	Yes
Capacity Reading	N/A	N/A	N/A	50, 75, 100	25, 50, 75, 100	N/A
Slide Stop Reading	2.2 - 5.0	2.2, 3.5, 5.0	2.2, 3.5, 5.0	N/A	N/A	N/A
Slide Stop Calibration	N/A	N/A	N/A	N/A	N/A	N/A
DX Circuit Option	Yes	Yes	Yes	N/A	N/A	Yes
Hot Gas Bypass/SV Setpoints Option	Yes	Yes	Yes	N/A	N/A	Yes
Remote Slide Valve Position Option	Yes	Yes	Yes	N/A	N/A	Yes
Sequence by Comp. Sequencing	Yes	Yes	Yes	N/A	N/A	Yes
Forced unload Inhibit load delay setpoint	N/A	N/A	N/A	Yes	Yes	N/A

<sup>\*</sup> Or other variable VI N/A = Not Applicable

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# QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



### **NOTES:**



### **SECTION 9**

### **SETPOINT DATA SHEETS**

**Quantum™ LX Version 7.0x (06/02/2011)** 

In most cases, updating software on the Quantum™ LX panel will require clearing the current setpoints and data stored in the nonvolatile memory on the main board. It is suggested that the operator first record all control setpoints prior to performing program upgrades. The setpoint data sheets are useful for recording this information.

The sheets that appear on the following pages are in the order that they are accessed from the Quantum™ LX Menu.

### **OPERATING VALUES - Used Defined**

Description	Value	Default	User Defined Selections
Status 1		Capacity Slide Position	
Status 2		Capacity Slide Position	
Status 3		Capacity Slide Position	Capacity Slide Position
Status 4		Capacity Slide Position	Volume Slide Position Suction Pressure
Status 5		Capacity Slide Position	Discharge Pressure Compressor Oil Pressure Main Oil Injection Pressure
Status 6		Capacity Slide Position	Economizer Pressure Filter Pressure
Status 7		Capacity Slide Position	Intermediate Pressure Balance Piston Pressure
Status 8		Capacity Slide Position	System Discharge Pressure Suction Temperature
Status 9		Enable User Defined Status 9	Discharge Temperature Compressor Oil Temperature
Status 10		Enable User Defined Status 10	Oil Separator Temperature Process/Brine Temperature Leaving
Status 11		Enable User Defined Status 11	Process/Brine Temperature Entering Motor Current
Status 12		Enable User Defined Status 12	RPM Auxiliary Analog 1-10
Status 1		Enable User Defined Status 13	EZ Cool Feedback % Auxiliary Analog 12-20
Status 14		Enable User Defined Status 14	Manifold Pressure Compressor Vibration – Suction
Status 15		Enable User Defined Status 15	Compressor Vibration – Discharge Motor Vibration – Shaft Side
Status 16		Enable User Defined Status 16	Motor Vibration – Opposite Shaft Side Motor Temp. – Shaft Side
Status 17		Enable User Defined Status 17	Motor Temp. – Opposite Shaft Side  Motor Stator # 1-3
Status 18		Enable User Defined Status 18	None
Status 19		Enable User Defined Status 19	
Status 20		Enable User Defined Status 20	



### **MODE SETUP**

Description	Value	Default	Mode Selections
Compressor		Manual	Manual Automatic Remote Comm Remote I/O Remote Seq Man. Browser
Capacity		Manual	Manual Automatic Remote Comm Remote I/O Remote 4-20 Remote Seq Man. Browser
Volume		Manual	Manual Automatic
Active Mode		Mode 1	Mode 1 Mode 2 Mode 3 Mode 4
<b>Pump</b> (only appears if a Pump type has been selected in Configuration)		Automatic	Manual Automatic
<b>Dual Pump Sequence</b> (only appears if Dual Pumps has been enabled in Configuration)		Pump 1 Lead	Pump 1 Lead Pump 2 Lead



## **SYSTEM STATUS - Trending Setup**

Control	Description	Value	Default	Trending Selections / Ranges
	Channel 1		Suction Pressure	Capacity Slide Position Volume Slide Position Suction Pressure Discharge Pressure
	Channel 2		Discharge Pressure	Compressor Oil Pressure Main Oil Injection Pressure Economizer Pressure Filter Pressure
	Channel 3		Motor Current	Intermediate Pressure Balance Piston Pressure System Discharge Pressure
	Channel 4		Enable Real Time Trend Channel 4	Suction Temperature Discharge Temperature Compressor Oil Temperature Oil Separator Temperature
Real Time	Channel 5		Enable Real Time Trend Channel 5	Process/Brine Temperature Leaving Process/Brine Temperature Entering Motor Current RPM
	Channel 6		Enable Real Time Trend Channel 6	Auxiliary Analog 1-10 EZ Cool Feedback % Auxiliary Analog 12-20 Manifold Pressure
	Channel 7		Enable Real Time Trend Channel 7	Compressor Vibration – Suction Compressor Vibration – Discharge Motor Vibration – Shaft Side Motor Vibration – Opposite Shaft Side
	Channel 8		Enable Real Time Trend Channel 8	Motor Temp. – Shaft Side Motor Temp. – Opposite Shaft Side Motor Stator # 1–3 None
İ	Recording Interval		10	1.0 to 86400.0 SEC
	Disable Real Time Trending		No	No Yes
	Channel 1		Suction Pressure	Capacity Slide Position Volume Slide Position Suction Pressure Discharge Pressure
	Channel 2		Discharge Pressure	Compressor Oil Pressure Main Oil Injection Pressure Economizer Pressure Filter Pressure
	Channel 3		Motor Current	Intermediate Pressure Balance Piston Pressure System Discharge Pressure Suction Temperature
	Channel 4		Enable History Trend Channel 4	Discharge Temperature Compressor Oil Temperature Oil Separator Temperature
History	Channel 5		Enable History Trend Channel 5	Process/Brine Temperature Leaving Process/Brine Temperature Entering Motor Current RPM
	Channel 6		Enable History Trend Channel 6	Auxiliary Analog 1-10 EZ Cool Feedback % Auxiliary Analog 12-20 Manifold Pressure
	Channel 7		Enable History Trend Channel 7	Compressor Vibration – Suction Compressor Vibration – Discharge Motor Vibration – Shaft Side Motor Vibration – Opposite Shaft Side
	Channel 8		Enable History Trend Channel 8	Motor Temp. – Shaft Side Motor Temp. – Opposite Shaft Side Motor Stator # 1-3 None
	Recording Interval		1	1.0 to 60.0 MIN
	Disable History Trending		No	No Yes

# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



### **SYSTEM STATUS - Maintenance**

Maintenance Required	Servi	e Every	Next Scheduled At		Dongo	Units	
Maintenance Required	Default	User Setting	Default	User Setting	Range	Units	
Oil Analysis	10000		1000		0.0 to 100000.0	HRS	
Change Filter	4800		200		0.0 to 100000.0	HRS	
Clean Oil Strainers	4800		200		0.0 to 100000.0	HRS	
Clean Liquid Strainers	4800		200		0.0 to 100000.0	HRS	
Change Coalescers	30000		30000		0.0 to 100000.0	HRS	
Clean Suction Screen	800		200		0.0 to 100000.0	HRS	
Vibration Analysis	4800		200		0.0 to 100000.0	HRS	
Check Coupling	4800		200		0.0 to 100000.0	HRS	
Grease Motor	1200		200		0.0 to 100000.0	HRS	
User Defined 1	0		0		0.0 to 100000.0	HRS	
User Defined 2	0		0		0.0 to 100000.0	HRS	
User Defined 3	0		0		0.0 to 100000.0	HRS	
User Defined 4	0		0		0.0 to 100000.0	HRS	
User Defined 5	0		0		0.0 to 100000.0	HRS	
User Defined 6	0		0		0.0 to 100000.0	HRS	
User Defined 7	0		0		0.0 to 100000.0	HRS	
User Defined 8	0		0		0.0 to 100000.0	HRS	



### **SETPOINTS - Capacity Control Setpoints (Mode 1)**

Control		Description		Value	Default	Range	Units	
		Setpoint			20.0	0.0 to 185.3	Pressure	PSIG
		Proportional	High		15.0	0.0 to 100.0		
		Band	Low		15.0	0.0 to 100.0	Dragatira	חכוכ
		Dand Band	High		0.5	0.0 to 20.0	(Magnitude)	PSIG
		Dead Band	Low		0.5	0.0 to 20.0		
	Capacity Control	Cyala Tima	High		,	0.0 to 60.0	Time	SEC
	Control	Cycle Time	Low		3	0.0 to 60.0	Time	SEC
		VFD Prop.	High		15.0	0.0 to 100.0	Drossuro	DCIC
		Band	Low		15.0	0.0 to 100.0	Pressure	PSIG
SUCTION		VFD Integ.	High		30	0.0 to 999.0	Time	SEC
PRESSURE		Time	Low		30	0.0 to 999.0	Tillle	SEC
MODE		Start	Pressure		25.0	0.0 to 185.3	Pressure	PSIG
	Autocycle	Start	Delay		1	0.0 to 60	Time	MIN
	Autocycle	Stop	Pressure		15.0	0.0 to 185.3	Pressure	PSIG
		Зтор	Delay		1	0.0 to 60	Time	MIN
		Load Inhibit			10.0			
		Force Unload			5.0	0.0 to 185.3	Pressure	PSIG
	Mode	Warning	Setpoint		2.0			
	Safeties	warring	Delay		2	0.0 to 60.0	Time	SEC
		Shutdown	Setpoint		0.0	0.0 to 185.3	Pressure	PSIG
		Silutuowii	Delay		3	0.0 to 60.0	Time	SEC
		Setpoint						
		Proportional	High		ļ			
	Capacity	Band	Low					
	Capacity	Dead Band	High		ļ			
			Low					
		Cycle Time	High		ļ			
		cycle Time	Low					
		Start	Temp.		ļ			
	Autocycle		Delay					
	7.0000,0.0	Stop	Temp.		ļ			
ALL OTHER			Delay					
MODES		Load Inhibit						
		Force Unload						
	Mode	Warning	Setpoint		ļ			
	Safeties	8	Delay		ļ			
		Shutdown	Setpoint					
		Delay			ļ			
		Load Inhibit			ļ			
		Force Unload						
	Low	Warning	Setpoint		<b> </b>			
	Suction	Shutdown Se	Delay					
			Setpoint					
			Delay					



### **SETPOINTS - Capacity Control Setpoints (Mode 2)**

Control		Description		Value	Default	Range	Units	
		Setpoint			20.0	0.0 to 185.3	Pressure	PSIG
		Proportional Band	High Low		15.0	0.0 to 100.0	Pressure	DCIC
		Dead Band	High Low		0.5	0.0 to 20.0	(Magnitude)	PSIG
	Capacity Control	Cycle Time	High Low		3	0.0 to 60.0	Time	SEC
		VFD Prop. Band	High Low		15.0	0.0 to 100.0	Pressure	PSIG
SUCTION PRESSURE		VFD Integ. Time	High Low		30	0.0 to 999.0	Time	SEC
MODE		Start	Pressure		25.0	0.0 to 185.3	Pressure	PSIG
	Autocycle	Start	Delay		1	0.0 to 60	Time	MIN
	Autocycle	Stop	Pressure		15.0	0.0 to 185.3	Pressure	PSIG
			Delay		1	0.0 to 60	Time	MIN
	Loa	Load Inhibit			10.0			
	Mode	Force Unload			5.0	0.0 to 185.3	Pressure	PSIG
			Setpoint		2.0	1		
	Safeties		Delay		2	0.0 to 60.0	Time	SEC
		GL	Setpoint		0.0	0.0 to 185.3	Pressure	PSIG
		Shutdown	Delay	Ì	3	0.0 to 60.0	Time	SEC
		Setpoint		i	İ			
		Proportional	High		1			
		Band	Low					
	Capacity		High		1			
	Control	Dead Band	Low		ĺ			
			High		i			
		Cycle Time	Low		İ			
		1	Temp.	1				
		Start	Delay					
	Autocycle		Temp.					
		Stop	Delay		f			
ALL OTHER		Load Inhibit	Delay					
MODES		Force Unload			ł			
	Mode	Torce officad	Setpoint					
	Safeties	Warning	Delay		ł			
	Saleties		Setpoint		ł			
		Shutdown						
		Load Inhibit	Delay					
		Force Unload		1	1			
	1.	Force Unioad	Catnalist		ł			
	Low Suction	Warning	Setpoint					
	Suction		Delay		-			
		■ Shutdown ⊢	Setpoint		-			
		Delay						



### **SETPOINTS - Capacity Control Setpoints (Mode 3)**

Control		Description		Value	Default	Range	Units		
		Setpoint			20.0	0.0 to 185.3	Pressure	PSIG	
		Proportional Band	High Low		15.0	0.0 to 100.0	Pressure	DCIC	
		Dead Band	High Low		0.5	0.0 to 20.0	(Magnitude)	PSIG	
	Capacity Control	Cycle Time	High Low		3	0.0 to 60.0	Time	SEC	
		VFD Prop. Band	High Low		15.0	0.0 to 100.0	Pressure	PSIG	
SUCTION PRESSURE		VFD Integ. Time	High Low		30	0.0 to 999.0	Time	SEC	
MODE		Start	Pressure		25.0	0.0 to 185.3	Pressure	PSIG	
	Autocyclo	Start	Delay		1	0.0 to 60	Time	MIN	
	Autocycle	Char	Pressure		15.0	0.0 to 185.3	Pressure	PSIG	
	Ī	Stop	Delay		1	0.0 to 60	Time	MIN	
		Load Inhibit			10.0				
		Force Unload				5.0	0.0 to 185.3	Pressure	PSIG
Mode		Setpoint		2.0	1				
	Safeties	Warning	Delay		2	0.0 to 60.0	Time	SEC	
			Setpoint		0.0	0.0 to 185.3	Pressure	PSIG	
		Shutdown	Delay		3	0.0 to 60.0	Time	SEC	
		Setpoint							
		Proportional	High		1				
		Band	Low		1				
	Capacity	acity	High		1				
	Control		Low		1				
			High		1				
		Cycle Time	Low		1				
		1	<del> </del>		1				
		Start	Temp.		-				
	Autocycle		Delay		-				
		Stop	Temp.		4				
ALL OTHER			Delay		4				
MODES		Load Inhibit			4				
		Force Unload			4				
	Mode Safeties	Warning	Setpoint Delay		<u> </u>				
		Shutdown	Setpoint		]				
	Silutuowii	Delay		]					
		Load Inhibit							
		Force Unload							
	Low	Marnina	Setpoint						
	Suction	Warning	Delay		1				
		Shutdown	Setpoint		1				
			Delay		1				



### **SETPOINTS - Capacity Control Setpoints (Mode 4)**

Control		Description		Value	Default	Range	Units	
		Setp	oint		20.0	0.0 to 185.3	Pressure	PSIG
		Proportional Band	High Low		15.0	0.0 to 100.0	Pressure	PSIG
	Canaa'i	Dead Band	High Low		0.5	0.0 to 20.0	(Magnitude)	P310
	Capacity Control	Cycle Time	High Low		3	0.0 to 60.0	Time	SEC
		VFD Prop. Band	High Low		15.0	0.0 to 100.0	Pressure	PSIG
SUCTION PRESSURE		VFD Integ. Time	High Low		30	0.0 to 999.0	Time	SEC
MODE		Start	Pressure		25.0	0.0 to 185.3	Pressure	PSIG
	Autocycle	Start	Delay		1	0.0 to 60	Time	MIN
	ridiocycle	Stop	Pressure		15.0	0.0 to 185.3	Pressure	PSIG
		·	Delay		1	0.0 to 60	Time	MIN
	Mode Safeties Warr	Load I			10.0	<u>[</u>		
		Force l			5.0	0.0 to 185.3	Pressure	PSIG
		Warning	Setpoint		2.0		<u> </u>	
		8	Delay		2	0.0 to 60.0	Time	SEC
		Shutdown	Setpoint		0.0	0.0 to 185.3	Pressure	PSIG
			Delay		3	0.0 to 60.0	Time	SEC
		Setpoint						
		Proportional	High					
	Capacity	Band	Low					
	Control	Dead Band	High					
			Low					
		Cycle Time	High					
			Low					
		Start	Temp.					
	Autocycle		Delay					
		Stop	Temp.					
ALL OTHER		Load I	Delay					
MODES		Force l						
	Mode	Torce	Setpoint					
	Safeties	Warning	Delay					
	Sarctics		Setpoint					
		Shutdown	Delay					
		Load I						
		Force l						
	Low		Setpoint					
	Suction	• Warning •	Delay					
		Shutdown	Setpoint					
			Delay					
		I	Delay					



## SETPOINTS - Sequencing (System 1 Setup)

Control	Description	Value	Default	Range	Uni	ts
	Sequencing		Disabled	Disabled / Enabled	Non	ie
System 1	Setpoint		32.0	Same as the range of the	Control inp	ut
Setup	Minimum Run Time		20	0.0 to 300.0	Time	MIN
	High Stage System Link		None	None / System 2 / System 3	Non	ie
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	] ,,,,,	_
1	Compressor Mode		Manual	All Available Modes	Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	None	_
2	Compressor Mode		Manual			ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		1
	Start #		1	0.0 to 8.0		
3	Compressor Mode		Manual		Non	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0	•	
-	Start #		1	0.0 to 8.0	İ	
4	Compressor Mode		Manual		Nor	ie
<b>I</b>	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0	İ	•
	Start #		1	0.0 to 8.0	i	
5	Compressor Mode		Manual		Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0	İ	•
	Start #		1	0.0 to 8.0	Ī	
6	Compressor Mode		Manual		Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0	İ	•
	Start #		1	0.0 to 8.0	Ī	
7	Compressor Mode		Manual		Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		1
	Start #		1	0.0 to 8.0		
8	Compressor Mode		Manual		- None	
	Capacity Mode		Manual	All Available Modes		
_	Minimum Capacity		0.0	0.0 to 100.0	Percent	%



### **SETPOINTS - Sequencing (System 2 Setup)**

Control	Description	Value	Default	Range	Uni	ts
	Sequencing		Disabled	Disabled / Enabled	Nor	ne
System 2	Setpoint		32.0	Same as the range of the	Control in	out
Setup	Minimum Run Time		20	0.0 to 300.0	Time	MIN
	High Stage System Link		None	None / System 1 / System 3	Nor	ne
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	]	
1	Compressor Mode		Manual	All Available Modes	None	
	Capacity Mode		Manual	All Available Wodes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	Nor	
2	Compressor Mode		Manual			ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	1	_
3	Compressor Mode		Manual	All Assellable Mades	Nor	ne
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	None	
4	Compressor Mode		Manual	All A citable Made	Nor	ne
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	Ì ,,	
5	Compressor Mode		Manual	All Assellable Mades	Nor	ne
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	]	
6	Compressor Mode		Manual	All Assellable Mades	Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0		
7	Compressor Mode		Manual	All Available Mades	Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	] Man	
8	Compressor Mode		Manual	All Aveilable Madaa	None	
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%



## **SETPOINTS - Sequencing (System 3 Setup)**

Control	Description	Value	Default	Range	Uni	ts
	Sequencing		Disabled	Disabled / Enabled	Nor	ne
System 3	Setpoint		32.0	Same as the range of the	Control inp	out
Setup	Minimum Run Time		20	0.0 to 300.0	Time	MIN
	High Stage System Link		None	None / System 1 / System 2	Nor	ne
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	] ,,,,,	
1	Compressor Mode		Manual	· All Available Modes	Nor	ie
	Capacity Mode		Manual	All Available Wodes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID	Sequencing ID 0 0.0 to 255.0		0.0 to 255.0		
	Start #		1	0.0 to 8.0	] ,,,,,	
2	Compressor Mode		Manual	· All Available Modes	Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	l	
- I-	Compressor Mode		Manual	All Assellable Mades	Nor	ıe
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
4	Start #		1	0.0 to 8.0	Ī ,,	
	Compressor Mode		Manual	All Assellable Mades	Nor	ıe
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	1 .	
5	Compressor Mode		Manual	All Available Mades	Nor	ıe
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	] ,,	
6	Compressor Mode		Manual	· All Available Modes	Nor	ie
	Capacity Mode		Manual	All Available Wodes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	] ,,,,,	_
7	Compressor Mode		Manual	All Available Mades	Nor	ie
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%
	Sequencing ID		0	0.0 to 255.0		
	Start #		1	0.0 to 8.0	,	
8	Compressor Mode		Manual	All Available Mada-	None	
	Capacity Mode		Manual	All Available Modes		
	Minimum Capacity		0.0	0.0 to 100.0	Percent	%

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### **SETPOINTS - Sequencing Control**

Description	Value	Default	Range	Units	
Average Capacity For Start		90.0	0.0 to 100.0		
Full Load Capacity Position		98.0	0.0 to 100.0	Percent	%
Minimum Capacity Dead Band		1.0	0.0 to 20.0		
Start Failure Reset Delay		12.0	0.0 to 600.0	Time	MIN
Slide Valve Failure Safety		Disabled	Disabled	None	
			Enabled		
Full Load Drive Speed (only with Vyper drive)		98.0	0.0 to 100.0	Percent	%



### **SETPOINTS - Compressor Safeties Setpoints**

Control		Description		Default	Range	Unit	:s
	Load Inhibit			212.0			
High Discharge Temp.	Force Unload	d		212.0	32.0 to 250.0	Temp.	F
	Warning	Setpoint		205.0			
		Delay		5	0. to 60.0	Time	SEC
	Shutdown	Setpoint		212.0	32.0 to 250.0	Temp.	F SEC
Misc.	Starting Diff	Delay Proce Polow		5	0.0 to 60.0	Time	
IVIISC.	Dual Mode	f. Press. Below 50.0 0.0 to 380.0  Enabled/Disabled Disabled None		None	Pressure PSIG		
	Dual Mode	Enabled/Disabled Modes 1 & 3		190.0	None	INOII	e I
	Load Inhibit	Modes 2 & 4		190.0			
	Force	Modes 1 & 3		200.0	0.0 to 270.0	Pres- sure	PSIG
	Unload	Modes 2 & 4		200.0	0.0 to 27 0.0		
High	omodu	Modes 1 & 3		220.0			
Discharge		Delay		2	0.0 to 5.0	Time	SEC
Pressure	Warning	Modes 2 & 4		220.0	0.0 to 270.0	Pressure	PSIG
		Delay		2	0.0 to 5.0	Time	SEC
		Modes 1 & 3		270.0	0.0 to 270.0	Pressure	PSIG
	Shutdown	Delay		2	0.0 to 5.0	Time	SEC
	Shutdown	Modes 2 & 4		225.0	0.0 to 270.0	Pressure	PSIG
		Delay		2	0.0 to 5.0	Time	SEC
		To Permit Starting		10	0.0 to 100.0	Percent	%
		od Before Permitting Cap. Increase		0	0.0 to 999.0	Time	SEC
		Stopping Period for Capacity Unload		30	0.0 to 300.0		
		Automatic Mode Min. Capacity		10	0.0 to 100.0	Percent	%
Misc.	Capacity Unload Assist			Disabled	None	Non	
Willoc.	Capacity Unload Assist Rate			2.0	1.0 to 5.0	Percent	%
		elocity Reference		0.00	0.0 to 100.0	Non	e
	Compression Ratio			4.00	1.0 to 30.0		
	Liquid	Warning		10.0	0.0 to 90.0	Temp.	F
	Slugging Shutdown			20.0			
	Load Inhibit			105.3	0.0 += 200.0	Pres-	PSIG
High	Force Unload	Setpoint		115.3 125.3	0.0 to 200.0	sure	P31G
Suction	Warning	Delay		2	0.0 to 60.0	Time	SEC
Pressure		Setpoint		135.3	0.0 to 200.0	Pressure	-
	Shutdown	Delay		2	0.0 to 60.0	Time	SEC
	Enabled / Dis			Disabled	None	Non	
	On when above			90.0		i	
	Off when below			85.0	0.0 to 100.0	Percent	%
	Override: Dis		15.0	0.0 to 100.0	Pressure	PSIG	
Econo-	Port Value			1.60	0.0 to 5.0		
mizer	Pressure Input				Disabled/	Non	۵
				Disabled	Fixed Press. Setpoint/	14011	C
					Econo. Analog Value	D	
	Fixed Pressure Setpoint			12.2 Hg	0.0 to 185.3	Pressure (Positive)	PSIG
	Enabled / Disabled			Disabled	None	None	
Balance Piston	On		90	0.0 to 100.0	Percent	%	
	Off			85	0.0 to 100.0	rercent	/0
	Ignore Delay			5	0.0 to 60.0	Time	MIN
Misc.	Fail Delay			2 Disabled			
	Oil Log Main Oil	Enabled / Disabled		Disabled	None	Non	
		Delay On When Is Above		30 150.0	0.0 to 300.0	Time	SEC F
	Injection	Discharge Temp. For		5	32.0 to 212.0 0.0 to 300.0	Temp. Time	SEC
				5 Enabled	Enabled/Disabled	Non	
	Oil Pump Unload Assist			Lilabled	Eliabled/Disabled	NON	<del>-</del>



### **SETPOINTS - Package Safeties**

Control		Description	Value	Default	Range Units			
Low Oil Separator Temp.	Warning	Setpoint		55.0	49.0 to 100.0	Temp.	F	
	vvarriing	Delay		5	0.0 to 60.0	Time	SEC	
	Shutdown	Setpoint		49.0	49.0 to 100.0	Temp.	F	
	Silutuowii	Delay		5	0.0 to 60.0	Time	SEC	
Low Comp. Oil Temp.	Warning	Setpoint		55.0	49.0 to 100.0	Temp.	F	
		Delay		5	0.0 to 60.0	Time	SEC	
	Shutdown	Setpoint		49.0	49.0 to 100.0	Temp.	F	
		Delay		5	0.0 to 60.0	Time	SEC	
High Comp. Oil	Warning	Setpoint		158.0	100.0 to 250.0	Temp.	F	
		Delay		5	0.0 to 60.0	Time	SEC	
Temp.	Chutdown	Setpoint		167.0	100.0 to 250.0	Temp.	F	
remp.	Shutdown	Delay		5	0.0 to 60.0	Time	SEC	
	10/	Setpoint		25.0	0.0 to 45.0	Pressure	PSIG	
Low	Warning	Delay		600	0.0 to 600.0	Time	SEC	
Comp. Oil Pressure	61	Setpoint		30.0	0.0 to 45.0	Pressure	PSIG	
Pressure	Shutdown	Delay		900	0.0 to 600.0	Time	SEC	
	Warning	Setpoint		25.0	0.0 to 50.0	Pressure (Differential)	PSIG	
High	Ŭ	Delay		10	0.0 to 60.0	Time	MIN	
Filter Pressure	Shutdown	Setpoint		30.0	0.0 to 50.0	Pressure (Differential)	PSIG	
		Delay		15	0.0 to 60.0	Time	MIN	
Maria	Enabled / Disab	oled		Disabled	None			
Main Oil	Shutdown	Setpoint		15.0	5.0 to 50.0	Pressure	PSIG	
Injection		Delay		180	0.0 to 1000.0	Time	SEC	
	Oil Heater Off	Above		120.0	100.0 to 150.0	Temp.	F	
	High Level Shutdown Delay			5	0.0 to 60.0			
Misc.	Low Oil Level Delay			30	0.0 to 30.0	Time	SEC	
	Oil Pump Lube Time Before Starting			0	0.0 to 60.0	] Tillie		
	Dual Pump Transition Time			10	0.0 to 00.0			
	Enabled / Disabled			Disabled	None			
Pull Down	Capacity Position			5.0	0.0 to 100.0	Percent	%	
	Amount of Time			60	0.0 to 900.0	Time	SEC	
Pump	Enabled / Disab			Disabled	None			
Down	On When	Setpoint		14.1	0.0 to 185.3	Pressure	PSIG	
	Suction Above	Delay		5	0.0 to 60.0	Time	MIN	
	#1 Action				Disabled			
DX Circuit	#2 Action			Disabled	DX Circuit On With Compressor DX Circuit On By Capacity Position			
	DX Circuit 1	Off When Below		85.0	0.0 to 100.0			
		On When Above		90.0	0.0 to 100.0	Percent	0/	
		Off When Below		85.0	0.0 to 100.0		%	
	DX Circuit 2	On When Above		90.0	0.0 to 100.0			
	Enabled / Disabled			Disabled		Vone		
Liquid	On When	Setpoint	122.0 10		100.0 to 180.0	Temp.	F	
Injection	Above	Delay		5	0.0 to 60.0	Time	SEC	
,	Dual Port Transition		<del>                                     </del>	4.2	0.0 to 5.0	None		
							0,	
Misc.	Hot Gas Bypass	j	-	0.0	0.0 to 100.0	Percent	%	
	Power Assist			30	0.0 to 60.0	Time	SEC	



## SETPOINTS - Motor (Engine/DBS/Motor/Turbine/Vyper)

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	D	escription	Value	Default	Range	Unit	ts
	Motor Amps			100.0	0.0 to 3000.0	Current	AMPS
	Volts			480.0	0.0 to 9999.0		
Name Plate	Service Facto	or		1.15	0.0 to 2.0	Nom	
Name Plate	Horse Power			100.0	0.0 to 3000.0	- None	
	CT Factor			100.0	0.0 to 3000.0		
	Recycle Delay	У		20	20.0 to 255.0	Time	MIN
	Load Inhibit			100.0			AMPS
	Force Unload			105.0	0.0 to 3000.0	Current	
High Motor	Warning	Setpoint		110.0			
Amps	vvarriing	Delay		5	0.0 to 60.0	Time	SEC
	Shutdown	Setpoint		115.0	0.0 to 3000.0	Current	AMPS
		Delay		5	0.0 to 60.0	Time	SEC
	Shutdown	Setpoint		25.0	0.0 to 750.0	Current	AMPS
		Delay		30	0.0 to 60.0	Time	SEC
Low Motor Amps	Confirmed Ru	Confirmed Running Motor Amps		20.0	0.0 to 750.0	Current	AMPS
7	Starting Moto	or Amps Ignore Period		5	0.0 to 30.0	Time	SEC
	Read Motor A	Amps From		DBS	DBS or CT	Non	ie
	Locked Rotor	Current		*	300.0 to 600.0	Percent	%
	Stall Time			*	1.0 to 60.0	Time	SEC
	Jam Current	Level		*	100.0 to 600.0	Percent	%
Motor	Jam Run Dela	ау		*	0.0 to 60.0	Time	SEC
Starter (See DBS	Service Facto	or		*	75.0 to 125.0	Percent	%
Manual)	Current	Warning Level		*	2.0 to 25.0	reiteilt	/0
	Unbalance	Warning Delay		*	0.0 to 240.0	Time	SEC
		Warning Level		*	* 22.0 to 500.0	O Tomp	F
	KID lellip.	Trip Level		•	32.0 to 500.0	Temp.	「

<sup>\*</sup> These values are returned from the DBS unit via communications

This Setpoint table continues on the next page.



## SETPOINTS - Motor (Engine/DBS/Motor/Turbine/Vyper)

#### -CONTINUED -

	Descri	ption		Value	Default	Range	Unit	:s
	Confirmed R	unning			450.0	0.0 to 750.0	RPN	Л
	Starting Max	kimum Delay			5	0.0 to 60.0	Time	MIN
	Idle Speed				0.0	0.0 to 100.0	Percent	%
	Cool Down F	Period Before	e Stopping		0	0.0 to 999.0	Time	SEC
		10/	Setpoint		1900	0.0 to 4000	RPN	//
	LISER DDM	Warning	Delay		1	0.0 to 5.0	Time	SEC
Engine /	High RPM	Claust al accord	Setpoint		2000	0.0 to 4000.0	RPM	RPM
Turbine		Shutdown	Delay		1	0.0 to 5.0	Time	SEC
		Load Inhibi	t		1100			
		Force Unlo	ad		1075	0.0 to 3000.0	Speed	RPM
	Lave DDM	14/2	Setpoint		700			
	Low RPM	Warning	Delay		30	0.0 to 180.0	Time	SEC
		Chutdown	Setpoint		600	0.0 to 3000	Speed	RPM
		Shutdown	Delay		30	0.0 to 180.0	Time	SEC
		Load Inhibi	t		5.9 Hg			
	High Manifold Pressure	Force Unlo	ad		5.1 Hg	0.0 to 31.0	Pressure	PSIG
Fueine		Warning	Setpoint		4.1 Hg			
Engine		vvarriing	Delay		3	0.0 to 6.0	Time	SEC
		Shutdown	Setpoint		3.1 Hg	0.0 to 31.0	Pressure	PSIG
		Silataoviii	Delay		3	0.0 to 60.0	Time	SEC
	Drive Output  Rate of Increase		Maximum		100.0	20.0 to 100.0		
			Minimum		50.0	20.0 to 100.0	Percent	%
			Setpoint		2.0	0.1 to 25.0		
Engine /	Rate of filtre	ease	Delay		1.0	0.0 to 30.0	Time	SEC
Turbine /	Pata of Docr		Setpoint		2.0	0.1 to 25.0	Percent	%
VFD / Vyper	Rate of Decr	ease	Delay		1.0	0.0 to 30.0	Time	SEC
	When the S.	V. loads to			95.0			
	The Drive Sp	peed will rea	ch		50.0	20.0 to 100.0	Percent	%
	Variable Spe	ed Minimum	S.V. Position		25.0			
	Bottom							
	Тор							
	Bottom							
	Тор							
Skip Frequency	Bottom				0.0	0.0 to 100.0	Percent	%
Bands	Тор				0.0	0.0 to 100.0	Percent	70
	Bottom							
	Тор							
	Bottom							
	Тор							



#### **SETPOINTS - Capacity Position**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Description	Value	Default	Range	Units	
Maximum Capacity Position		100.0	0.0 to 100.0	None	
Minimum Capacity Position		0.0	0.0 to 100.0	None	

## **SETPOINTS - Condenser Digital Control**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Desc	ription	Value	Default	Range	Units	
	Condenser Co	ontrol Setpoint		30 Hg	0.0 to 485.3	Pressure	e
	Module A					Maria	
	Module B			0	0 to 4		
	Module C				0 to 4	None	
	Module D						
Condenser Digital Control	Step Up	Deadband		0.0	0.0 to 20.0	Pressure (Magnitude)	PSIG
Setpoints		Delay		0	0.0 to 60.0	Time	SEC
	Step Down	Deadband		0.0	0.0 to 20.0	Pressure (Magnitude)	PSIG
		Delay		0	0.0 to 60.0	Time	SEC
	High Pressure	Override		200.0	0 to 1000.0	Pressure	PSIG
		Delay		0	0.0 to 300.0	Time	SEC

### **SETPOINTS - Condenser Analog Control**

Control	Description	Value	Default	Range	Unit	s
	Condenser Control Setpoint		30.0 Hg	0.0 to 485.3	Pressure	PSIG
	Analog Output A		Disabled	Disabled or	Non	•
Condenser	Analog Output B		Disabled	Enabled	None	
Analog Control	Proportional Band		5.0	0.0 to 100.0	Pressure	PSIG
Setpoints	Integration Time		30	0.0 to 999.0	Time	SEC
	High Limit		100.0	0.0 to 100.0	Percent	%
	Low Limit		40.0	0.0 to 100.0	Percent	%



#### **SETPOINTS - Miscellaneous**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

De	escription	Value	Default	Range	Ur	nits
Remote Capacity Dead	band		1.0	0.5 to 20.0	Percent	%
	Enabled / Disabled		Disabled	None	No	ne
High Comp. Oil Pressure	Shutdown		50.0	0.0 to 500.0	Pressure	PSIG
ressure	Delay		5	0.0 to 60.0	Time	SEC
Max. Slide Valve Timer			30	0.0 to 600.0	Time	TENTHS- SEC
	Enabled / Disabled		Disabled	None	None	
Dewpoint Temp. Warning - Running	Safety Factor		20.0	20.0 to 100.0	Temp.	F
	Delay		5	0.0 to 99.0	Time	MIN
	Enabled / Disabled		Disabled	None		
Dewpoint Temp.	Safety Factor		2.0	0.0 to 100.0	Temp.	F
Warning - Off	Delay		5	0.0 to 99.0	Time	MIN
	Heater Control Safety Factor		5.0	0.0 to 100.0	Temp.	F
Maximum Discharge Pressure			270.0	0.0 to 365.3	Pressure	PSIG
Maximum Discharge and Oil. Temp.			250.0	100.0 to 300.0	Temp.	F

## SETPOINTS - Scheduling

Control	Hour (0-23)	Min (0-59)	Mode (1-4)	Hour (0-23)	Min (0-59)	Mode (1-4)	Hour (0-23)	Min (0-59)	Mode (1-4)	Hour (0-23)	Min (0-59)	Mode (1-4)
Sunday												
Monday												
Tuesday												
Wednesday												
Thursday												
Friday												
Saturday												
Sunday												



#### **SETPOINTS - PHD Monitoring**

	Descr	iption	Value	Default	Range	Units	
	Disabled /	Vibration Monitoring		Disabled	None	None	
		High Warning		3.5	0.0 to 30.0	(See Manual 070.020-TB)	gF
	Suction	High Warning Delay		99	0.0 to 999.0	Time	SEC
<b>C</b>	End	High Shutdown		10.0	0.0 to 30.0	(See Manual 070.020-TB)	gF
Compressor Bearing		High Shutdown Delay		1	0.0 to 999.0	Time	SEC
J		High Warning		3.5	0.0 to 30.0	(See Manual 070.020-TB)	gF
	Discharge	High Warning Delay		99	0.0 to 999.0	Time	SEC
	End	High Shutdown		10.0	0.0 to 30.0	(See Manual 070.020-TB)	gF
		High Shutdown Delay		1	0.0 to 999.0	Time	SEC
		Vibration Monitoring / re Monitoring		Disabled	None	None	
	Shaft Side	High Warning		3.5	0.0 to 30.0	(See Manual 070.020-TB)	gF
		High Warning Delay		99	0.0 to 999.0	Time	SEC
Motor		High Shutdown		10.0	0.0 to 30.0	(See Manual 070.020-TB)	gF
Bearing		High Shutdown Delay		1	0.0 to 999.0	Time	SEC
	Opposite Shaft	High Warning		3.5	0.0 to 30.0	(See Manual 070.020-TB)	gF
		High Warning Delay		99	0.0 to 999.0	Time	SEC
		High Shutdown		10.0	0.0 to 30.0	(See Manual 070.020-TB)	gF
		High Shutdown Delay		1	0.0 to 999.0	Time	SEC
	Disabled /	Temperature Monitoring		Disabled	None	None	
		High Warning		302.0	32.0 to 500.0	Temp.	F
	Stator #1	High Warning Delay		5	0.0 to 999.0	Time	SEC
	Statol #1	High Shutdown		311.0	32.0 to 500.0	Temp.	F
		High Shutdown Delay		5	0.0 to 999.0	Time	SEC
		High Warning		302.0	32.0 to 500.0	Temp.	F
Motor Stator	Stator	High Warning Delay		5	0.0 to 999.0	Time	SEC
	# 2	High Shutdown		311.0	32.0 to 500.0	Temp.	F
		High Shutdown Delay		5	0.0 to 999.0	Time	SEC
		High Warning		302.0	32.0 to 500.0	Temp.	F
	Stator	High Warning Delay		5	0.0 to 999.0	Time	SEC
	# 3	High Shutdown		11.0	32.0 to 500.0	Temp.	F
		High Shutdown Delay		5	0.0 to 999.0	Time	SEC



#### SETPOINTS - PID Setup Page 1 \*

Control	Description	Value	Default *	Range *	Units	*
	Name		EZ Cool LIOC			
İ	Control		Always	Ì		
	Action		Forward	1 .		
İ	Control Point		Disch. Temp.	Refer to	Non	е
	IO Board		Analog 1	090.022-0 (Op- eration)		
DID 4	Output Channel		1	eration)		
PID 1	Setpoint		145.0	Ì	Based ι	ıpon
	Proportional Band		25.0	1	Control	
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0		
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 2			
	Control		Disabled			
	Action		Forward	]	Non	_
	Control Point		Cap. slide	Refer to 090.022-0	INOII	е
	IO Board		Analog 1	(Operation)		
PID 2	Output Channel		2	(Operation)		
PID 2	Setpoint		0		Based ι	ıpon
	Proportional Band		0		Control	Point
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0		
	Low Limit			-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 3			
	Control		Disabled	]		
	Action		Forward	] ,	Non	•
	Control Point		Cap. slide	Refer to 090.022-0	INOII	e
	IO Board		None	(Operation)		
PID 3	Output Channel		0	(operation)		
l PID 3	Setpoint		0		Based ເ	
	Proportional Band		0		Control	Point
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0	]	
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 4			
	Control		Disabled			
	Action		Forward	Defente	Non	_
	Control Point		Cap. slide	Refer to 090.022-O	INOIT	-
	IO Board		None	(Operation)		
PID 4	Output Channel		0	(		
'''	Setpoint		0		Based เ	
	Proportional Band		0		Control	
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0	Į	
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		

<sup>\*</sup> Defaults, ranges and Units will be based upon the setting of the Control Point (settings shown are for the default Control Point setting of Capacity Slide).



#### SETPOINTS - PID Setup Page 2 \*

Control	Description	Value	Default *	Range *	Units	*
	Name		PID # 5			
	Control		Disabled			
	Action		Forward	5.6.	Non	_
	Control Point		Cap. slide	Refer to 090.022-0	Non	е
Dis-	IO Board		None	(Operation)		
charge	Output Channel		0	(Operation)		
Butterfly	Setpoint		0		Based u	ıpon
Valve	Proportional Band		0		Control	Point
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0		
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 6			
	Control		Disabled			
	Action		Forward	56.	Non	•
	Control Point		Cap. slide	Refer to 090.022-0	NOII	E
	IO Board		None	(Operation)		
PID 6	Output Channel		0	(Operation)		
I PID 6	Setpoint		0	_	Based u	ıpon
	Proportional Band		0		Control Poir	
	Integration Time		30.0	0.0 to 1000.0 -50.0 to 150.0	Time	SEC
	High Limit		100.0			
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 7			
	Control		Disabled			
	Action		Forward	Defeate	Non	^
	Control Point		Cap. slide	Refer to 090.022-0	NOI	<b>C</b>
	IO Board		None	(Operation)		
PID 7	Output Channel		0	(0 p 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0		
''''	Setpoint		0		Based u	
	Proportional Band		0		Control	Point
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0		
	Low Limit		0.0	-50.0 to 150.0	Percent	%
	When Running Off Value		0.0	0.0 to 100.0		
	Name		PID # 8			
	Control		Disabled			
1	Action		Forward	Refer to	Non	<b>e</b>
	Control Point		Cap. slide	090.022-O	11011	_
	IO Board		None	(Operation)		
PID 8	Output Channel		0			
	Setpoint		0		Based u	
	Proportional Band		0		Control	
	Integration Time		30.0	0.0 to 1000.0	Time	SEC
	High Limit		100.0	-50.0 to 150.0	_	
	Low Limit 0.0 -50.0 to 150.0				Percent	%
	When Running Off Value		0.0	0.0 to 100.0		

<sup>\*</sup> Defaults, ranges and Units will be based upon the setting of the Control Point (settings shown are for the default Control Point setting of Capacity Slide).



### SETPOINTS - Superheat Control Setup\*

Control	Description	Value	Default *	Range *	Units	s *	
	Name		Superheat # 1				
	Control		Disabled				
	Action		Forward				
	Control Pressure		Suction Pressure	Refer to	Non	е	
	Control Temperature		Suction Temperature	090.022-0			
	Output Board		None	(Operation)			
SUPERHEAT # 1	Output Channel		0				
# 1	Setpoint		10.0		Based	upon	
	Proportional Band		2.0		Control		
	Integration Time		30.0	0.0 to 999.0	Time	SEC	
	High Limit		100.0	-50.0 to 150.0	Percent		
	Low Limit		0.0	-50.0 to 150.0	rereene	%	
	When Running Off		0.0	0.0 to 100.0			
	Name		Superheat # 2			^	
	Control	Dis					
	Action		Forward				
	Control Pressure		Suction Pressure	Refer to	Non	е	
	Control Temperature		Discharge Temperature	090.022-O			
	Output Board		None	(Operation)			
SUPERHEAT # 2	Output Channel		0				
# 2	Setpoint		10.0 F		Based upon		
	Proportional Band		2.0 F		Control		
	Integration Time		30.0	0.0 to 999.0	Time	SEC	
	High Limit		100.0	-50.0 to 150.0			
	Low Limit		0.0	-50.0 to 150.0	Percent	%	
	When Running Off		0.0	0.0 to 100.0			
	Name		Superheat # 3			1	
	Control		Disabled				
	Action		Forward				
	Control Pressure		Suction Pressure	Refer to	Non	е	
	Control Temperature		Discharge Temperature	090.022-O			
	Output Board		None	(Operation)			
SUPERHEAT # 3	Output Channel		0				
# 3	Setpoint		10.0 F		Based (	upon	
	Proportional Band		2.0 F		Control		
	Integration Time		30.0	0.0 to 999.0	Time	SEC	
	High Limit		100.0	-50.0 to 150.0	Percent	%	
	Low Limit		0.0	-50.0 to 150.0			
	When Running Off		0.0	0.0 to 100.0			

<sup>\*</sup> Defaults, ranges and Units will be based upon the setting of the Control Point (settings shown are for the default Control Point setting of Capacity Slide).

## **SETPOINTS - Discharge Butterfly Valve**

Description	Value	Default	Range	Ur	nits
Discharge Butterfly Valve		Disabled	Disabled/ Enabled		
I/O Board		None	None Analog Board 1 Analog Board 2	None	
I/O Channel		0	0 to 999		
Pressure Differential Setpoint		0.0	0.0 to 40.0		
Dead Band		2.0	0.0 to 100.0	Pressure	PSIG
Proportional Band		5.0	0.0 to 100.0		



### SETPOINTS - Auxiliary Analog Input Safeties - Page 1

Control	Description		Value	Default	Range	Units	5
	Auxiliary A	nalog 1		Disabled	Disabled/ Enabled	None	
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
l	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Auxiliary Analog 1	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
Allalog 1	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A	nalog 2		Disabled	Disabled/ Enabled	None	
	Low Warning	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
		Delay		0	0.0 to 999.0	Time	SEC
Auxiliary Analog 2	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
Alialog 2	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A	nalog 3		Disabled	Disabled/ Enabled	None	
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Auxiliary Analog 3	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
Allalog	High Warning	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
		Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A	nalog 4		Disabled	Disabled/ Enabled	None	
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Auxiliary	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Analog 4	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A			Disabled	Disabled/ Enabled	None	
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Auxiliary	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Analog 5	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC



## SETPOINTS - Auxiliary Analog Input Safeties - Page 2

Control	Description		Value	Default	Range	Units	5
	Auxiliary A	nalog 6		Disabled	Disabled/ Enabled	None	9
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Amilian	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Auxiliary Analog 6	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
Androg	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A	nalog 7		Disabled	Disabled/ Enabled	None	<u>,                                    </u>
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Amilian	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Auxiliary Analog 7	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
'	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A	nalog 8		Disabled	Disabled/ Enabled	None	<u>,                                      </u>
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Auxiliary	Low Shutdown	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Analog 8		Delay		0	0.0 to 999.0	Time	SEC
	High Warning	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
		Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A			Disabled	Disabled/ Enabled	None	
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Auxiliary	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Analog 9	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	Auxiliary A			Disabled	Disabled/ Enabled	None	DC: 5
	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
Auxiliary	Low	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
Analog 10	Shutdown	Delay		0	0.0 to 999.0	Time	SEC
	High	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
	Warning	Delay		0	0.0 to 999.0	Time	SEC
	High Shutdown	Setpoint		30 Hg	0.0 to 420.4	Pressure	PSIG
		Delay		0	0.0 to 999.0	Time	SEC



### **SETPOINTS - Auxiliary Digital Input Configuration**

Control	Description	Value	Default	Range	Units
	Name ***		Auxiliary Input 1		None
	IO Board *		Dig. Bd. 1		*
Auxiliary Input 1	IO Channel		17		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 2		None
	IO Board *		Dig. Bd. 1		*
Auxiliary Input 2	IO Channel		18		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 3		None
	IO Board *		Dig. Bd. 2		*
Auxiliary Input 3	IO Channel		9		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 4		None
	IO Board *		Dig. Bd. 2		*
Auxiliary Input 4	IO Channel		10		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 5		None
	IO Board *		Dig. Bd. 2		*
Auxiliary Input 5	IO Channel		11		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 6		None
	IO Board *		Dig. Bd. 2		*
Auxiliary Input 6	IO Channel		12		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 7		None
	IO Board *		Dig. Bd. 2		*
Auxiliary Input 7	IO Channel		13	None	
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC
	Name ***		Auxiliary Input 8		None
	IO Board *		Dig. Bd. 2	*	
Auxiliary Input 8	IO Channel		14		None
	Activity **		Disabled		**
	Delay		0	0 to 60	Time SEC

#### \* IO Board

None
Digital Board 1
Digital Board 2

#### \*\* Activity

Disabled
Shutdown When Starting/Running
Shutdown When Running
Shutdown Always
Warning When Starting/Running
Warning When Running
Warning Always

#### \*\*\* Name

Chinese version does not have the option to change text for auxiliary input Name – default name only available.



## **SETPOINTS - Auxiliary Digital Output Configuration**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Description	Value	Default	Range	Units
	Analog Channel		Capacity Slide Position	None	Mana
	< >		>	< or >	None
	On When Off When		0.0	-10000.0 to 10000.0	%
Output A	Control When		Disabled	Disabled Running Always	
	IO Board		Dig. Bd. 2		
	IO Channel		7		
	Analog Channel		Capacity Slide Position	None	
	< >		>	< or >	None
	On When		0.0	-10000.0 to	%
	Off When		0.0	10000.0	70
Output B	Control When		Disabled	Disabled Running Always	
	IO Board		Dig. Bd. 2	None	
	IO Channel		8	None	
	Analog Channel		Capacity Slide Position	None	
	< >		>	< or >	None
	On When Off When		0.0	-10000.0 to 10000.0	%
Output C	Control When		Disabled	Disabled Running Always	
	IO Board		Dig. Bd. 2	None	
	IO Channel		18	110110	
	Analog Channel		Capacity Slide Position	None	
	< >		>	< or >	None
	On When			-10000.0 to	٥,
	Off When		0.0	10000.0	%
Output D	Control When		Disabled	Disabled Running Always	
	IO Board		None	None	
	IO Channel		0	None	
	Analog Channel		Capacity Slide Position	None	
	< >		>	< or >	None
	On When		0.0	-10000.0 to	%
Output E	Off When		0.0	10000.0	/0
	Control When		Disabled	Disabled Running Always	
	IO Board		None		
I	IO Channel		0		



# SETPOINTS - Auxiliary Digital Output Configuration -CONTINUED -

Control	Description	Value	Default	Range	Units
	Analog Channel		Capacity Slide Position	None	
	<>		>	< or >	None
	On When		0.0	-10000.0 to	%
	Off When		0.0	10000.0	70
Output F	Control When		Disabled	Disabled Running Always	
	IO Board		None	None	
	IO Channel		0	None	
	Analog Channel		Capacity Slide Position	None	
	<>		>	< or >	None
	On When		0.0	-10000.0 to	0/
	Off When		0.0	10000.0	%
Output G	Control When		Disabled	Disable Running Always	g
	IO Board		None		
	IO Channel		0	None	
	Analog Channel		Capacity Slide Position	None	
	< >	Suppose		< or >	None
	On When		>		
	Off When		0.0		%
Output H	Control When		Disabled	Disabled Running Always	
	IO Board		None		
	IO Channel		0	None	
	Analog Channel		Capacity Slide Position		
İ	<>		>	< or >	None
	On When		0.0	-10000.0 to	۰,
	Off When		0.0	10000.0	%
Output I	Control When		Disabled	Disable Runnin Always	g
	IO Board		None		
	IO Channel		0	None	
	Analog Channel		Capacity Slide Position		
	<>		>	< or >	None
	On When			-10000.0 to	۰,
	Off When		0.0	10000.0	%
Output J	Control When	Disabled		Disable Runnin Always	g
1	IO Board		None		
	10 Board		None	None	

### **SETPOINTS - Timed Digital Output Configuration**

Control	Description	Value	Default	Range	Units	
	On		00 : 00	0.0-23.0 : 0.0-59.0	HR:MIN	
	Off		00 : 00	0.0-23.0 . 0.0-39.0	LIK'IMIIN	
	Control When		Disabled	Disabled Running Always		
Output A	Which Days		Every Day	Every Day Week Days		
	IO Board		None	None Digital Board 1 Digital Board 2		
	IO Channel		0	None		
	On		00 : 00	0.0-23.0 : 0.0-59.0	HR:MIN	
	Off		00 : 00	0.0-23.0 . 0.0-39.0	HK.IVIIIN	
	Control When		Disabled	Disabled Running Always		
Output B	Which Days		Every Day	Every Day Week Days		
	IO Board		None	None Digital Board 1 Digital Board 2		
	IO Channel		0	None		
	Run Hour Interval		0	0.0 - 100000.0	HOURS	
	On Time		0	0.0 - 100000.0	MINUTES	
Output C	IO Board			None Digital Board 1 Digital Board 2		
	IO Channel		0	None		



### **SETPOINTS - Panel**

Descr	ription	Value	Default	Range		Units	
Panel Heater	On		53.6	32.0 to 77.0	Temp.	F	
Paner Heater	Off		55.4	32.0 to 77.0		Г	
Remote Enable Output			Disabled	Disabled Compressor Mode: Remote I/O Compressor and Capacity Modes: Remote I/O Compressor Mode: Remote I/O and Cap. Mode: Remote 4			
Input Module Selection	Input Module Capacity Mode Selection		Disabled	Disabled Enabled			
Permissive Start			Disabled	Disabled Starting Always			
Power Fail Enabled/Dis- abled			Disabled	Disabled Enabled			
Restart	Restart Time		0	1.0 to 99.0	Time	MIN	
Run Hours			0	0 to 100000	Tille	HRS	
PLC Interlock			Disabled	Disabled			
Remote Contr	ol Setpoint		Disabled	Enabled			
Recycle Delay if VFD selected			Enabled	Disabled Enabled			
Pressure Displ	ay Resolution		1 Place	1 Place 2 Place 3 Place			
Browser Automatic Refresh		Disabled	Disabled Enabled				
Extra Digital Auxiliaries		Disabled	Disabled Enabled				
Extra Analog Auxiliaries and Retransmitting Outputs		Disabled	Disabled Enabled				



#### **CALIBRATION - Pressure**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	ntrol Description		Value	Default	Range	Unit	s	
Atmospheric P	ressure			14.7	8.0 to 20.0	Pressure	PSIG	
	Current v	alue			None	None	e	
	Offset			0.0	-30.0 to 30.0			
		Low		30.0 Hg		Pressure	PSIG	
Suction	Range	High		185.3	0.0 to 985.3			
	Sensor Signal **			1-5V			•	
	IO Board	*		Analog Board 1	None	None	е	
	IO Chann	el		9		Ī		
	Current v	alue			None	Non	e	
	Offset			0.0	-30.0 to 30.0			
		Low		30.0 Hg	İ	Pressure	PSIG	
Discharge	Range	High		485.3	-14.7 to 985.3			
J	Sensor S			1-5V				
	IO Board			Analog Board 1	None	None	е	
	IO Chann			8				
	Current v	alue		1	None	None	e	
	Offset			0.0	-30.0 to 30.0			
Oil		_	Low		30.0 Hg		Pressure	PSIG
	Range	High		485.3	-14.7 to 985.3			
	Sensor S			1-5V				
	IO Board *			Analog Board 1	None	None	е	
	IO Channel			6				
	Current v	alue			None	None		
	Offset			0.0	-30.0 to 30.0			
		Low		30.0 Hg		Pressure	PSIG	
Filter	Range	High		485.3	-14.7 to 985.3			
	Sensor S	ignal **		1-5V				
	IO Board	*		Analog Board 1	None	None	е	
	IO Chann	el		6				
	Current v	alue			None	None	e	
	Offset			0.0	-30.0 to 30.0			
	D	Low		30.0 Hg	1471-0052	Pressure	PSIG	
Economizer	Range	High		485.3	-14.7 to 985.3			
	Sensor S	ignal **		1-5V				
	IO Board	*		Analog Board 1	None	None	е	
	IO Chann	el		6				
	Current v	alue			None	None	е	
	Offset			0.0	-30.0 to 30.0			
	Danza	Low		30.0 Hg	147+- 005 3	Pressure	PSIG	
Balance Piston	Range	High		485.3	-14.7 to 985.3			
FISCOII	Sensor S	ignal **		1-5V				
	IO Board			None	None	None		
	IO Board * IO Channel							

This Setpoint table continues on the next page.



## **CALIBRATION - Pressure**

#### -CONTINUED -

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Description	)	Value	Default	Range	Unit	s	
	Current value				None	None		
	Offset			0.0	-30.0 to 30.0			
6	Dange	Low		30.0 Hg	-14.7 to 985.3	Pressure	PSIG	
System Discharge	Range	High		485.3	-14.7 (0 965.5			
Discharge	Sensor Signal **			1-5V				
	IO Board *			Analog Board 1	None	None	e	
	IO Channel			6				
	Current value				None	None	е	
	Offset			0.0	-30.0 to 30.0	Pressure		
Maria 011	Range	Low		30.0 Hg	-14.7 to 985.3		PSIG	
Main Oil Injection		High		485.3	-14.7 (0 965.5			
linjection	Sensor Signal **			1-5V				
	IO Board *			Analog Board 1	None	None		
	IO Channel			6				
	Current value				None	None	e e	
	Offset			0.0	-30.0 to 30.0			
	Pango	Low		30.0 Hg	-14.7 to 985.3	Pressure	PSIG	
Manifold	Range	High		485.3	-14.7 (0 965.5			
	Sensor Signal **			1-5V				
	IO Board *			None	None None		None	
	IO Channel			15				

#### \* IO Board:

None				
Analog Board 1				
Analog Board 2				

- U			
None	4-20mA	RTD	Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V



#### **CALIBRATION - Temperature**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Descrip	tion	Value	Default	Range	Units	
	Current va	lue			None	None	
	Offset			0.0	-92.2 to 92.2		
	D	Low		-459.4	1760   1022	Temperature	F
Suction	Range	High		463.1	-1768 to 1832		
	Sensor Sig	nal **		ICTD			
	IO Board *			Analog Board 1	None	None	
	IO Channe	Ī		1			
	Current va	lue			None	None	
	Offset			0.0	-92.2 to 92.2		
	_	Low		-459.4	1760 / 1000	Temperature	F
Discharge	Range	High		463.1	-1768 to 1832		İ
	Sensor Sig	nal **		ICTD			
	IO Board *			Analog Board 1	None	None	
	IO Channe	I		2			
	Current va	lue			None	None	
	Offset			0.0	-92.2 to 92.2		
	Range	Low		-459.4	-1768 to 1832	Temperature	F
Oil		High		463.1	-1706 (0 1632		
	Sensor Signal **			ICTD		None	
	IO Board *			Analog Board 1	None		
	IO Channel			3			
	Current va	lue			None	None	
	Offset			0.0	-92.2 to 92.2		
	Range	Low		-459.4	-1768 to 1832	Temperature	F
Separator		High		463.1	1700 (0 1032		
	Sensor Sig			ICTD			
	IO Board *			Analog Board 1	None	None	
	IO Channe	l		4			
	Current va	lue			None	None	
	Offset			0.0	-92.2 to 92.2		
Process	Range	Low		-459.4	-1768 to 1832	Temperature	F
Leaving		High		463.1			
l	Sensor Sig			ICTD			
	IO Board *			None	None	None	
	IO Channe			5			
	Current va	lue			None	None	1
	Offset			0.0	-92.2 to 92.2	_	_
Process	Range	Low		-459.4	-1768 to 1832	Temperature	F
Entering		High		463.1			
	Sensor Sig			ICTD			
	IO Board *			None	None	None	
	IO Channe			4			
Panel	Current va	lue			0.0 to 45.0	Temperature	F
Pallel	Offset			0.0		,	

#### \* IO Board

# None Analog Board 1

Analog Board 2

None	None 4-20mA		Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V

## $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



### **CALIBRATION - Capacity/Volume**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Description	Value	Default	Range	Units
	Sensor Signal **		4-20mA		
Canadity	IO Board *		Analog Board 1	None	None
Capacity	IO Channel		14		None
	Travel		196.0	0.0 to 500.0	
Volume	Sensor Signal **		4-20mA		
	IO Board *		Analog Board 1	None	
	IO Channel		15		
	Bottom of Range		2.2	0.0 to 10.0	None
	Top of Range		5.0	0.0 to 10.0	
	Dead Band		0.2	0.0 to 2.0	
	Minimum On Time		0.5	0.0 to 5.0	

#### \* IO Board

None				
Analog Board 1				
Analog Board 2				

None	4-20mA	RTD	Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V



#### **CALIBRATION - Motor/Miscellaneous**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Motor Amps   Current value	Control	Description		Value	Default	Range	Unit	s
None								
None   None	Motor	Sensor Sig	gnal **		СТ	Nama	None	
Current value	Amps				Analog Board 1	None	None	
None   None		IO Channe	el		16			
None   None		Current value				None	Non	е
None   High   Sonou.0   Mone   Non		Offset			0.0	-500.0 to 500.0		
High   5000.0   A + 20mA   None		Pango	Low		0.0	1000 0 += 10000 0	Kilowatts l	kW
None   None	Kilowatts	Ranσe —	High		5000.0	-1000.0 to 10000.0		
None   None		Sensor Sig	gnal **		4-20mA			
Current v   V   Current v   V   Current v   V   Current v   V   V   V   V   V   V   V   V   V					None	None	Non	e
Part		IO Channe	el		16			
Remote Capacity Position In processing In Processing In In Processing In In Processing In In In In In In In In In In In In In		Current va	alue			None	Non	е
RPM		Offset			0.0	-360.0 to 360.0		
RPM		D	Low		0.0	1000 0 1 - 6000 0	Speed	RPM
OB   OB   OB   OB   OB   OB   OB   OB	RPM	Range	High		3600 RPM	-1000.0 to 6000.0		
O Board *   O Board *   O C		Sensor Sig	gnal **		4-20ma			
None   None					Analog Board 2	None	None	
Remote Capacity Position         Offset         0.0         -10.0 to 10.0         Percent         %           Position         Low High         0.0         -1000.0 to 1000.0         Percent         %           Sensor Signal ** Input         Low Input         None <th colspa<="" td=""><td>i I</td><td>IO Channe</td><td>el</td><td></td><td></td><td></td></th>	<td>i I</td> <td>IO Channe</td> <td>el</td> <td></td> <td></td> <td></td>	i I	IO Channe	el				
Remote Capacity Position         Low High         0.0         -1000.0 to 1000.0         Percent         %           Sensor Signal ** IO Board * IO Channel         4-20Ma IO Board * IO Channel         None         None         None         None         None         None         None         None         None         None         None         None         None         None         None         None         None         Persure         PSIG         None         None         Pressure         PSIG         PSIG         None <td></td> <td>Current va</td> <td>alue</td> <td></td> <td></td> <td>None</td> <td>Non</td> <td>е</td>		Current va	alue			None	Non	е
Range   High   100.0 %   -1000.0 to 1000.0		Offset			0.0	-10.0 to 10.0		
Capacity Position   High   100.0 %   -100.0 to 1000.0	Remote	D	Low		0.0	1000 0 1 - 1000 0	Percent	%
None   None	Capacity	Range Hi	High		100.0 %	-1000.0 to 1000.0		
None   None					4-20Ma		None	
Current value   Offset   O.0   O.	İ				None	None		
Description   Control   Pressure   Policy   P					0			
External Input         Low High         -30.0 485.3 PSIG         -14.7 to 985.3         Pressure         PSIG           Sensor Signal ** IO Board * IO Channel         None						None	one None	
Range		Offset			0.0	-75.0 to 75.0		
Sensor Signal **   10 Board *   10 Board *   10 Channel   10 Channel   12   12   12   12   12   14   15   15   15   15   15   15   15		D	Low		-30.0	147+- 0052	Pressure	PSIG
Sensor Signal **   10 Board *   10 Board *   12		Range	High		485.3 PSIG	-14.7 to 985.3		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	iliput	Sensor Sig	gnal **		4-20mA			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		IO Board *			None	None	None	
Current value		IO Channel			12	1		
Offset	Control	Description		Value	Default	Range	Unit	s
Remote Control Setpoint         Low High         30.0         0.0 to 985.3         Pressure         PSIG           4-20mA         Sensor Signal **         4-20mA         4-20mA         Pressure         PSIG		Current va	alue			None	Non	e
Control         Range         High         185.3         0.0 to 985.3           Setpoint         Sensor Signal **         4-20mA		Offset			0.0	-30.0 to 30.0		
Control         High         185.3         0.0 to 985.3           Setpoint         Sensor Signal **         4-20mA	Remote	Dance	Low		30.0	0.0 to 985.3	Pressure	PSIG
	Control	•			185.3	0.0 to 985.3		
	Setpoint	Sensor Sig	gnal **		4-20mA			
TO BOULD INDIE		IO Board *			Analog Board 1	None	Non	e
IO Channel 12								
Current value None None		Current va	alue			None	Non	e
Offset 0.0 -10.0 to 10.0		Offset			0.0	-10.0 to 10.0		
Low 0.0 -1000.0 to 1000.0 Percent %		Danes	Low		0.0	-1000.0 to 1000.0	Percent	%
Liquid Range High 100.0 -1000.0 to 1000.0		kange	High		100.0	-1000.0 to 1000.0		
Level         Sensor Signal **         4-20mA	Level	Sensor Sig	gnal **		4-20mA		·	
IO Board * None None None					•	None	Non	e
IO Channel 0								

#### \* IO Board

None				
Analog Board 1				
Analog Board 2				

None	4-20mA	RTD	Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V



## **CALIBRATION - PhD Monitoring**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Description		Value	Default	Range	Units	
	Current value				None		
	Offset			0.0	-3.0 to 3.0	_	
Compressor	Range (4-20mA only)	Low		0.0	-1000.0 to	gF	
Vibration - Suction		High		30.0	1000.0		
Suction	Sensor Signal **			Vibration		<b> </b>	
	IO Board			None	None	None	
	IO Channel			17			
	Current value				None		
	Offset			0.0	-3.0 to 3.0	gF	
Compressor	Range (4-20mA only)	Low		0.0	-1000.0 to	8.	
Vibration -		High		30.0	1000.0		
Discharge	Sensor Signal **			Vibration			
	IO Board			None	None	None	
	IO Channel			18			
	Current value	,			None		
	Offset			0.0	-3.0 to 3.0	gF	
Motor	Range (4-20mA only)	Low		0.0	-1000.0 to	gr	
Vibration – Shaft Side	Range (4 ZoniA only)	High		30.0	1000.0		
	Sensor Signal **			Vibration	None	None	
	IO Board			None			
	IO Channel			19			
	Current value				None		
	Offset			0.0	-3.0 to 3.0		
Motor	Danier (4. 20 a. A. a. d.)	Low		0.0	-1000.0 to	gF	
Vibration – Opposite Shaft	Range (4-20mA only)	High		30.0	1000.0	İ	
Side	Sensor Signal **			Vibration			
	IO Board			None	None	None	
	IO Channel			20			
	Current value				None		
	Offset			0.0	-92.3 to 92.3	<b> </b>	
Motor	Danier (4.00 A. 1.)	Low		-459.4	-1768.0 to	F	
Temperature – Shaft Side	Range (4-20mA only)	High		463.1	1832.0		
	Sensor Signal **			RTD			
	IO Board			None	None	None	
	IO Channel	i i		19			
	Current value				None		
Motor Temperature –	Offset			0.0	-92.3 to 92.3		
	. (	Low		-459.4	-1768.0 to	F	
	Range (4-20mA only)	High		463.1	1832.0		
Opposite Shaft Side	Sensor Signal **			RTD			
Side						l	
	IO Board			None	None	None	

This Setpoint table continues on the next page.



## **CALIBRATION - PhD Monitoring**

#### -CONTINUED -

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Control	Description		Value	Default	Range	Units
	Current value				None	
	Offset			0.0	-92.3 to 92.3	F
Motor	Range (4-20mA only)	Low		-459.4	-1768.0 to	Г
Stator	Range (4-2011A Only)	High		463.1	1832.0	
# 1	Sensor Signal **			RTD		
	IO Board			None	None	None
	IO Channel			21		
	Current value				None	
	Offset			0.0	-92.3 to 92.3	F
Motor	Range (4-20mA only)	Low		-459.4	-1768.0 to	Г
Stator		High		463.1	1832.0	
# 2	Sensor Signal **			RTD		
	IO Board			None	None	None
	IO Channel			22		
	Current value				None	
	Offset			0.0	-92.3 to 92.3	_
Motor Stator	Dange (4 20m A anly)	Low		-459.4	-1768.0 to	F
	Range (4-20mA only)	High		463.1	1832.0	
# 3	Sensor Signal **			RTD		
	IO Board	_		None	None	None
	IO Channel			23		

#### \* IO Board

None				
Analog Board 1				
Analog Board 2				

None	None 4-20mA		Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V



#### **CALIBRATION - Analog Outputs (Retransmitting Outputs)**

Output Channel	Description	Value	Default	Range	Units
	Input Channel to Retransmit *		Capacity Slide Position		
Α	IO Board **		Analog Board 1	None	None
	IO Channel		3		
	Input Channel to Retransmit *		Capacity Slide Position		
В	IO Board **		None	None	None
	IO Channel		0		
	Input Channel to Retransmit * Capacity Slide Position				
С	IO Board **		None	None	None
	IO Channel		0		
	Input Channel to Retransmit *		Capacity Slide Position		None
D	IO Board **		None	None	
	IO Channel		0		
	Input Channel to Retransmit *		Capacity Slide Position		
E	IO Board **		None	None	None
	IO Channel		0		
	Input Channel to Retransmit *		Capacity Slide Position		
F	IO Board **		None	None	None
	IO Channel		0		
	Input Channel to Retransmit *		Capacity Slide Position		
G	IO Board **		None	None	None
	IO Channel		0		
	Input Channel to Retransmit *		Capacity Slide Position		
Н	IO Board **		None	None	None
	IO Channel		0		

#### \* Input Channel to Retransmit

Capacity Slide Position Process/Brine Temperature Entering Volume Slide Position Remote Control Setpoint Suction Pressure **Motor Current** Discharge Pressure RPM Compressor Oil Pressure Auxiliary Analog 1 - 10 Main Oil Injection Pressure EZ Cool Feedback % **Economizer Pressure** Auxiliary Analog 12-20 Filter Pressure Manifold Pressure Intermediate Pressure Remote Capacity Position **Balance Piston Pressure** Compressor Vibration - Suction Compressor Vibration - Discharge System Discharge Pressure Motor Vibration - Shaft Side Suction Temperature Motor Vibration - Opposite Shaft Side Discharge Temperature Motor Temperature - Shaft Side Motor Temperature - Opposite Shaft Side Compressor Oil Temperature Oil Separator Temperature Process/Brine Temperature Leaving Motor Stator #1 - #3

\*\* IO Board

None Analog Board 1 Analog Board 2



## **CALIBRATION - Analog Outputs (VFD / Condenser Outputs)**

Output Channel	Description	Value	Default	Range	Units
Communication VED	IO Board *		Analog Board 2	None	Name
Compressor VFD	IO Channel		3	None	None
Condonoer Outnut A	IO Board *		Analog Board 1	None	None
Condenser Output A	IO Channel		5	None	None
Condenser Output B	IO Board *		Analog Board 1	None	None
Condenser Output B	IO Channel		6	None	None

#### \* IO Board

None		
Analog Board 1		
Analog Board 2		

## **CALIBRATION - Analog Output Calibration**

Description	Value	Default	Range	Units
Select Analog Board		Analog Board 1	None	None
Select Analog Output Channel to Calibrate		1		



## **CALIBRATION - Auxiliaries Analogs (Page 1)**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Name	Description	Value	Default	Range	Units	5
	Name		Auxiliary Analog 1	None	None	:
Auxiliary	Current value				l	
Analog 1	Offset		0.0	-75.0 to 75.0	Pressure	PSIG
7	Range Low		30.0 Hg	0.0 to 1435.6	11033410	1 5.0
	High		485.3		<u> </u>	
	Name		Auxiliary Analog 2	None	None	<u>:</u>
Auxiliary	Current value		0.0	75.0 += 75.0		
Analog 2	Offset		0.0	-75.0 to 75.0	Pressure	PSIG
	Range Low High		30.0 Hg 485.3	0.0 to 1435.6		
	Name		Auxiliary Analog 3		None	
	Current value		Auxiliary Arialog 5	None	None	
Auxiliary	Offset		0.0	-75.0 to 75.0	i	
Analog 3	Low		30.0 Hg		Pressure	PSIG
	Range High		485.3	0.0 to 1435.6	l	
	Name		Auxiliary Analog 4		None	:
A	Current value		, , , , , , , , , , , , , , , , , , ,	None	<u> </u>	
Auxiliary	Offset		0.0	-75.0 to 75.0	Drocoure	PSIG
Analog 4	Pango Low		30.0 Hg	0.0 to 1435.6	Pressure	P31G
	Range High		485.3	0.0 (0 1435.0		
	Name		Auxiliary Analog 5	None	None	:
Auxiliary	Current value					
Analog 5	Offset		0.0	-75.0 to 75.0	Pressure	PSIG
Allalog 3	Range Low		30.0 Hg	0.0 to 1435.6	Tressure	1 3.0
	High		485.3			
	Name		Auxiliary Analog 6	None	None	:
Auxiliary	Current value					
Analog 6	Offset		0.0	-75.0 to 75.0	Pressure	PSIG
Ĭ	Range Low High		30.0 Hg 485.3	0.0 to 1435.6	l	
					None	
	Name Current value		Auxiliary Analog 7	None	None	:
Auxiliary	Offset		0.0	-75.0 to 75.0		
Analog 7	Low		30.0 Hg		Pressure	PSIG
	Range High		485.3	0.0 to 1435.6	i	
	Name		Auxiliary Analog 8		None	
	Current value			None		
Auxiliary	Offset		0.0	-75.0 to 75.0	Dwagarra	חכוכ
Analog 8	Pango Low		30.0 Hg	0.0 to 1435.6	Pressure	PSIG
	Range High		485.3	0.0 (0 1435.6		<u></u> j
	Name		Auxiliary Analog 9	None	None	
Auxiliary	Current value					
Analog 9	Offset		0.0	-75.0 to 75.0	Pressure	PSIG
,	Range Low		30.0 Hg	0.0 to 1435.6		
	High		485.3			
	Name		Auxiliary Analog 10	None	None	
Auxiliary Analog 10	Current value		20.0 ⊔~			
	Offset		30.0 Hg 0.0	-75.0 to 75.0	Pressure	PSIG
	Range Low High		485.3	0.0 to 1435.6	1	
	Name		EZ Cool Feedback %		None	
	Current value		LZ COULLECANACK /0	None	INOTIE	$\vdash$
EZ Cool	Offset		0.0	-10.0 to 10.0	i _	
Feedback %	Low		0.0	-1000.0 to	Percent	%
	Range High		100.0	10000.0	i	
		•				

<sup>\*</sup> Sensor Signal Selections:

None	4-20mA	RTD	Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V

\*\* Sensor Type

None		Temperature
Press	ure	Other



## **CALIBRATION - Auxiliaries (Page 2)**

(Units will be based upon the settings of the Session Screen, defaults are shown here)

Name	Description	Value	Default	Range	Units	
	IO Board		Auxiliary Analog 2			
Amellan	IO Channel		5			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 1	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
A 'II'	IO Channel		6			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 2	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
A !!! a	IO Channel		7			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 3	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
A !!!	IO Channel		8			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 4	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
	IO Channel		9			
Auxiliary Analog 5	Sensor Signal *		1-5 V	None		
	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
	IO Channel		10			
Auxiliary Analog 6	Sensor Signal *		1-5 V	Nor	ne	
	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
	IO Channel		11			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 7	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
A !!!	IO Channel		12			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 8	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
A	IO Channel		13			
Auxiliary	Sensor Signal *		1-5 V	Nor	ne	
Analog 9	Sensor Type **		Pressure	1		
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 2			
Auxiliary Analog 10	IO Channel		14			
	Sensor Signal *		1-5 V	Nor	ne	
	Sensor Type **		Pressure			
	Units if Type is Other		None			
	IO Board		Auxiliary Analog 1			
E7 C!	IO Channel		24			
EZ Cool	Sensor Signal *		4-20mA	None		
Feedback %	Sensor Type **		Other			
	Units if Type is Other		%			

\* Sensor Signal Selections:

None	4-20mA	RTD	Vibration
0-5V	Pot.	СТ	1-10V
1-5V	ICTD	RPM	+/- 5V

\*\* Sensor Type

None	Temperature
Pressure	Other

# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



## **CONFIGURATION - Compressor**

Control	Des	cription	Value	Default	-	Range		Units	
	Seque			Disabled		Disabled		None	
Misc.	Conde			Disabled		Enabled			
	Screer	Saver		15		0 to 60		Time MIN	
		Disabled / Enabled		Disabled		Disabled Enabled			
	Mode 1	Channel *		Suction Pressure		None			
		Direction		Forward		Forward Reverse			
	Mode	Disabled / Enabled		Disabled		Disabled Enabled			
	2	Channel *		Disabled			1		
Capacity	_	Direction		Forward		Forward Reverse		None	
	Mada	Disabled / Enabled		Disabled		Disabled			
	Mode 3	Channel *		Disabled		Enabled			
	3	Direction		Forward		Forward Reverse			
	Mada	Disabled / Enabled		Disabled		Disabled			
	Mode 4	Channel *		Disabled		Enabled		1	
	4	Direction		Forward		Forward Reverse			
	Compr	essor		RWF	RWF RWBII RXB RXF 12-50 RXF 58-101 RDB 4-Step RDB 3-Step	GSV II GST GSB 3-Step YLC SC York S7 York S5	Other Manuf. Recip-0 Recip-1 Recip-2 Recip-3		
	Pump			No Pump	No Pump Full Time		ry		
	Dual P	ump		Disabled		Disabled Enabled	,		
Package	Drive			Screw w/ Constant Electric		onstant Elec. D VFD Engine Drive Turbine DBS Vyper (Ram) Vyper (4-20m <i>l</i>		None	
	Refrige	erant		R717	R11 R113 R114 R1150 R12 R1270 R13 R134a R13b1 R14 R142b R170	R218 R22 R23 R290 R401a R402a R404a R410a R50 R500 R502 R503	R507 R508 R508B R600 R600a R717 R718 R728 R729 R744 R771 User Defined		



## **CONFIGURATION - Compressor (Continued)**

Control	Description	Value	Default		Range		Units
	Oil Type (VFD or Vyper only)		None	None Frick #2a Frick #2b Frick #3	Frick #9 Frick #11 Frick #13 Frick #13b	Frick #14 CP-4624-68F Solest 68 Solest 120	
Package (Cont)	Model (VFD or Vyper only)		NGC 100A	NGC 100A NGC 100B NGC 100C NGC 100D NGC 150A NGC 150B NGC 150C NGC 150D NGC 200A NGC 200B NGC 200C NGC 200D NGC 250A NGC 250B NGC 250C NGC 250D NGC 250D NGC 300A NGC 300B NGC 300C NGC 300D NGC 300D NGC 400A NGC 400B NGC 400C NGC 400D NGC 400C NGC 450B NGC 450B NGC 450C NGC 450D NGC 450D NGC 450E	NGC 450F SGC 1913 SGC 1918 SGC 2313 SGC 2317 SGC 2321 SGC 2813 SGC 2817 SGC 2821 SGC 2824 SGC 3511 SGC 3515 SGC 3519 SGB 3511 SGB 3515 SGB 3519 SGB 3555 TDSB 3555 TDSB 3555 TDSB 355XL TDSH 163L TDSH 163L TDSH 163L TDSH 163S TDSH 193L TDSH 233S TDSH 233XL TDSH 283S TDSH 283SX TDSH 283SX TDSH 283SX	TDSH 355L TDSH 355S TDSH 355XL TDSL 193L TDSL 193S TDSL 233L TDSL 233S TDSL 283L TDSL 283S TDSL 283XL XJF 120L XJF 120M XJF 120S XJF 151A XJF 151L XJF 151N XJF 151N XJF 151XR XJF 151XR XJF 151XR XJF 151XR XJF 151XR XJF 151XT XJF 95L XJF 95M XJF 95S XJS 120L XJS 120M XJS 120S XJS 120S XJS 95L XJS 95S XJS 95S	
	Filter		Disabled		Disabled Filter-Oil Discharge-Oil Discharge-Filte		
	Power Pac		No		No Yes		

#### \* Capacity Channel Range

Capacity Slide Position	Process/Brine Temperature Entering
Volume Slide Position	Remote Control Setpoint
Suction Pressure	Motor Current
Discharge Pressure	RPM
Compressor Oil Pressure	Auxiliary Analog 1 - 10
Main Oil Injection Pressure	EZ Cool Feedback %
Economizer Pressure	Auxiliary Analog 12- 20
Filter Pressure	Manifold Pressure
Intermediate Pressure	Remote Capacity Position
Balance Piston Pressure	Compressor Vibration - Suction
System Discharge Pressure	Compressor Vibration - Discharge
Suction Temperature	Motor Vibration - Shaft Side
Discharge Temperature	Motor Vibration - Opposite Shaft Side
Compressor Oil Temperature	Motor Temperature - Shaft Side
Oil Separator Temperature	Motor Temperature - Opposite Shaft Side
Process/Brine Temperature Leaving	Motor Stator #1 - #3



#### **CONFIGURATION - Communications**

Control	Description	Value	Default	Range	Units
Compres	ssor ID		0	0 to 99	
	Baud rate		19200	*	
	Data Bits		8	7 to 8	
Comm 1	Stop Bits		1	1 to 2	
	Parity		None	*	
	Protocol				
	Baud rate		19200		
	Data Bits		8	7 to 8	
Comm 2	Stop Bits		1	1 to 2	* None
	Parity		None	*	
	Protocol				
	Baud rate		19200		
	Data Bits		8	7 to 8	
Comm 3	Stop Bits		1	1 to 2	
	Parity		None	*	
	Protocol				]
Map File	Use Map File		No	*	

<sup>\*</sup> Refer to 090.020-CS (Communications Setup) for additional information

#### **CONFIGURATION - Ethernet**

Control	Description		Val	ue		Default	Range	
	Address Type				1	Fixed	Static or Dynamic	
	IP Address					*	*	
IP Data	Gateway Address					*	*	
	Subnet Mask					*	*	
	Web Server Port					80	0.0 to 99999.0	
	Host Name					QLX-Host	*	
Naming Data	Workgroup					QLX Compressors	*	
Data	Comment					*	*	
	Email Notification On Shutdown					Disabled	Disabled / Enabled	
	Local Email Address							
	Alias Name for Local Email Address					*	*	
Email	Subject							
Data	SMTP Server Name OR IP Address							
	SMTP Server Port Number					25	0.0 to 99999.0	
	Comma-Delimited List Of Email Recipients					*	*	
	ModBus TCP							
Protocols	Ethernet/IP			Disabled	Disabled / Enabled			
	PROFINET							

<sup>\*</sup> Refer to 090.020-CS (Communications Setup) for additional information



## CONFIGURATION - Digital I/O (Page 3)

Input/Output	Description	Value	Default	Range
Liquid Lovel Increase	IO Board		None	*
Liquid Level Increase	IO Channel		0	None
Liquid Lovel Decrees	IO Board		None	*
Liquid Level Decrease	IO Channel		0	None
PLC Interlock	IO Board		None	*
PLC IIILEHOCK	IO Channel		0	None
High VI Liquid	IO Board		Digital Board 1	*
Injection	IO Channel		10	None
Charact Tain	IO Board		Digital Board 1	*
Shunt Trip	IO Channel		15	None

#### \* IO Board

None	Digital Board 1	Digital Board 2

#### **SECURITY**

Description		Value	Default	Range
Level 1 Password			****	
Level 2 Password			****	0.0 to 5000.0
Level 3 Password			****	
Password For Current	Level Or Higher User Level		PSIG	-999999.0 to 999999.0
Remote Internet	User Name			N/A
Acces	Password		****	N/A

Refer to 090.020-O (Operation) for additional information

#### **SESSION**

Description	Value	Default	Range	Units
User Level		0		
Password		None		
Language		English	*	*
Pressure Units		PSIG		
Temperature Units		Fahrenheit		
Date Format		US		

<sup>\*</sup> Refer to 090.020-O (Operation) for additional information

#### **ABOUT**

Description	Value	Default	Range	Units
Sales Order		0	0.0 to 9999999	None
Item		0	0.0 to 99999	None

# $\begin{array}{c} \mathsf{QUANTUM}^{\mathsf{m}} \; \mathsf{LX} \; \mathsf{COMPRESSOR} \; \mathsf{CONTROL} \; \mathsf{PANEL} \\ \mathsf{MAINTENANCE} \end{array}$



## CONFIGURATION - Digital I/O (Page 1)

Input/Output	Description	Value	Default	Range
Oil Level Switch	IO Board		Digital Board 1	*
Oil Level Switch	IO Channel		13	None
Capacity Decrease	IO Board		Digital Board 1	*
cupacity Decrease	IO Channel		6	None
Capacity Increase	IO Board		Digital Board 1	*
capacity increase	IO Channel		5	None
Volume Decrease	IO Board		Digital Board 1	*
Volume Decrease	IO Channel		8	None
Volume Increase	IO Board		Digital Board 1	*
	IO Channel		7	None
Capacity Step #1	IO Board		None	*
. , .	IO Channel		0	None *
Capacity Step #2	IO Board		None	
	IO Channel		O Name	None *
Capacity Step #3	IO Board IO Channel		None O	None
	IO Board			wone *
Capacity Step #4	IO Channel		None O	None
	IO Board		None	*
Capacity Step #5	IO Channel		0	None
	IO Board		None	*
Capacity Step #6	IO Channel		0	None
	IO Board		None	*
Capacity Step #7	IO Channel		0	None
	IO Board		Digital Board 1	*
Economizer	IO Channel		11	None
Linuid Intention	IO Board		Digital Board 1	*
Liquid Injection	IO Channel		9	None
Oil Heater	IO Board		Digital Board 1	*
Oli neatei	IO Channel		21	None
Hot Gas Bypass	IO Board		Digital Board 1	*
Hot das bypass	IO Channel		16	None
Compressor Motor	IO Board		Digital Board 1	*
Start Signal	IO Channel		1	None
Compressor Motor	IO Board		Digital Board 1	*
Starter Feedback	IO Channel		2	None
Oil Pump Start Signal	IO Board		Digital Board 1	*
	IO Channel		3	None
Oil Pump Feedback	IO Board		Digital Board 1	*
·	IO Channel		<u>4</u>	None
Full Flow Pump Start	IO Board		None	* Nana
Signal	IO Channel		0	None *
Oil Pump #2 Start	IO Board		Digital Board 2	
Signal	IO Channel		15	None *
Oil Pump #2 Feedback	IO Board		Digital Board 2	
·	IO Channel		16	None

#### \* IO Board

None	Digital Board 1	Digital Board 2



## CONFIGURATION - Digital I/O (Page 2)

Input/Output	Description	Value	Default	Range
	IO Board		Digital Board 1	*
High Liquid Level Shutdown	IO Channel		14	None
	IO Board		Digital Board 1	*
Mode Select A	IO Channel		19	None
	IO Board		Digital Board 1	*
Mode Select B	IO Channel		20	None
Chartela	IO Board		Digital Board 1	*
Shutdown	IO Channel		23	None
Mouning	IO Board		Digital Board 1	*
Warning	IO Channel		22	None
Palaras Piatas	IO Board		Digital Board 1	*
Balance Piston	IO Channel		12	None
Daniel Heaten	IO Board		Digital Board 1	*
Panel Heater	IO Channel		15	None
D 1 1 C1 1	IO Board		Digital Board 2	*
Permissive Start	IO Channel		17	None
Deed To Dee	IO Board		Digital Board 2	*
Ready To Run	IO Channel		1	None
Denote Frobled	IO Board		Digital Board 2	*
Remote Enabled	IO Channel		2	None
De suele Deleu	IO Board		Digital Board 2	*
Recycle Delay	IO Channel		6	None
Dometa Start/Stan	IO Board		Digital Board 2	*
Remote Start/Stop	IO Channel		3	None
Remote Load	IO Board		Digital Board 2	*
Remote Load	IO Channel		4	None
Remote Unload	IO Board		Digital Board 2	*
Remote Omoad	IO Channel		5	None
Condenser Control Step 1	IO Board		Digital Board 2	*
Condenser Control Step 1	IO Channel		21	None
Condenser Control Step 2	IO Board		Digital Board 2	*
Condenser Control Step 2	IO Channel		22	None
Condenser Control Step 3	IO Board		Digital Board 2	*
Condenser Control Step 3	IO Channel		23	None
Condenser Control Step 4	IO Board		Digital Board 2	*
condenser control step 4	IO Channel		24	None
Power Assist	IO Board		Digital Board 1	*
. 51161 /155156	IO Channel		24	None
Dx Circuit #1	IO Board		Digital Board 2	*
	IO Channel		19	None
Dx Circuit #2	IO Board		Digital Board 2	*
DA GIIGUIC IIZ	IO Channel		20	None
Main Oil Injection	IO Board		None	*
on injection	IO Channel		0	None

\* IO Board

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## QUANTUM™ LX COMPRESSOR CONTROL PANEL MAINTENANCE



#### **NOTES:**



## **SECTION 10**

## **QUANTUM™ LX DRAWINGS**

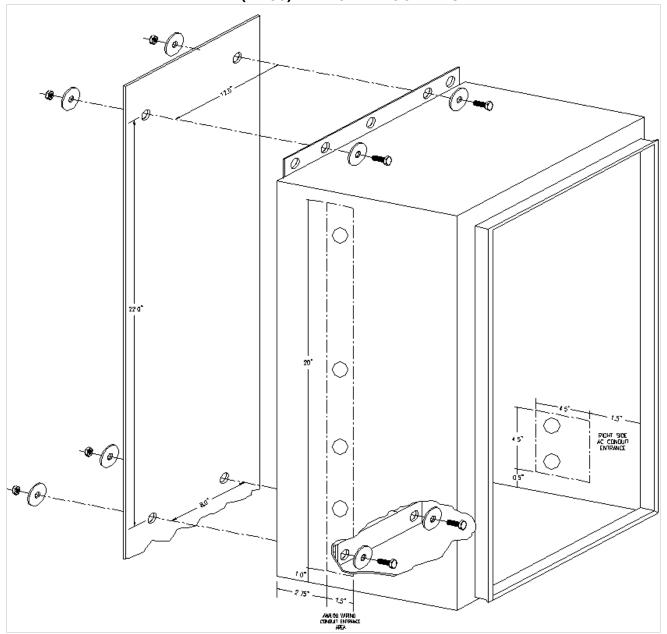
This table lists the numbers for the drawings that appear on the following pages. The drawings shown here is the latest revision as of the printing of this manual. These drawings appear here for reference purposes only, and are subject to change without notice. When installing, or servicing equipment, always refer to the actual drawings that are included with the control panel for the latest information.

Wiring Diagrams	Page	Drawing Number
RXF (12-50) RETROFIT MOUNTING	140	N/A
RWF & RWFII	141 - 144	649D5154 Rev. H
RWBII	145- 148	649D5155 Rev. F
RXF 12-101	149 - 152	649D5153 Rev. F
RDB	153 - 156	649D5278 Rev. F
PhD for 32 channel Analog Board	157	649D5050 Rev. D
Digital I/O Board 2	158- 159	649D5210 Rev. C
Analog I/O Board 2	160 - 161	649D5211 Rev. E

Other Drawings	Page	
Isolater Repeater Module (Isolates Communications Signals)	162	639C0133 Rev. A
Communications Wiring Diagrams	163	N/A
Point-to-Point Field Wiring Diagram	164	N/A

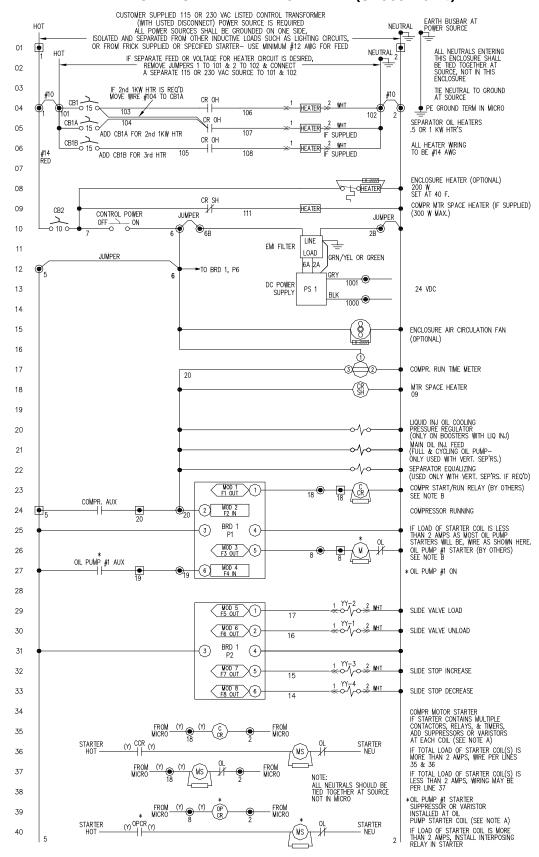


#### **RXF (12-50) RETROFIT MOUNTING**



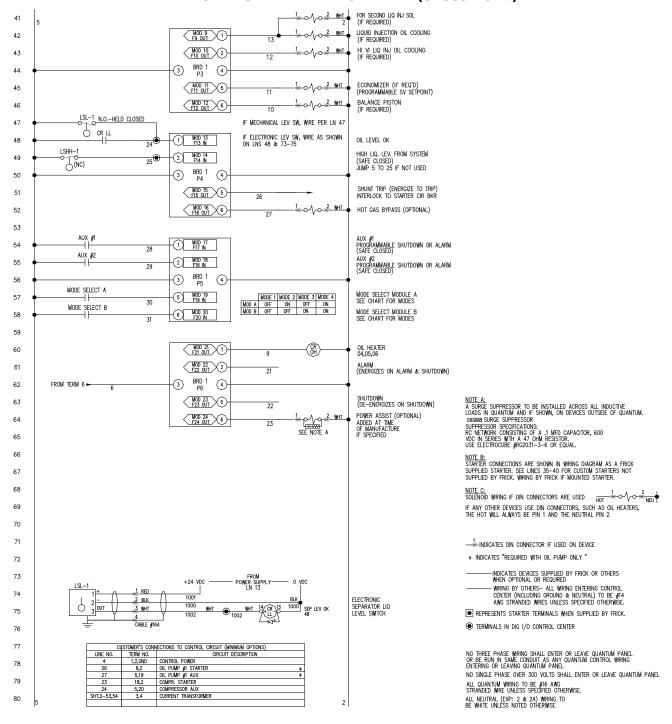


### WIRING DIAGRAM - RWF & RWF II (Sheet 1 of 4)



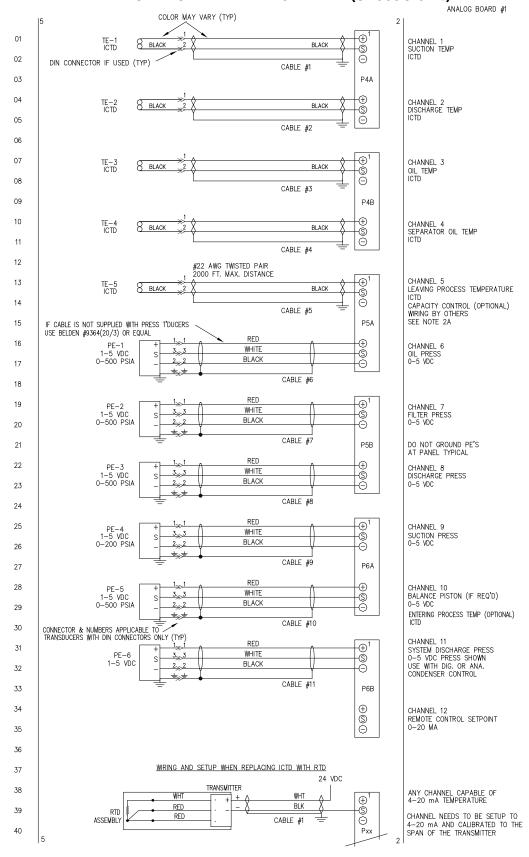


## WIRING DIAGRAM - RWF & RWF II (Sheet 2 of 4)



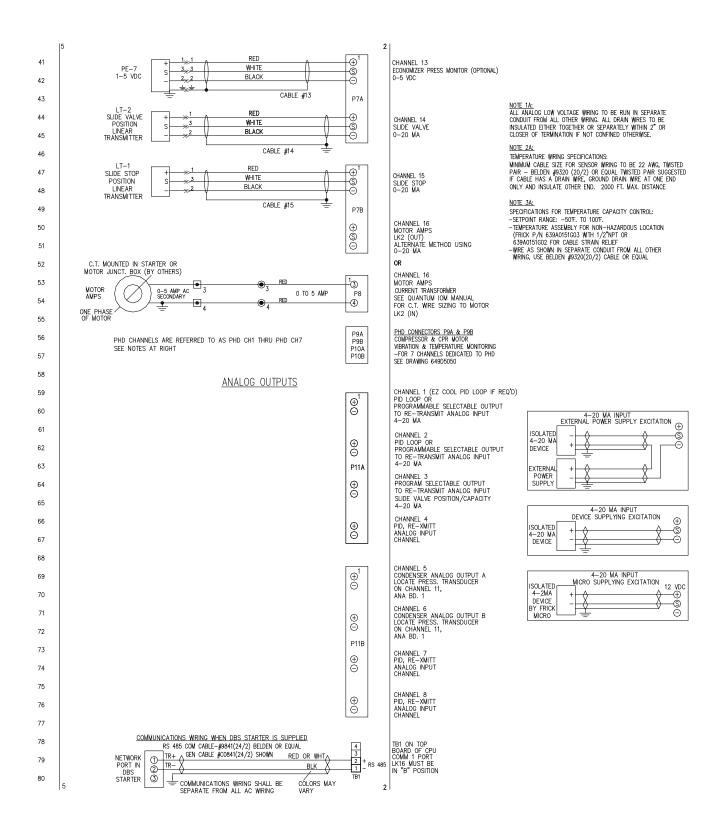


### WIRING DIAGRAM - RWF & RWF II (Sheet 3 of 4)



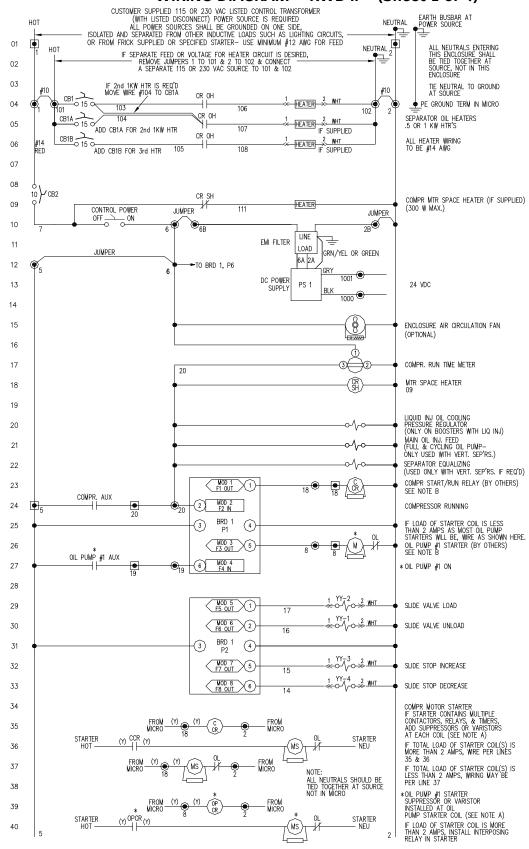


### WIRING DIAGRAM - RWF & RWF II (Sheet 4 of 4)



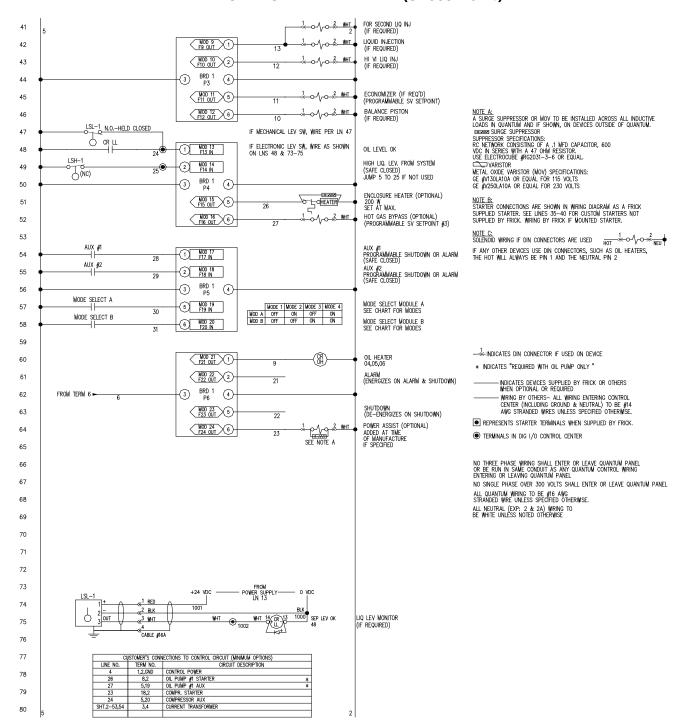


### WIRING DIAGRAM - RWB II - (Sheet 1 of 4)



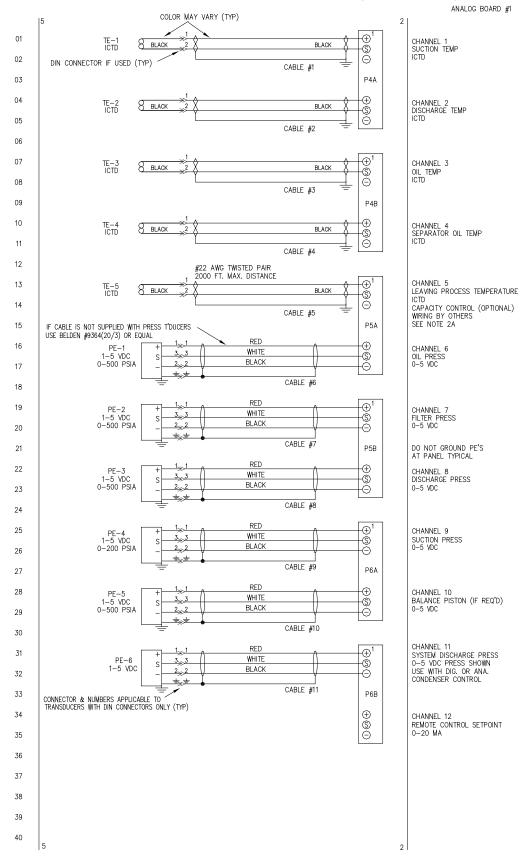


## WIRING DIAGRAM - RWB II - (Sheet 2 of 4)



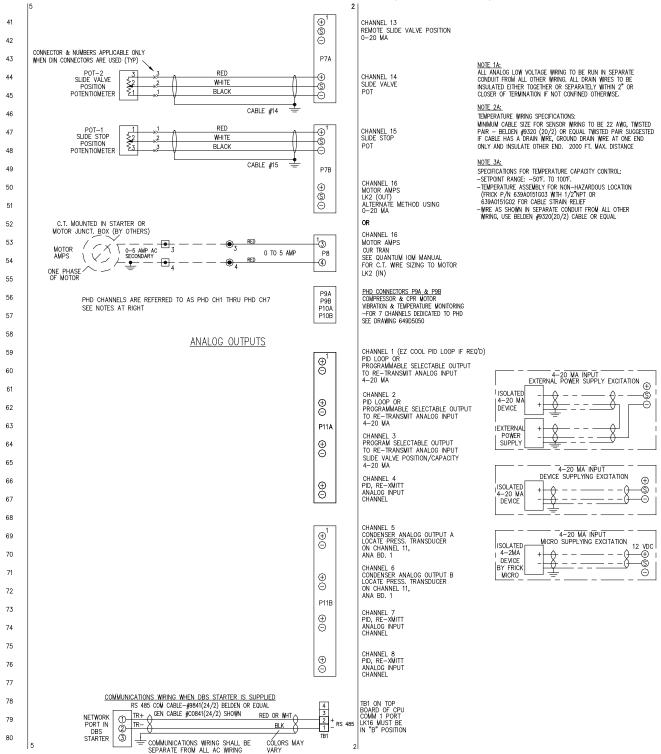


### WIRING DIAGRAM - RWB II - (Sheet 3 of 4)



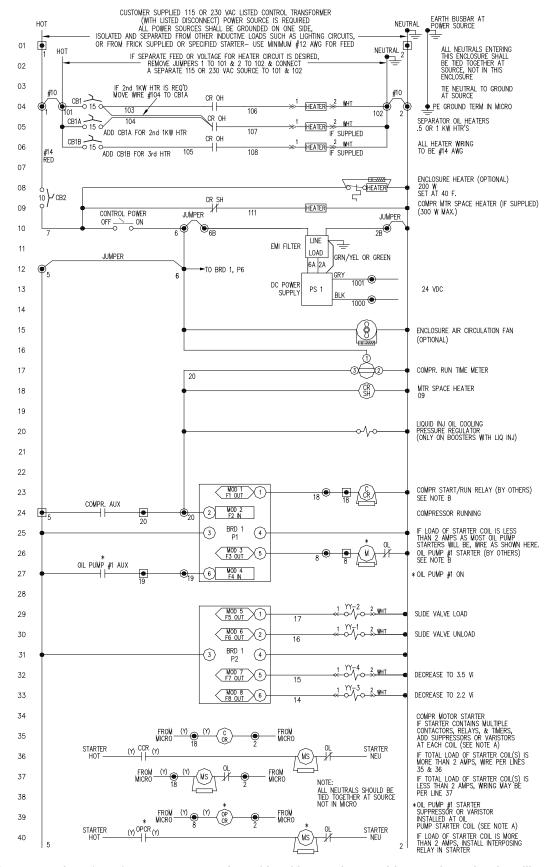


### WIRING DIAGRAM - RWB II - (Sheet 4 of 4)



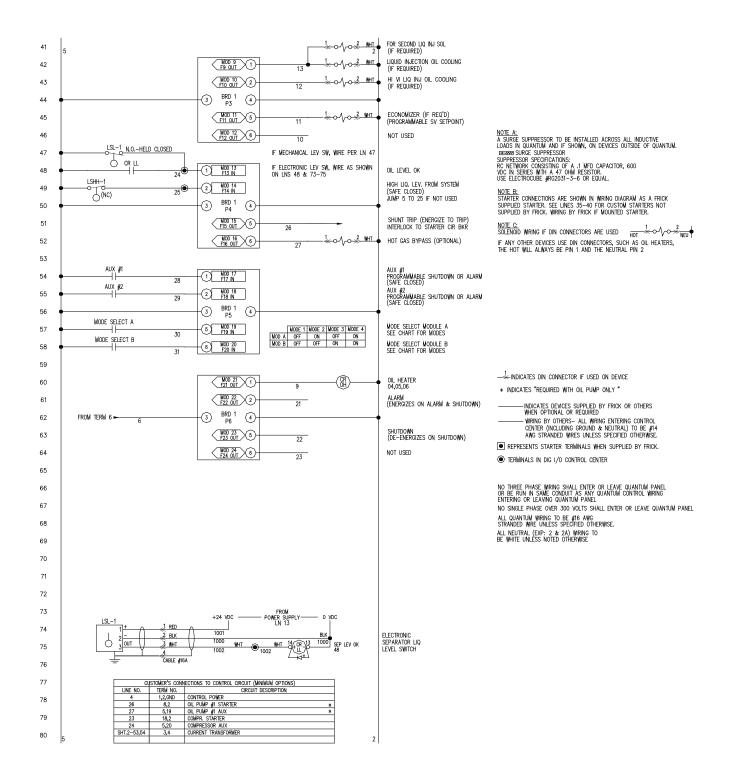


## WIRING DIAGRAM - RXF (12-101) (Sheet 1 of 4)





### WIRING DIAGRAM - RXF (12-101) (Sheet 2 of 4)



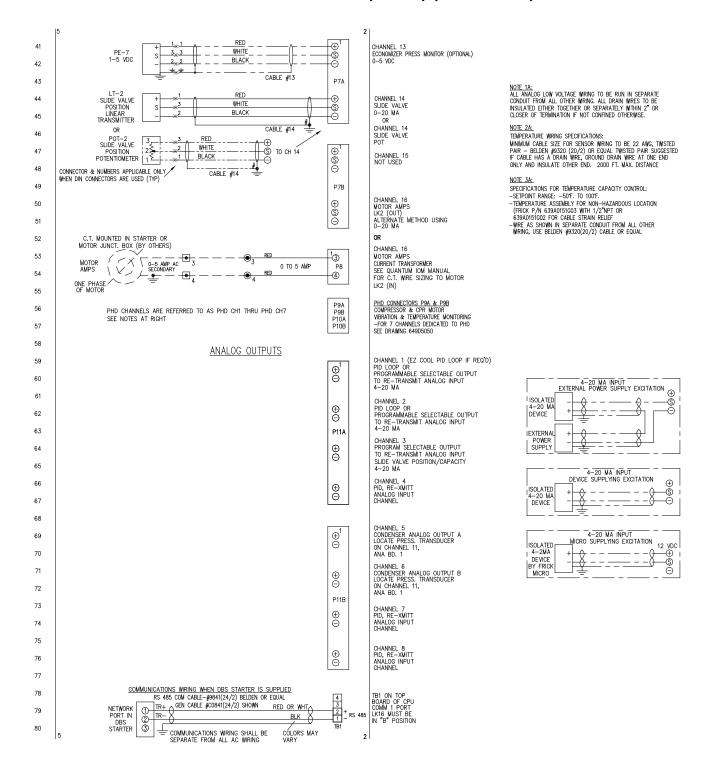


#### WIRING DIAGRAM - RXF (12-101) (Sheet 3 of 4) ANALOG BOARD #1 COLOR MAY VARY (TYP) 01 CHANNEL 1 SUCTION TEMP ICTD 8 BLACK 02 Θ DIN CONNECTOR IF USED (TYP) CABLE #1 P4A 0.3 CHANNEL 2 DISCHARGE TEMP ICTD 04 TE-2 ICTD Š 05 Θ CABLE #2 06 07 CHANNEL 3 TE-3 8 BLACK OIL TEMP 80 CABLE #3 09 P4B CHANNEL 4 SEPARATOR OIL TEMP ICTD 10 ⑤ ⊝ 11 CABLE #4 12 #22 AWG TWISTED PAIR 2000 FT. MAX. DISTANCE CHANNEL 5 LEAVING PROCESS TEMPERATURE ICTD ⊕¹ 13 TE-5 ICTD Š Θ CAPACITY CONTROL (OPTIONAL) WIRING BY OTHERS CABLE #5 15 P5A SEE NOTE 2A IF CABLE IS NOT SUPPLIED WITH PRESS T'DUCERS USE BELDEN #9364(20/3) OR EQUAL RED 16 PE-1 CHANNEL 6 OIL PRESS 0-5 VDC WHITE 1-5 VDC 0-500 PSIA BLACK 17 CABLE #6 18 RED **(** 19 PE-2 1-5 VDC CHANNEL 7 FILTER PRESS (OPTIONAL) 0-5 VDC WHITE (\$) BLACK 20 (-)CABLE #7 DO NOT GROUND PE'S AT PANEL TYPICAL P5B 21 RED 22 PE-3 1-5 VDC 0-500 PSIA CHANNEL 8 DISCHARGE PRESS WHITE Ğ ⊝ BLACK 0-5 VDC 23 CABLE #8 24 RED 25 **(** PE-4 1-5 VDC 0-200 PSIA WHITE (S) (E) SUCTION PRESS 0-5 VDC BI ACK 26 CABLE #9 P6A 27 ① ③ ① CHANNEL 10 NOT USED 0-5 VDC 28 29 30 CHANNEL 11 RED 31 **(** SYSTEM DISCHARGE PRESS 0-5 VDC PRESS SHOWN USE WITH DIG. OR ANA. WHITE 1-5 VDC BLACK 32 CONDENSER CONTROL CABLE #11 33 P6B CONNECTOR & NUMBERS APPLICABLE TO TRANSDUCERS WITH DIN CONNECTORS ONLY (TYP) 34 CHANNEL 12 REMOTE CONTROL SETPOINT 0-20 MA Š ⊝ 35 36 37 38 39

This drawing appears here for reference purposes only, and is subject to change without notice. When installing, or servicing equipment, always refer to the actual drawings that are included with the control panel for the latest information.

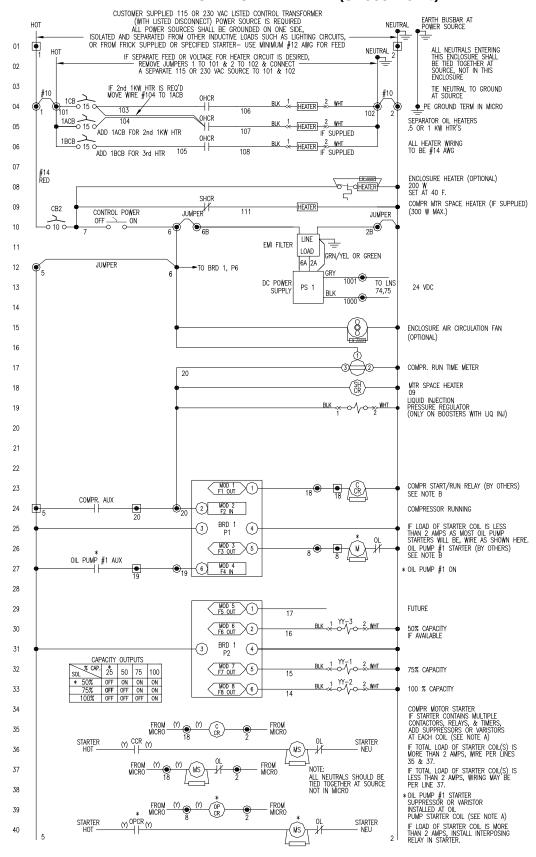


### WIRING DIAGRAM - RXF (12-101) (Sheet 4 of 4)



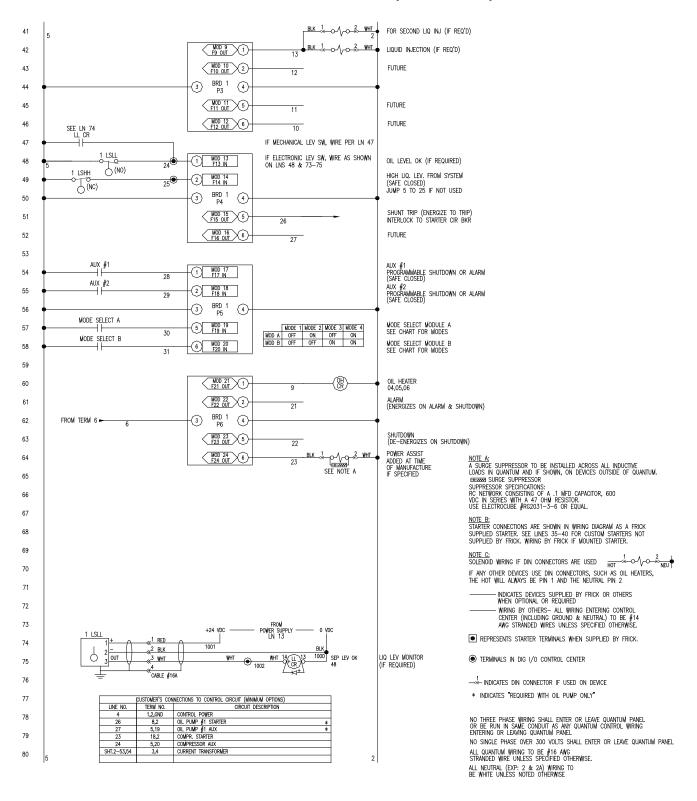


### WIRING DIAGRAM - RDB (Sheet 1 of 4)



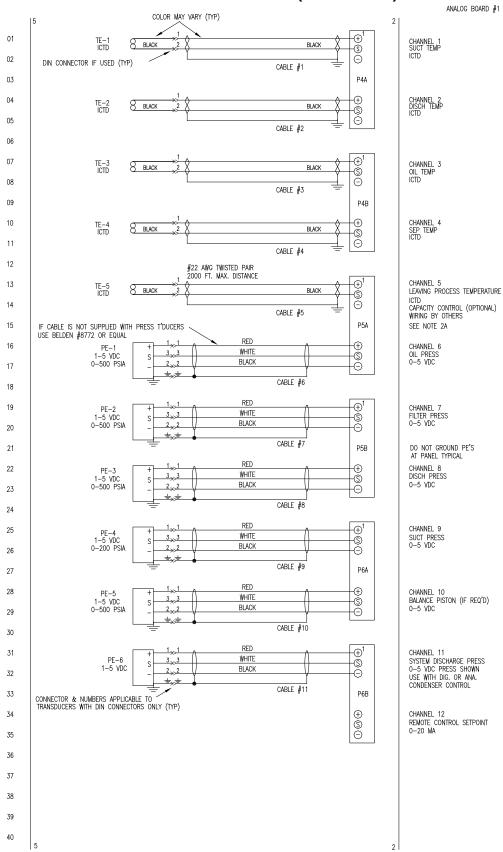


### WIRING DIAGRAM - RDB (Sheet 2 of 4)



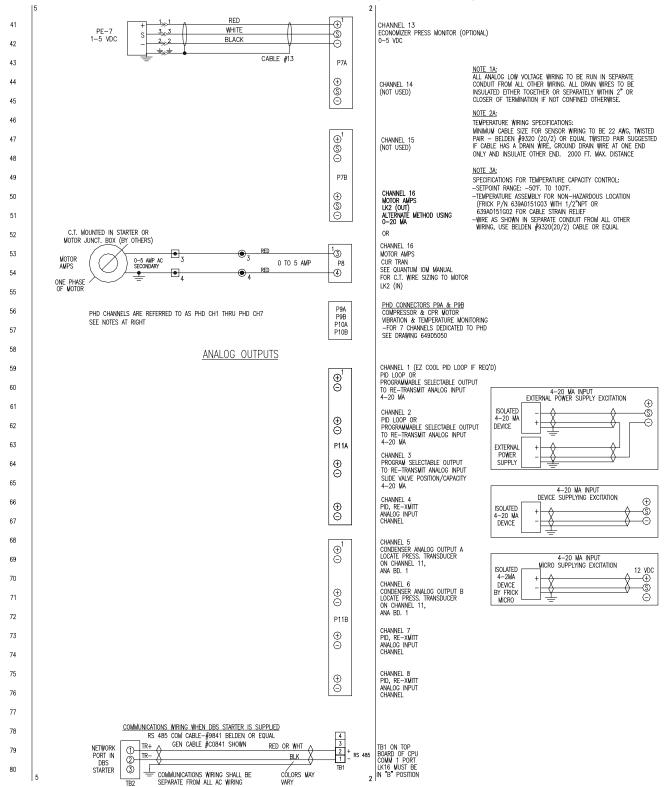


### WIRING DIAGRAM - RDB (Sheet 3 of 4)



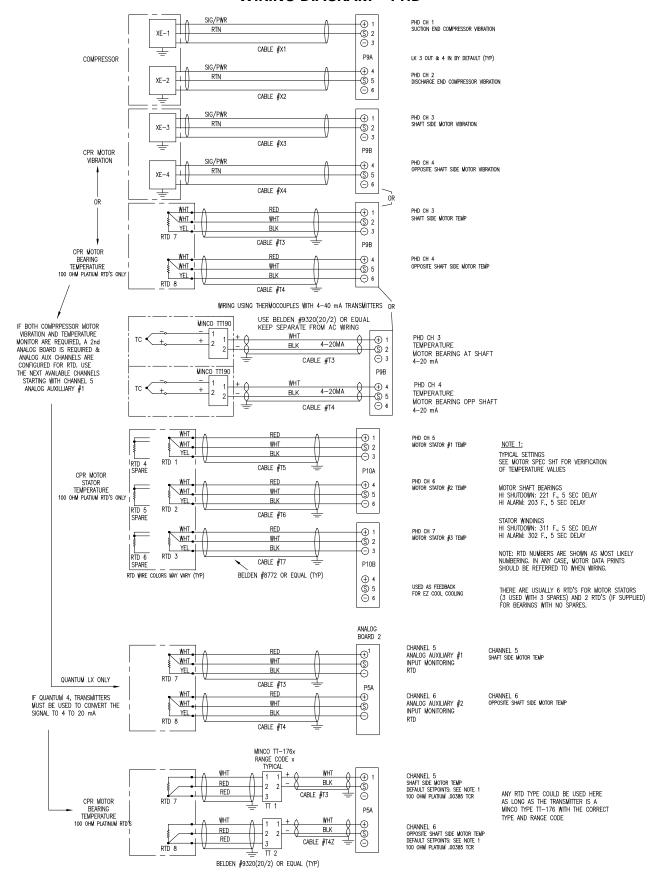


### WIRING DIAGRAM - RDB (Sheet 4 of 4)





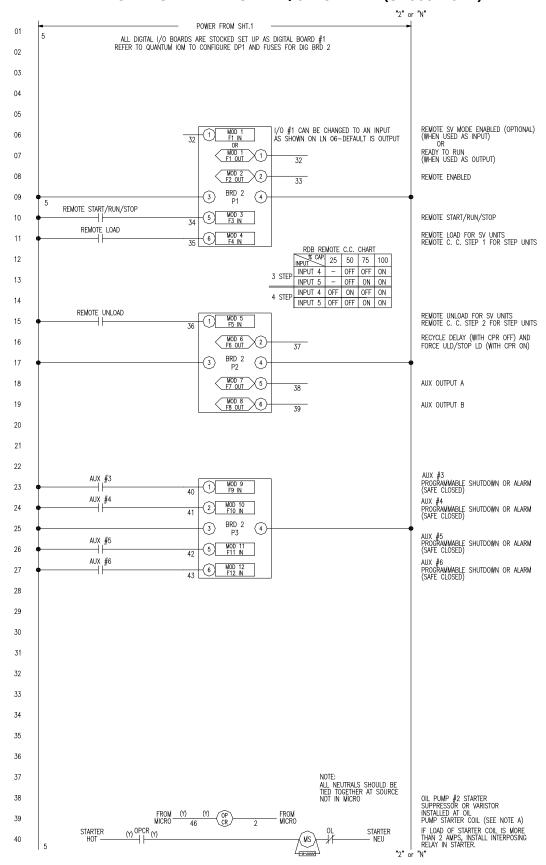
#### **WIRING DIAGRAM - PHD**



This drawing appears here for reference purposes only, and is subject to change without notice. When installing, or servicing equipment, always refer to the actual drawings that are included with the control panel for the latest information.

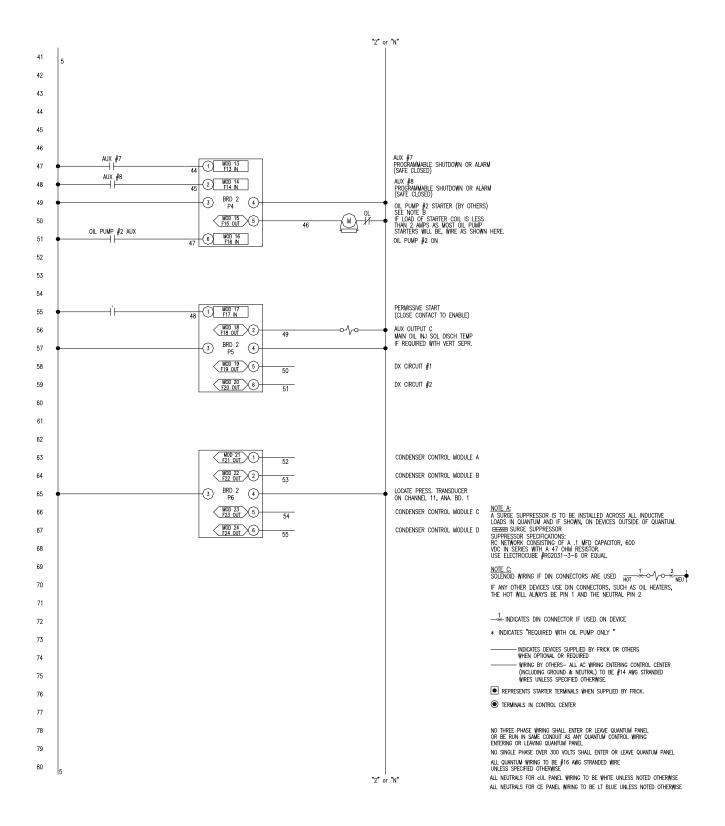


### WIRING DIAGRAM - DIGITAL I/O BOARD 2 (Sheet 1 of 2)



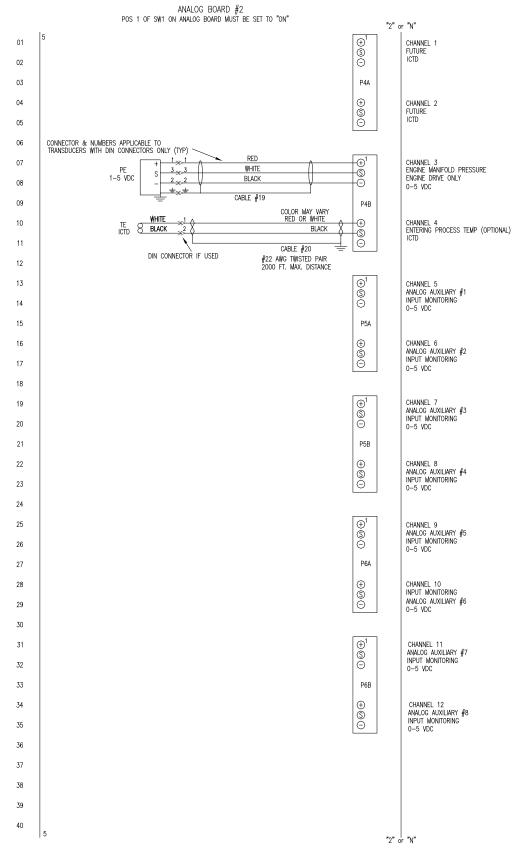


### WIRING DIAGRAM - DIGITAL I/O BOARD 2 (Sheet 2 of 2)



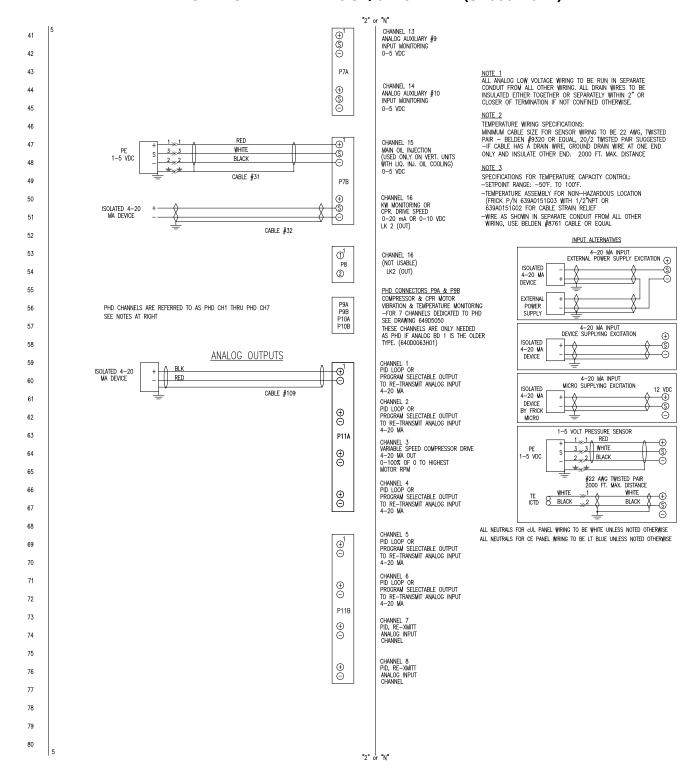


## WIRING DIAGRAM - ANALOG I/O BOARD 2 (Sheet 1 of 2)



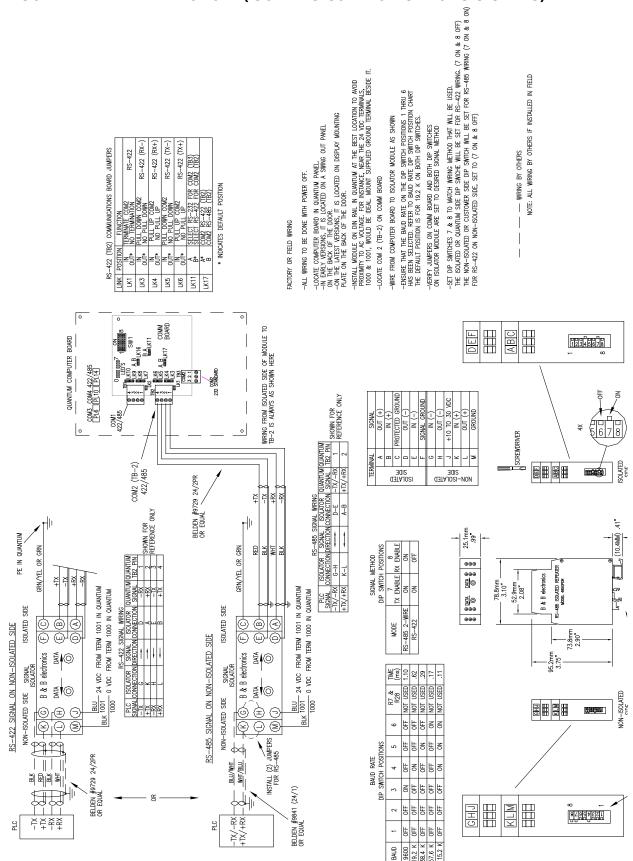


### WIRING DIAGRAM - ANALOG I/O BOARD 2 (Sheet 2 of 2)





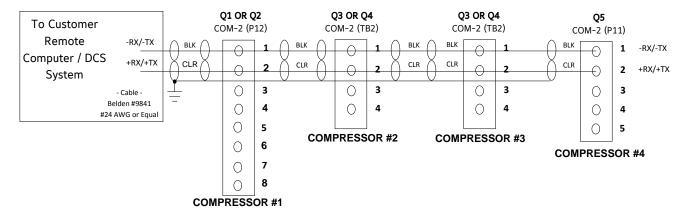
## ISOLATER REPEATER MODULE (ISOLATES COMMUNICATIONS SIGNALS)



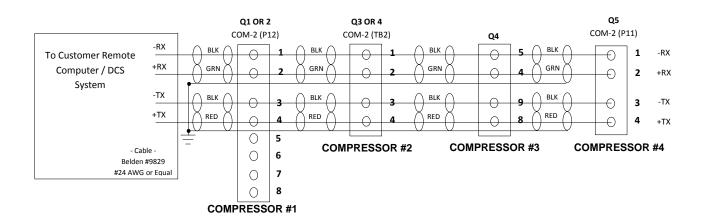


#### **COMMUNICATIONS WIRING DIAGRAMS**

## TO CUSTOMER REMOTE COMPUTER/DCS RS-485 COMMUNICATIONS

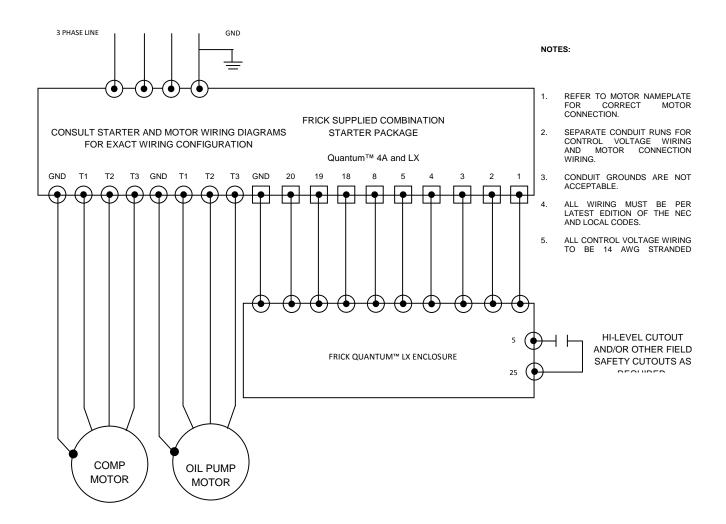


## TO CUSTOMER REMOTE COMPUTER/DCS RS-422 COMMUNICATIONS





#### POINT-TO-POINT FIELD WIRING DIAGRAM





## **SECTION 11**

## **TABLES**

### PRESSURE TRANSDUCER CONVERSION DATA

(Data Instruments Model SA)

Sensor Voltage		) psi - psig*		O psi - psig*		0 psi e - psig*		00 psi e - psig*
	Low	High	Low	High	Low	High	Low	High
1.0	29.92"	19.74"	29.92"	9.57"	29.92"	7.0"	29.92"	4.1
1.1	29.92"	14.65"	29.92"	0.3	29.92"	4.1	29.92"	16.6
1.2	29.92"	9.57"	29.92"	5.3	22.3"	11.6	17.1"	29.1
1.3	24.83"	4.48"	19.74"	10.3	7.0"	19.1	4.1	41.6
1.4	19.74"	0.3	9.57"	15.3	4.1	26.6	16.6	54.1
1.5	14.65"	2.8	0.3	20.3	11.6	34.1	29.1	66.6
1.6	9.57"	5.3	5.3	25.3	19.1	41.6	41.6	79.1
1.7	4.48"	7.8	10.3	30.3	26.6	49.1	54.1	91.6
1.8	0.3	10.3	15.3	35.3	34.1	56.6	66.6	104.1
1.9	2.8	12.8	20.3	40.3	41.6	64.1	79.1	116.6
2.0	5.3	15.3	25.3	45.3	49.1	71.6	91.6	129.1
2.1	7.8	17.8	30.3	50.3	56.6	79.1	104.1	141.6
2.2	10.3	20.3	35.3	55.3	64.1	86.6	116.6	154.1
2.3	12.8	22.8	40.3	60.3	71.6	94.1	129.1	166.6
2.4	15.3	25.3	45.3	65.3	79.1	101.6	141.6	179.1
2.5	17.8	27.8	50.3	70.3	86.6	109.1	154.1	191.6
2.6	20.3	30.3	55.3	75.3	94.1	116.6	166.6	204.1
2.7	22.8	32.8	60.3	80.3	101.6	124.1	179.1	216.6
2.8	25.3	35.3	65.3	85.3	109.1	131.6	191.6	229.1
2.9	27.8	37.8	70.3	90.3	116.6	139.1	204.1	241.6
3.0	30.3	40.3	75.3	95.3	124.1	146.6	216.6	254.1
3.1	32.8	42.8	80.3	100.3	131.6	154.1	229.1	266.6
3.2	35.3	45.3	85.3	105.3	139.1	161.6	241.6	279.1
3.3	37.8	47.8	90.3	110.3	146.6	169.1	254.1	291.6
3.4	40.3	50.3	95.3	115.3	154.1	176.6	266.6	304.1
3.5	42.8	52.8	100.3	120.3	161.6	184.1	279.1	316.6
3.6	45.3	55.3	105.3	125.3	169.1	191.6	291.6	329.1
3.7	47.8	57.8	110.3	130.3	176.6	199.1	304.1	341.6
3.8	50.3	60.3	115.3	135.3	184.1	206.6	316.6	354.1
3.9	52.8	62.8	120.3	140.3	191.6	214.1	329.1	366.6
4.0	55.3	65.3	125.3	145.3	199.1	221.6	341.6	379.1
4.1	57.8	67.8	130.3	150.3	206.6	229.1	354.1	391.6
4.2	60.3	70.3	135.3	155.3	214.1	236.6	366.6	404.1
4.3	62.8	72.8	140.3	160.3	221.6	244.1	379.1	416.6
4.4	65.3	75.3	145.3	165.3	229.1	251.6	391.6	429.1
4.5	67.8	77.8	150.3	170.3	236.6	259.1	404.1	441.6
4.6	70.3	80.3	155.3	175.3	244.1	266.6	416.6	454.1
4.7	72.8	82.8	160.3	180.3	251.6	274.1	429.1	466.6
4.8	75.3	85.3	165.3	185.3	259.1	281.6	441.6	479.1
4.9	77.8	87.8	170.3	190.3	266.6	289.1	454.1	491.6
5.0	80.3	90.3	175.3	195.3	274.1	296.6	466.6	504.1
t zero psig	1.388 V	1.788 V	1.094 V	1.494 V	1.046 V	1.346 V	0.968 V	1.268 V

<sup>\*</sup> Below 0 psig measured in inches of mercury.



### **COMPRESSOR VOLUME RATIO AND CAPACITY INFORMATION**

			Standard		Low Vi		Theo-	Micro	Micro
			Slide Valve		Slide Valve		retical	Slide	Slide
Bare Model	Package Model	Bare Model Serial Number	Min.	Max.	Min.	Max.	Minimum	Valve	Stop
			Vi	Vi	Vi	Vi	Capacity	Travel	Travel
XJS/XJF 95 RXB/RXF 12, 15, 19		all	2.2, 3.5, 5.0		n/a	n/a	25%		
XJS/XJF 120	RXB/RXF 24,30, 39, 50	all	2.2, 3	3.5, 5.0	n/a	n/a	25%		
XJF/XJB 151 & 151X	RXF 58, 68, 85, 101	all		3.5, 5.0	n/a	n/a	21%		
TDSH 163S	RWB-II 60	all	2.2	5.0	n/a	n/a	12%	195.6	76.2
TDSH 163L	RWB-II 38, 76	all	2.2	5.0	n/a	n/a	12%	195.6	76.2
TDSH 193S	RWB-II 100	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 193L	RWB-II 134	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 233S	RWB-II 177	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 233L	RWB-II 222	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 233XL	RWB-II 270	all	2.2	5.0	1.7	n/a	23%	158.6	76.2
TDSH 283S	RWB-II 316	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 283L	RWB-II 399	all	2.2	5.0	1.7	n/a	12%	195.6	76.2
TDSH 283LY	YS chiller (S7 compressor)	all	n/a	n/a	1.7	2.5	8%	194.1	56.5
TDSH 283SX	RWB-II 480	all	2.2	4.2	1.7	2.7	23%	165.5	64.8
TDSH/TDSB 355S	RWB-II 496	0153L / 0011SBS and lower	2.2	5.0	1.7	3.0	18%	185.6	76.2
TDSH/TDSB 355S	RWB-II 496	0154L / 0012SBS and higher	2.2	5.0	1.7	3.0	12%	213.9	76.2
TDSH/TDSB 355L	RWB-II 676	0222K / 0025SBL and lower	2.2	5.0	1.7	3.0	18%	185.6	76.2
TDSH/TDSB 355L	RWB-II 676	0223K / 0026SBL and higher	2.2	5.0	1.7	3.0	12%	213.9	76.2
TDSH/TDSB 355XL	RWB-II 856	0109XL / 0052SBXL and lower	2.2	5.0	1.7	3.0	30%	146.5	76.2
TDSH/TDSB 355XL	RWB-II 856	0110XL / 0053SBXL and higher	2.2	5.0	1.7	3.0	18%	184.6	76.2
TDSB 355U	RWB-II 1080	all	2.4	4.5	1.7	2.6	26%	141.5	58.0
TDSH 408S	RWH-II 852	all	2.2	5.0	1.7	3.0	12%	193.0	76.2
TDSH 408L	RWH-II 1179	all	2.2	5.0	1.7	3.0	12%	193.0	76.2
TDSH 408XL	RWH-II 1395	all	2.2	4.3	1.7	2.7	15%	183.9	66.4
API 408S	K AA LL-11 1232	all	2.2	5.0	1.7	3.0	12%	193.0	76.2
API 4083 API 408L		all	2.2	5.0	1.7	3.0	12%	193.0	76.2
			2.2	4.3	1.7	2.7	21%		66.4
API 408XL	RWF 100	all		5.0		3.0	12%	163.4	76.2
SGC 1913		all	2.2		1.7			195.6	
SGC 1918	RWF 134	all	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2313	RWF 177	all	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2317	RWF 222	all	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2321	RWF 270	all	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2813	RWF 316	all "	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2817	RWF 399	all	2.2	5.0	1.7	3.0	12%	195.6	76.2
SGC 2821	RWF 480	all	2.2	5.0	1.7	3.0	12%	213.9	76.2
SGC 2824	RWF 546	all	2.0	4.1	n/a	n/a	18%	185.6	76.2
SGC 3511	RWF-II 496	all	2.2	5.0	1.7	3.0	12%	213.9	76.2
SGC 3515	RWF-II 676	all	2.2	5.0	1.7	3.0	12%	213.9	76.2
SGC 3519	RWF-II 856	all	2.2	5.0	1.7	3.0	18%	184.6	76.2
SGC 3524	RWF-II 1080	all 	2.4	4.5	1.7	2.6	26%	141.5	58.0
NGC 100		all	2.2	5.0	1.7	3.0	12%	195.6	76.2
NGC 150		all	2.2	5.0	1.7	3.0	12%	195.6	76.2
NGC 200		all	2.2	5.0	1.7	3.0	12%	195.6	76.2
NGC 250		all	2.2	5.0	1.7	3.0	12%	195.6	76.2
NGC 300		all	2.0	4.1	n/a	n/a	15%	197.3	76.2
NGC 400		all	2.2	5.0	n/a	n/a	12%	213.9	76.2
NGC 450		NGC 450E0001Z only	2.0	3.3	n/a	n/a	26%	141.5	58.0
NGC 450		All NGC 450 except E0001Z	2.2	3.9	n/a	n/a	26%	141.5	58.0

NOTE: For 95, 120, and 151mm compressors, the slide stop travel value in parentheses is the travel from Vi=2.2 to Vi=3.5.



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**NOTES:** 

#### November 2016 Form Revisions

p.28 - Updated Analog Board Q5 Replacement part line item descriptions p.48 - Updated Analog Board Q4 Replacement part line item descriptions



